## Positioning Modules

One of Q Series' strengths is the ability to integrate positioning directly onto your system. If a Q Series motion CPU is not required, the following modules provide a range of alternative positioning control capabilities in a range of formats.

| Model Number |  | QD75P1N (*1) • QD75D1N | QD75P2N (*1) • QD75D2N | QD75P4N (*1) • QD75D4N |
| :---: | :---: | :---: | :---: | :---: |
| Stocked Item |  | - | S | S |
| Certification |  | UL • CE |  |  |
| Number of Control Axes |  | 1 axis | 2 axes | 4 axes |
| Interpolation Function |  | No | 2-axis linear interpolation; 2-axis circular interpolation | 2-, 3-, or 4-axis linear interpolation 2-axis circular interpolation |
| Control Unit |  | mm, inch, degree, pulse |  |  |
| Backup |  | Parameters, positioning data, and block start data can be saved on flash ROM (battery-less backup). |  |  |
| Positioning System |  | PTP control: Incremental system/absolute system <br> Speed-position switching control: Incremental system/absolute system (*2) <br> Position-speed switching control: Incremental system <br> Path control: Incremental system/absolute system |  |  |
| Positioning | Position Range | In absolute system <br> - -214748364.8 to 214748364.7 ( m) <br> - 21474.83648 to 21474.83647 (inch) <br> - 0 to 359.99999 (degree) <br> - -2147483648 to 2147483647 (pulse) <br> In incremental system <br> - 214748364.8 to 214748364.7 ( m) <br> - 21474.83648 to 21474.83647 (inch) <br> - 21474.83648 to 21474.83647 (degree) <br> - 2147483648 to 2147483647 (pulse) <br> In speed-position switching control (INC mode) / position-speed switching control <br> - 0 to 214748364.7( m) <br> - 0 to 21474.83647(inch) <br> - 0 to 21474.83647 (degree) <br> - 0 to 2147483647 (pulse) <br> In speed-position switching control (ABS mode) <br> - 0 to 359.99999 (degree) |  |  |
|  | Speed Command | 0.01 to 40000000.00 (mm/min); 0.001 to 2000000.000 (inch/min); 0.001 to 2000000.000(degree/min); 1 to 4000000 (pulse/s) |  |  |
|  | Acceleration/Deceleration Process | Automatic trapezoidal acceleration/deceleration, S-pattern acceleration/deceleration |  |  |
|  | Acceleration/Deceleration Time | 1 to 8388608 (ms) Four patterns can be set for each of acceleration time and deceleration time |  |  |
|  | Sudden Stop Deceleration Time | 1 to 8388608 (ms) |  |  |
| Protective Degree |  | IP2X |  |  |
| External Wiring Connection System |  | 40-pin connector |  |  |
| Applicable Wire Size |  | 0.3mm² (AWG\#22) or less (for A6CON1, A6CON4), AWG \#24 (for A6CON2) |  |  |
| Applicable Connector for External Devices |  | A6CON1, A6CON2, A6CON4 (Sold separately) |  |  |
| Max. Output Pulse |  | QD75D1N, QD75D2N, QD75D4N: 4Mpps |  |  |
| Max. Connection Distance Between Servos |  | QD75P1, QD75P2, QD75P4: 2m; QD75D1, QD75D2,QD75D4: 10m |  |  |
| Online Module Change |  | Disabled |  |  |
| I/O Device Points Occupied |  | 32 points/slot (I/O assignment: intelligent) |  |  |
| 5VDC Internal Current Consumption |  | QD75P1N: 0.29A QD75D1N: 0.43 A | $\begin{array}{\|l} \hline \text { QD75P2N: 0.30A } \\ \text { QD75D2N: } 0.45 \mathrm{~A} \\ \hline \end{array}$ | QD75P4N: 0.36A QD75D4N: 0.66 A |
| Weight (kg) |  | 0.15 | 0.15 | 0.16 |
| Base Unit Slots Occupied |  | 1 |  |  |

Notes:

1. QD75P represents the open-collector output system, and QD75D represents the differential driver output system.
2. In speed-position switching control (ABS mode), the control unit available is "degree" only.

## Positioning Module with Built-in Counter Function

| Model Number | QD72P3C3 |
| :--- | :--- |
| Stocked Item | - |
| Certification | UL • cUL •CE |
| Number of Control Axes | 3 axes |
| Interpolation Function | No (Artificial linear interpolation by concurrent start is available) |
| Control Unit | Pulse |
| Backup | No |
| Positioning | Positioning System |
|  | Position Range |
|  | Speed Command |
|  | Acceleration/Deceleration Process |
|  | Acceleration/Deceleration Time |
| External Wiring Connection System | 1 To |
| Applicable Cont) control, speed control |  |
| Max. Output Pulse acceleration/deceleration | 1 to 5000 ms |
| I/0 Device Points Occupied | $40-$ pin connector |
| 5VDC Internal Current Consumption (A) | A6CON1, A6CON2, A6CON4 (Sold separately) |
| Weight (kg) | 100 kpps |
| Base Unit Slots Occupied | 32 points |

Note 1: When the "speed limit value" setting is 100000 (pulse/s) ( 25 -pulse units), set the "speed command" value in multiples of 25 . If other values are set, the value will be change to a multiple of 25.

Positioning Module with Deviation Counter and D/A Counter

| Model Number |  | QD73A1 |
| :---: | :---: | :---: |
| Stocked Item |  | - |
| Certification |  | UL • CUL • CE |
| Number of Occupied I/O Points |  | 48 points (I/O assignment: empty 16 points and intelligent 32 points) |
| Number of Control Axes |  | 1 axis |
| Positioning Data | Capacity | 1 data |
|  | Setting Method | Sequence program |
| Positioning | Mode | Position control mode; Speed-position control switch mode |
|  | System | Position control mode: Selectable from absolute system or incremental system; Speed-position control switch mode: Incremental system |
|  | Position Command | -2147483648 to 2147483647 (pulse) (signed 32-bit binary) |
|  | Speed Command | 1 to 4000000 (pulse/s) |
|  | Acceleration | Automatic trapezoidal acceleration/deceleration |
|  | Automatic Accel/Decel Time | Acceleration time: 2 to 9999 (ms); Deceleration time: 2 to 9999 (ms) |
|  | In-Position Range | 1 to 20479 (pulse) |
|  | Backlash Compensation | None |
|  | Error Correction Function | None |
| Speed Command Output |  | 0 to $\pm 10 \mathrm{VDC}$ (Adjustable to set in the range of $\pm 5$ to $\pm 10 \mathrm{VDC}$ ) |
| Positioning Feedback Pulse Input | Pulse Frequency | Open collector: 200kpulse/s; TTL: 200kpulse/s; Differential output: 1Mpulse/s |
|  | Connectable Encoder Type | Open collector, TTL, or differential output |
|  | Multiplication Setting | The number of input feedback pulses can be multiplied by 4, 2, 1, or $1 / 2$ |
| OPR Control |  | With OPR address change; An OPR method and OPR direction can be set through the intelligent function module switch setting |
| JOG Operation |  | JOG operation can be started by inputting a JOG start signal |
| M Function |  | None |
| Internal Current Consumption (5VDC) |  | 0.52A |
| External Supply Voltage/Current Terminal Block |  | No external power supply |
| External Dimensions (H x W x D) mm |  | $98 \times 55.2 \times 90$ |
| Weight (kg) |  | 0.20 |
| Starting Time <br> (From a Start Request to Analog Output Start) |  | Absolute system: 1.2ms (same for two-phase trapezoidal positioning); Incremental system: 1.2ms (same for two-phase trapezoidal positioning); JOG operation: 1.2 ms ; OPR (near-point dog method): 1.2 ms ; OPR (count method): 1.2 ms |

## Basic Positioning Control Modules

For applications not requiring the level of sophistication offered by our QD75P/D/M modules, consider the QD70P4 and P8 modules. These modules offer four and eight axis control from a single module. All basic motion control capabilities for non-coordinated axes are offered.

| Model Number |  | QD70P4 | QD70P8 |
| :---: | :---: | :---: | :---: |
| Stocked Item |  | S | S |
| Certification |  | $\mathrm{UL} \bullet \mathrm{cUL} \bullet$ CE | UL • cUL |
| Number of Control Axes |  | 4 axes | 8 axes |
| Interpolation Function |  | No |  |
| Control Method |  | PTP (Point To Point) control, path control (linear only), speed-position switching control |  |
| Control Unit |  | Pulse |  |
| Data Backup |  | No |  |
| Positioning Control | Positioning Control Method | PTP control : Incremental system/absolute system Speed-position switching control : Incremental system Path control : Incremental system/absolute system |  |
|  | Positioning Control Range | Absolute system: -2147483648 to 2147483647 (pulse) Incremental system: -2147483648 to 2147483647 (pulse) Speed-position switching control: 0 to 2147483647 (pulse) |  |
|  | Speed Command | 0 to 200000 (pulse/s) |  |
|  | Acceleration/Deceleration Processing | Trapezoidal acceleration/deceleration |  |
|  | Accel./Decel. Time | 0 to 32767 (ms) |  |
| External Device Connection Connector |  | A6CON1, A6CON2 (option), A6CON4 |  |
| Pulse Output Method |  | Open collector output |  |
| Max. Output Pulse |  | 200kpps |  |
| Max. Connection Distance Between QD70 and Drive Unit |  | 2 m (6.56 feet) |  |
| Internal Current Consumption (5VDC) |  | 0.55A | 0.74A |
| External 24V Current Consumption (24VDC) |  | 0.065A | 0.12A |
| I/O Device Points Occupied |  | 32 points (l/0 assignment: Intelligent function module 32 points) |  |
| Weight (kg) |  | 0.15 | 0.17 |
| Base Unit Slots Occupied |  | 1 |  |

## Q Series / V680 Series RFID Interface Module

The RFID interface module is mounted on a Q Series platform enabling communication with Omron V680 Series RFID systems.

| Model Number |  | EQ-V680D1 | EQ-V680D2 |
| :---: | :---: | :---: | :---: |
| Stocked Item |  | - | - |
| Certification |  | UL •CE |  |
| Manufactured by Omron Corporation Connectable Antenna |  | $\begin{aligned} & \text { V680-HA63A+V680-HS_ _; V680-HA63B+V680-HS__ } \\ & \text { V680-H01-V2 } \end{aligned}$ | V680-HA63A+V680-HS_ _ V680-HA63B+V680-HS_ _ |
| No. of Connectable Antennas |  | 1 antenna | 2 antennas |
| No. of Occupied IO Points |  | 32 points (I0 assignments: 32 intelligent module points) |  |
| Data Transfer Volume |  | 2,048 bytes, maximum |  |
| Internal Power Supply Current Consumption 5VDC (Supplied From Inside the Programmable Controller) |  | 0.42A | 0.52A |
| External Power Supply Current Consumption 24VDC (20.4 to 26.4VDC) |  | 0.25A | 0.37A |
| External Power Supply Connection Terminal |  | 2-point terminal block |  |
| Wiring Recommendations | Wire Standard | Heat Resistant PVC Insulated Wire; JIS C 3316 HKIV,JIS C 3317 HIV, UL 758 Style No. 1007 r1015 |  |
|  | Temperature Rating | Minimum $75^{\circ} \mathrm{C}$ |  |
|  | Voltage Rating | 300 V to 600V |  |
|  | Conductors Wire Size | AWG18 (0.75mm², 0.9mm) |  |
|  | Conductors Metal | Stranded copper |  |
| Compatible Crimp Contact Lugs |  | 1.25-3, R1.25-3 |  |
| Outer Dimensions (Hx W x D) mm |  | $98 \times 27.4 \times 106.5$ |  |
| Weight (kg) |  | 0.2 | 0.2 |

