



# Programmable Controllers MELSEC-L series

# Little on size, Large on performance

The new L series has a small footprint and is loaded with features.







# GLOBAL IMPACT OF MITSUBISHI ELECTRIC



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

# Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following

#### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

#### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

#### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

#### **Information and Communication Systems**

Commercial and consumer-centric equipment, products and systems.

#### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.

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L Series Features

# Simple

# **Flexible**

CPU P.13

# Convenience that fits in the palm of your hand

The L Series is a compact-class controller, part of the MELSEC products renowned for exceptional cost verses performance and strong reliability. It provides the performance, functions, and capabilities required for today's demanding applications in a small

MELSEC-L Series greatly expands the range of functionality traditionally associated with compact programmable controllers and through user-centric design, pushes the limits of ease of use.

# Ideally configured to satisfy the applications requirements

MELSEC L Series has been designed with three key concepts in mind.

#### Reliability

Robust and trusted MELSEC product quality.

#### Ease-of-use

Enabling engineers and programmers to do their job as efficiently as possible to reduce costs.

#### Flexibility

L Series is a cost-efficient control system flexible to various applications, enabling an ideal system design.

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Analog/ Temperature Control

P.25

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**USB** 

**Built-in I/O functions** 

Display unit\*1

Positioning **High-speed Counter** 

**Pulse Catch** 

Interrupt Input

General Purpose I/O

**Built-in CC-Link** 

connectivity\*2

Network

Flexible I/O/ **High-Speed Counter** 

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Ethernet\*3

Time setting function

SD memory card slot\*3

Data Logging

Backup & Restore

Simple PLC nunication function

Predefined protocol support function

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<sup>\*1:</sup> Option (sold separately). Does not support L02SCPU(-P). \*2: Included with L26CPU-(P)BT

<sup>\*3:</sup> Included with L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT



# L Series Built-in I/O Features

Every L Series CPU comes with 24 points of built-in I/O standard. These I/O points are capable of many functions usually reserved for separate modules. Save on system costs by using the built-in functions rather than relying exclusively on additional modules.

The built-in I/O\*1 comes in sink or source type format and may be chosen based on the application.

■ L Series CPU Built-in I/O Functions

Positioning (Built-in control of 2 axes	High-Speed Counter (Two channels built-in)	Puls	e Catch	Interrupt Input	General-purpose Input/Output		
	Function		Features				
Positioning*2	Number of axes: Maximum 2 axe	es	Maximum speed: 200K pulses/s High-speed activation: 30 µs (Shortest activation time) S-curve acceleration and deceleration are supported.				
High-Speed Counter*2	Number of channels: Maximum 2	2 channels		a resolution of 5 µs ligh speed pulse output)			
Pulse Catch	Number of input points: 16 points	s	Minimum input response time: 10 µs Pulse signals whose ON time is shorter than the scan time can be det				
Interrupt Input	Number of interrupt points: 16 po	bints: 16 points  Built-in CPU provides high-speed processing.  All input points support interrupt inputs.					
General-purpose Input	Number of high-speed inputs: 6 Number of standard inputs: 10 p		Minimum input response time of high-speed input: 10 μs Minimum input response time of standard input: 100 μs				
General-purpose Output	ut Number of output points: 8 points Output response time: 1 µs or less						

<sup>11:</sup> The L02SCPU, L02CPU, L06CPU, L26CPU and L26CPU-BT are sink type, and the L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P and L26CPU-PBT are source type.

# Easy setup of built-in I/O functions

Configuring built-in I/O functions can be done easily by setting parameters using the programming tool.

	Traut Sprid Function Selection		Response Term		Interset Processing Condition	
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SIA.	Interrupt input	*	STR. STRE STREET	100	Rorg	- 5
80	Interrupt Erport	*	19st		Faling	
	General Digust	7	1064	-	Maria -	п
207	General Insul	*	10ms		North Control	113
200	General Impor		Libria Clima	w	Rimg	1
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Counter Promet	Linear Counter	
Punchin Republicate Seriesa	Prestive Logic	19
Counter Punction Selection	Count Drosbling Function	
Completions Distant Time Preset Setting	Post present.	- 3
Concilence Selection Enterrupt Selling (Courter Indian Concidence No. 1)	hot used.	
Considered Detection Enterrupt Setting (Counter Your Considered No. 2)	Not used	- 3
Sargeling Time Setting (ma) Frequency Movement Averaging Processing Count		
Fraguetry Pleasurement Unit Time Setting Robuston Special Homement Averaging Processing Count.		- :
Science Speed Peasurement Life Tox Serling		
Number of Pulses per Robeton (pulse)  Pulse Planscomment Terget Setting		-

Built-in I/O function example parameter settings
Pulse Catch: 0.01 ms (response time)
Interrupt Input: 1 ms (response time)

Positioning function example parameter settings
Pulse Output Mode: CW/CCW mode
Rotation Direction Setting:
Current Value Increment with Forward Run Pulse Output

High-speed counter function example parameter settings
Pulse Input Mode: 1-Phase Multiple of 1
Counting Speed Setting: 100 kpps

Positioning

High-Speed Counter

# **Built-in CPU positioning control function**

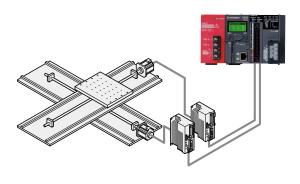
# **Positioning function**

The built-in positioning function has a start time of just 30  $\mu$ s with a maximum high speed output of 200K pulses per second.

Furthermore, it supports S-curve acceleration and deceleration for applications that require minimal machine vibration.

#### **High-speed counter function**

Two channels support the high speed counting function. The differential line driver inputs support counting speeds up to 200K pulses per second.



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<sup>\*2:</sup> Points used by the positioning and high speed counting functions are fixed (as in A phase, B phase, near-point dog).

Custom points for these functions may not be assigned.

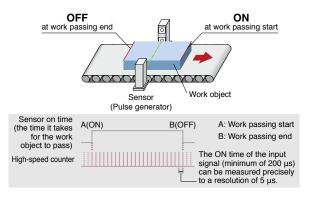
MELSEG L series

# Make highly accurate measurements with a resolution of 5 µs

**High-Speed Counter** 

Using pulse measurement mode, where the input signal ON/ OFF time is 200 µs or greater, highly accurate measurements in units of 5 µs or greater are possible.

For example it is possible to calculate length by knowing the "work object passing speed" and measuring the ON time of the sensor.



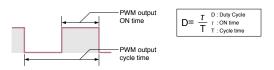
#### **High-Speed Counter**

#### High precision PWM control up to 200 kHz

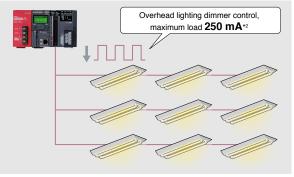
Using the pulse width modulation control function of the high speed outputs, cycle times as fast as 5 µs can be created. Simply input the ON time and cycle time to drive a wide range of devices from lighting dimmer control, motors, and heaters to precision inspection equipment requiring high resolution performance.

Setting item		Setting range	Description	
	PWM output	0 or 10	Set the ON time of output pulse	
	ON time*1	10000000*1 (0.1 μs)	Set the ON time of output pulse	
	PWM output	5010000000*1 (0.1 μs)	Set the cycle time of output pulse	
	cycle time*1	σο 10000000 * (0.1 μs)	Set the cycle time of output pulse	

\*1: The PWM output ON time must be ≤ than PWM output cycle time.



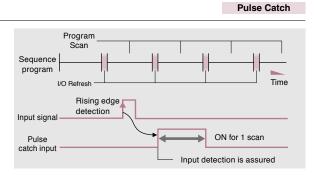
#### ■ Lighting dimmer control using PWM output



\*2: In cases where the first six digits of the serial number are "120722" or later. Previous serial numbers of the CPU module are applied to 100 mA

# Guaranteed input pulse detection

Typical programmable controller input devices are unable to detect pulse signals whose ON time is shorter than the scan time or do not occur during I/O refresh periods. The pulse catch function allows these signals to be reliably detected and passed to the sequence program. This function is different from the interrupt input function in that it does not require any special programming. Pulse catch inputs may be used in programs exactly the same as traditional input (X) signals.



# CPU with built-in CC-Link network connectivity

L Series CC-Link ready CPUs are compatible with the latest generation of CC-Link devices and support connections with over 1,000 different product types. Without adding a module, these CPUs can perform high-speed communication with a maximum of 128 words\*3 between a master station and a local station. CC-Link is the dominate FA network standard in Asia and continues to gain support worldwide.



# CPUs with built-in CC-Link can function as master or local stations. Local station Master station Up to 128 words\*3 CC-Link Master Local stations (Up to 26)

Choose from an extensive range of CC-Link compatible equipment Up to 64 devices can be connected.

L26CPU-(P)BT

<sup>\*3:</sup> When the number of occupied stations is 4 and the extended cyclic setting is



# Convenient communication and storage options come as standard

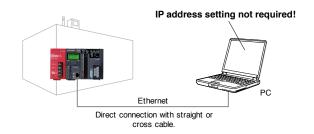
Program, configure, and perform diagnostics on L Series systems using either the USB 2.0 or Ethernet connections. The SD Memory Card slot has many uses including the easy backup and restore of programs and parameters.



L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT

# **USB** and Ethernet connections standard

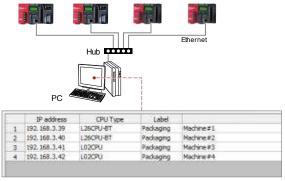
Use the USB 2.0 interface or Ethernet to connect directly at the instillation site. The Ethernet interface supports direct connection with either a cross or straight LAN cable and does not require any configuration of the programmable controller or PC to operate.



#### Easy connection through hub

All CPUs connected to the same hub can be searched and displayed in a list.

By selecting the access target CPU from the list, it can be connected to even if the IP address is unknown.

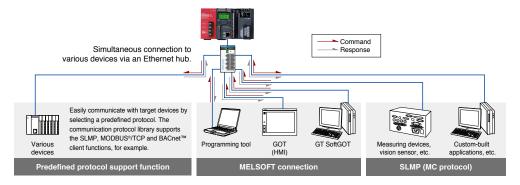


Use GX Works2 to retrieve a list of all CPUs connected to the network.

# Easily connect to BACnet™ and MODBUS®/TCP Improved function

Ethernet realizes a high-speed connection, such as communication with external devices.

By using the predefined protocol support function, various devices that require open network protocol support, such as BACnet<sup>™</sup> and MODBUS®/TCP are supported.

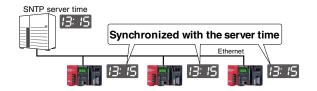




# **Network timestamp**

Synchronize systems on an Ethernet network using an SNTP\*1 server. Time synchronization can be achieved to enable simultaneous operations, quality control, or error tracking.

\*1: SNTP: Simple Network Time Protocol



# Program-less device data transfer

#### Simple PLC communication function\*2

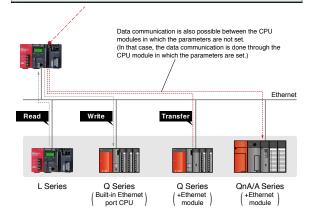
Using the programming tool, a simple parameter setting is all that is needed to transfer device data such as production information with no programming required.

This function makes it possible to easily establish communications not only with L Series, but also Q Series and QnA/A Series controllers.

\*2: CPU module whose first five serial number digits are "13042" or later is required.

Item		Description				
	Read	Read the data of the specified destination device (transmission source) to the specified device of the host station (transmission destination).				
Communication pattern	Write	Write the data of the specified device of the host station (transmission source) to the specified destination device (transmission destination).				
	Transfer	Read the data of the specified destination device (transmission source) and write it to another specified destination device (transmission destination).				
Communication	Execution interval	Set between 10 ms and 65535 ms (1 ms unit)				
setting	Request contact	Data send/receive is executed at the rising edge (OFF to ON) of the specified device (X, M, B).				
	Setting No.	Set between 1 and 64.				
Available devices	Device points	The maximum number that can be set for each setting No. is 512 words. (Maximum points of a word device: 256 points + Maximum points of a bit device: 4096 points) The total of setting No. 164 is maximum 4096 words.				





# SD memory card special features

Use the SD/SDHC compatible memory card to quickly and easily back-up the CPU programs and parameters. The backups can then be just as easily restored or used to program other CPUs. The memory card can also be used to hold data captured with the data logging function\*3.

\*3: For details about the data logging function, please refer to page 9.

#### Save/load programs directly into the Programmable Controller

#### Multiple project save/load function\*4

Parameters, program files, etc., can be saved/read onto an SD memory card by simply using the onboard display unit, without having to connect to a separate PC. Once saved on the SD memory card, files can be sent via e-mail, for example, when requiring off-site editing of the files.

\*4: Supported by CPU module whose first five serial number digits are "14042" or later.







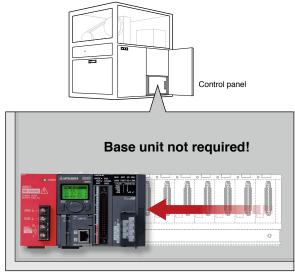
# Gain more flexibility with an integrated system bus structure

Save space in control panels by utilizing the integrated system bus structure. Flexibility in system design is made possible by choosing only the required expansion modules for the application.

# Expand L Series systems with no base unit restrictions

L Series modules do not require a base unit. The installation space is not restricted by base size, and the system can be installed with minimal required space.

Furthermore, the addition of modules to the system is not restricted by the number of available base unit slots and costs may be reduced due to the elimination of extension base units.

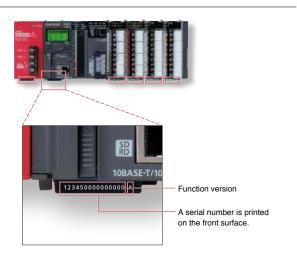


Installation space is reduced in the control panel

# Identify important information easily

Every L Series module has the serial number printed on the front surface of the module to allow viewing even during system operation (modules do not need to be removed).

\*: Serial numbers can also be checked using GX Works2.



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# MELSEG L series

# System expandable according to production equipment scale

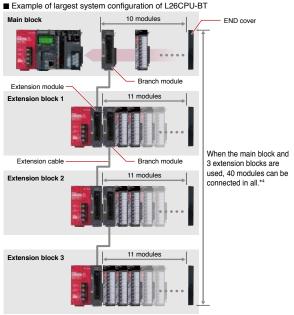
Up to three extension blocks connectable to the main block using branch and extension modules. A maximum of 40 modules\* caters a wide range of production equipment and line scale.

CPU module*2 Number of extension blocks		Number of connectable modules*3		
L02SCPU(-P)	Lin to O blooks			
L02CPU(-P)	Up to 2 blocks	Main block: 10 modules		
L06CPU(-P)		Extension block: 11 modules		
L26CPU(-P)	Up to 3 blocks	Extension block: 11 modules		
L26CPU-(P)BT				

- \*1: In the case of L06CPU(-P), L26CPU(-P), and L26CPU-(P)BT.
- \*2: CPU modules whose first five serial number digits are 13072 or later.
- \*3: Total number of I/O modules, intelligent function modules, network modules and branch modules.

This does not include the following: Power supply, CPU, display units, extension modules, RS-232 adapter, RS-422/485 adapter, and END covers.

When adding a branch module to a fully occupied block, relocate one of the other modules to a new block to give way to the branch module.



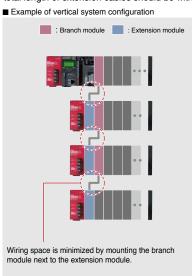
\*4: Total number of I/O modules, intelligent function modules and network modules, excluding branch modules.

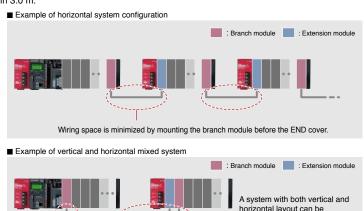
# Well-organized control panel with minimum wiring

Branch module can be strategically placed in a block to minimize wiring space. Extension cables are available in 0.6-, 1.0- and 3.0-m. The maximum extension length is 3.0 m\*5.

The extension cable is a one-touch type which can be easily connected and disconnected.

\*5: The total length of extension cables should be within 3.0 m.





A system with both vertical a horizontal layout can be configured to match the installation space.

The modules can be replaced according to the system configuration!

■ Installation position when branch or extension module is used

1000		Installation
	<b>.</b>	Modul
		Branch mod
	1	Extension n

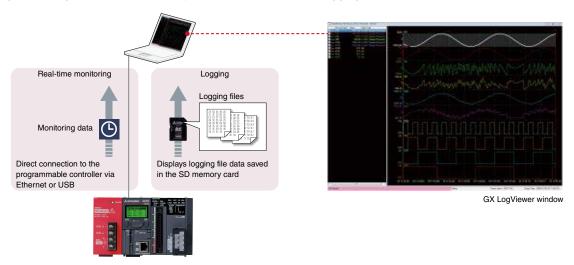
Matching	marks on
the slot an	d the cable

Installed block Possible installation position			
Main block	Right side of CPU module or left side of END cover		
Extension block	Right side of extension module or left side of END cover		
Main block	Not applicable		
Extension block	Right side of power supply module		
	Main block Extension block Main block		



# Easily collect production data

Utilizing the installed SD memory card or a direct live connection to the CPU module, logging data can be easily realized just by simply registering parameters. Logged data can be saved in CSV format and utilized in a number of ways, such as for using on third-party spreadsheet software or as a real-time feed data for analyzing various manufacturing processes. The real-time feature of GX LogViewer also enables live feeds showing device status changes, helping to improve traceability, smooth startup, and debugging.



#### Logging of control data variances

Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.

■ Generic sample data from a PC or external device at 100 ms intervals

■ L Series data logging function is capable of sampling data at much higher intervals as to detect fast changing values.

Rapidly changing values result in undetected errors

Value deviation are detected and clearly identified.

Measure value (PC)

Measure value (PC)

Measure value (PC)

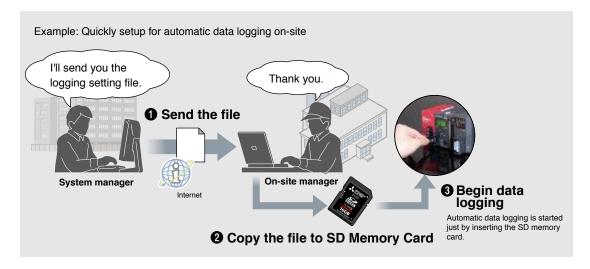
300 ► Time [ms]

► Time [ms]



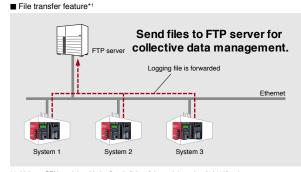
# **Auto logging function**

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card.



# Automatically send logging files to FTP server

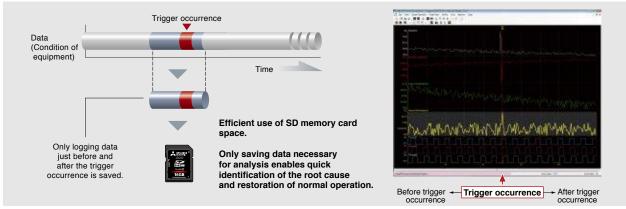
Data logging files saved on the SD memory card can be sent to the FTP server just by making a simple setting with the logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.



\*1: Using a CPU module with the first 5 digits of the serial number "12112" or later.

# **Trigger logging function**

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.



To receive a copy of GX LogViewer, contact your local Mitsubishi Electric representative.

# **L Series Features**



# Feature rich and easy to use display

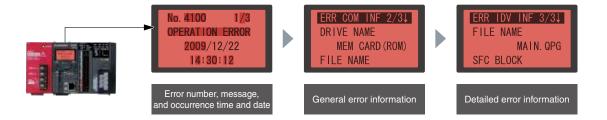
Check the system status and make setting changes directly from the display. Error status is clearly identified and troubleshooting and error investigation can be performed all without the need for any connections or engineering software.

\*: Not available for L02SCPU(-P).

L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT

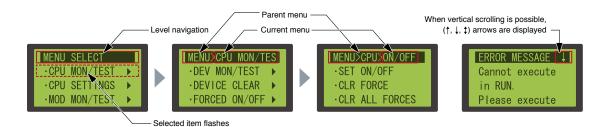
# Instant error information check

Error history and detailed error information are available directly from the display unit.



# Intuitive menu navigation

The menu navigation guide shows the current menu tree location and an arrow to indicate the scroll direction at the top of the display.



# **Multilingual operation**

The display unit language can be selected (Japanese or English).







# An easy-to-use modular design

The L Series module labeling design has been created to ensure clear legibility and identification of information at a glance to avoid mistakes.

# Universal design

# Adopting a universal font

A high visibility font has been chosen for characters printed on system modules.



■ Regular Gothic font

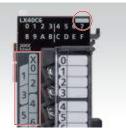
The characters are thick enough. however the numbers "3, 6, 8, 9" and the alphabet "C" are not clearly distinguishable because the spacing indicated with a red circle is not large

The space indicated with a red circle has been enlarged.

The numbers "3, 6, 8, 9" and the alphabet "C" are clearly distinguishable. Characters are legible even in small print.

#### Module design

White and red are used to distinguish inputs from outputs respectively to allow for easy identification of terminal connection type.



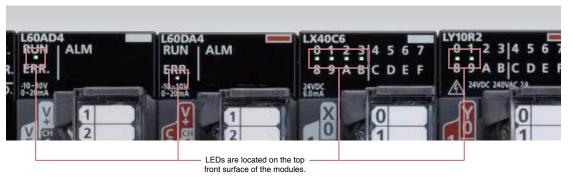
White for input module



Red for output module

# Easily identify module status

LEDs display the current status of modules including run and error states.



# **CPU Modules**

Communication interface: RS-232



#### L02SCPU

#### L02SCPU-P

General-purpose output: Sink type Program capacity: 20K steps Basic operation processing speed: 60 ns General-purpose output: Source type Program capacity: 20K steps Basic operation processing speed: 60 ns

\*: End cover is enclosed.

Cannot be mounted on display unit (L6DSPU). RS-232 adapter, RS-422/485 adapter.

Communication interface:



L02CPU

#### L02CPU-P

General-purpose output: Sink type Program capacity: 20K steps Basic operation processing speed: 40 ns

\*: END cover is included.

General-purpose output: Source type Program capacity: 20K steps Basic operation processing speed: 40 ns



#### L06CPU

#### L06CPU-P

General-purpose output: Sink type Program capacity: 60K steps Basic operation processing speed: 9.5 ns

\*: END cover is included.

General-purpose output: Source type Program capacity: 60K steps Basic operation processing speed: 9.5 ns



#### L26CPU

#### L26CPU-P

General-purpose output: Sink type Program capacity: 260K steps Basic operation processing speed: 9.5 ns

\*: END cover is included.

General-purpose output: Source type Program capacity: 260K steps Basic operation processing speed: 9.5 ns





#### L26CPU-BT

#### L26CPU-PBT

General-purpose output: Sink type Program capacity: 260K steps Basic operation processing speed: 9.5 ns General-purpose output: Source type Program capacity: 260K steps Basic operation processing speed: 9.5 ns

\*: END cover is include

Model	General-purpose output	Number of I/O points	Program capacity	Basic operation processing speed (LD instruction)	Peripheral connection ports	Built-in network
L02SCPU		1024 points	001/	60 ns	USB/RS-232	_
L02CPU		1024 points	20K steps	40 ns	USB/Ethernet	_
L06CPU	Sink type		60K steps			_
L26CPU		4096 points		9.5 ns		_
L26CPU-BT		260K s	260K steps			CC-Link
L02SCPU-P		1024 points	1024 points 20K steps	60 ns	USB/RS-232	_
L02CPU-P		1024 points	ZUK Steps	40 ns		_
L06CPU-P	Source type	Source type 4096 points	60K steps	9.5 ns	USB/Ethernet	_
L26CPU-P						_
L26CPU-PBT			260K steps			CC-Link

#### **CPU** packages

- ■L02CPU-SET
- Includes CPU (L02CPU), power supply module (L61P), and display unit (L6DSPU).
- ■L02CPU-P-SET

Includes CPU (L02CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L26CPU-SET
- Includes CPU (L26CPU), power supply module (L61P), and display unit (L6DSPU).
- ■L26CPU-P-SET

Includes CPU (L26CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L06CPU-SET
- Includes CPU (L06CPU), power supply module (L61P), and display unit (L6DSPU).
- ■L06CPU-P-SET

Includes CPU (L06CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L26CPU-BT-SET
- Includes CPU (L26CPU-BT), power supply module (L61P), and display unit (L6DSPU).
- ■L26CPU-PBT-SET

Includes CPU (L26CPU-PBT), power supply module (L61P), and display unit (L6DSPU).



MELSEG L series

#### **■** General specifications

General specifications indicate the environmental specifications in which this product can be installed and operated. Unless otherwise specified, these general specifications apply to all L Series products.
\*: General specifications of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi Electric representative.

Item	Specification							
Operating ambient temperature	055°C							
Storage ambient temperature	-2575°C							
Operating ambient humidity Storage ambient humidity	595%RH, non-condensing							
			Frequency	Constant acceleration	Half amplitude	Sweep count		
Vibration resistance	Compliant with JIS B 3502 and IEC 61131-2	Under intermittent vibration	58.4 Hz	_	3.5 mm	10 times each in		
			8.4150 Hz	9.8 m/s <sup>2</sup>	_	X, Y, Z directions		
		Under continuous vibration	58.4 Hz	_	1.75 mm	_		
			8.4150 Hz	4.9 m/s <sup>2</sup>	_			
Shock resistance		Compliant with JIS B	3502 and IEC 61131-2 (	147 m/s <sup>2</sup> , 3 times each in	directions X, Y, Z)			
Operating atmosphere			No corrosi	ve gases				
Operating altitude*1	02000 m							
Installation location			Inside a cor	trol panel				
Overvoltage category*2		≤II						
Pollution degree*3	•		≤ 2	2				
Equipment class			Class	i I				

<sup>\*1:</sup> Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0 m.

Doing so may cause malfunction. When using the programmable controller under pressure, please consult your local Mitsubishi Electric representative.

\*2: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises.

Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

\*3: This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used.

Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally.

■ CPU module specifications

	Item		L02SCPU L02SCPU-P	L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT
Control method			L025CPU-P		pred program cyclic operation		L20CPU-PB1
Control metriou			Refresh mode				
I/O control mode			(The direct	access input/output is av	vailable by specifying the di	rect access input/outpu	it (DX, DY).)
Programming languag	е		Function block rela	v symbol language MEI	SAP3 (SEC) MEI SAP-L e	tructured text (ST) log	ic symbolic language
(sequence control lang	<del>, , , , , , , , , , , , , , , , , , , </del>		Function block, relay symbol language, MELSAP3 (SFC), MELSAP-L, structured text (ST), logic symbolic language				
Processing speed*4	LD instruct		60 ns	40 ns 9.5 ns			
(sequence instruction)	MOV instru	uction	120 ns	80 ns		19 ns	
Constant scan			0014 -+ /		is available in increments of		(40.40K h. +)
Program capacity	Drogram m	nemory (drive 0)	20K steps ( 80K b		60K steps (240K bytes) 240K bytes		(1040K bytes) 0K bytes
		rd (RAM) (drive 1)	OUN I	lytes .	240K bytes	1040	in bytes
Memory capacity		rd (ROM) (drive 1)			Depends on the SD/SDH	C memory card used *5	3
wemory capacity	_	RAM (drive 3)	128K	hvtes	Depends on the OD/ODIT	768K bytes	
		ROM (drive 4)	512K	·	1024K bytes		BK bytes
	Program m		64 f	•	124 files		2 files
	Memory ca				_		2 11100
		1 ,		Root directory: 511 files (maximum)			
Maximum number of	Memory card (ROM)	SD	_	Subdirectory: 65533 files (maximum)			
files stored		SDHC		Root directory: 65534 files (maximum)			
		SDHC	Subdirectory: 65533 files (maximum)				
	Standard RAM		4 files (each one of the following files: file register file, local device file, sampling trace file, and module error collection file)				
	Standard F		128 files 256 files				
Maximum number of in	•	Initial setting		2048 parameters 4096 parameters			
function module paran		Refresh	<u>'</u> _	parameters 2048 parameters			
Maximum number of in	nstallable mo	odules*6	3(			40	
Built-in I/O function				Refer to the built-in I/O specifications ⇒ P.16 to P.18  Pefer to the data legging function specifications ⇒ P.17			
Data logging function Built-in Ethernet functi			_	Refer to the data logging function specifications → P.17  Refer to the built-in Ethernet specifications → P.18			
built-in Ethernet luncti	OH		Refer to the built-in		Refer to the built-in Ethern	et specifications - P. I	<u> </u>
Built-in serial commun	ication funct	ion	serial communication		_		
Dant-III Serial Commun	ication funct	1011	specifications ⇒ P.18				
Built-in CC-Link function	on			Refer to the CC-L Master/Local Mod			Refer to the CC-Link Master/Local Module specifications. → P.55
	Displayed	information	Year mo	onth, date, hour minute s	second, and day of the wee	k (automatic leap vear	
	,		Year, month, date, hour, minute, second, and day of the week (automatic leap year detection)  0°C: -2.96+3.74 s (TYP. +1.42 s) per day				
Clock function	Accuracy				.18+3.74 s (TYP. +1.50 s)	,	
				55°C: -13	3.20+2.12 s (TYP3.54 s)	per day	
5 V DC internal	CPU	With display unit	_	1.00 A	1.06	A	1.43 A
current consumption		Without display unit	0.75 A	0.94 A	1.00	A	1.37 A
ourioni consumption	END cover	r (Accessory)*7			0.04 A		
	CPU	With display unit	_		0.40 kg		0.50 kg
Weight		Without display unit	0.32 kg		0.37 kg		0.47 kg
	END cover	r (Accessory)*7			0.06 kg		

<sup>\*4:</sup> Indexing devices does not delay processing time.

<sup>\*5:</sup> The operation of devices that are not manufactured or recommended as compatible products by Mitsubishi Electric cannot be guaranteed.
\*6: The total number of modules that can be installed onto a CPU module. Also refer to the "Module size allocation" for each module.

<sup>\*6:</sup> The total number of modules that can be installed onto a CPU module. Also refer to the "Module size allocation" for each module. (Power supply modules, CPU module, Display unit, Extension module, RS-232 adapter, RS-422/485 adapter, END cover, and END cover with error terminal are not included. Note that only one CPU per system is possible.)

<sup>\*7:</sup> The END cover is included with the CPU module and must be placed on the right end of the last module in the system.

# ■ CPU module device specifications

	Item	L02SCPU L02SCPU-P	L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT	
Number of I/O device points							
(number of points	available on a program)	8192 points (X/Y0X/Y1FFF)					
Number of I/O points		1024 points (X/Y0X/Y3FF)		4096 points (X/Y0X/YFFF)			
Internal relay (M)			8192 points	(M0M8191) by default (	changeable)		
Latch relay (L)			8192 points	(L0L8191) by default (c	hangeable)		
Link relay (B)			8192 points	(B0B1FFF) by default (d	changeable)		
		2048 poi		It (changeable) (Low-spee		available)	
Timer (T)		(Low-speed timer: 11000 ms (in increments of 1 ms), default: 100 ms)					
				.100 ms (in increments of			
		· ·		e)(Low-speed and high-spe		,	
Retentive timer (S	Т)	,		11000 ms (in increment	,,	,	
2 (2)		(Hi	• •	0.1100 ms (in increment		ms)	
Counter (C)				4 points (C0C1023) by c			
Data register (D)		00700 /D1000		(D0D12287) by default		. l	
Extended data reg	gister (D)	32768 points (D12288 (chang		·	ints (D12288D143359) (changeable)	) by default	
_ink register (W)			8192 points (W0W1FFF) by default (changeable)				
Extended link regi	ster (W)	0 point by default (changeable)					
Annunciator (F)		2048 points (F0F2047) by default (changeable)					
Edge relay (V)		2048 points (V0V2047) by default (changeable)					
ink special relay	(SB)	2048 points (SB0SB7FF) by default (changeable)					
ink special regist	er (SW)	2048 points (SW0SW7FF) by default (changeable)					
	(R)	32768 points ( (Maximum 65536 po	R0R32767) ints are available by		2768 points (R0R3276		
File register	,	switching	blocks.)	(Maximum 393216 points are available by switch	switching blocks.)		
	(ZR)	65536 points (Z	R0ZR65535)	3932	216 points (ZR0ZR393	215)	
	(ZN)	(Blocks do not nee	ed to be switched.)	(Block	s do not need to be swit	ched.)	
step relay (S)		8192 points (S0S8191) by default					
ndex register/star	ndard device register (Z)	20 point (Z0Z19) (maximum)					
ndex register (Z)			10	point (Z0Z18) (maximus	m)		
32-bit index modi	fication of ZR device)		(The index re	gister is used as a double-	word device.)		
Pointer (P)		4096 points (PC	P4095) (The local poin	ter range and the commor	pointer range can be se	t by parameter.)	
				256 points (I0I255)			
nterrupt pointer (I	)	(The fi		ystem interrupt pointer I28	, ,	meter.)	
	,			000 ms (in increments of 0	,		
		Default I28: 100 ms, I29: 40 ms, I30: 20 ms, I31: 10 ms					
Special relay (SM)		2048 points (SM0SM2047) (The number of device points is fixed.)					
Special register (SD)		2048 points (SD0SD2047) (The number of device points is fixed.)					
Function input (FX)		16 points (FX0FX F) (The number of device points is fixed.)					
Function output (FY)			<u> </u>	FY F) (The number of device			
unction register (	FD)			D4) (The number of device	<u> </u>		
ntelligent function	module device	D		es the buffer memory of an ecification format: U□□/G[		ule	
_atch (data retenti	on during power failure) range	(The l	8192	2 points (L0L8191) by de	fault	neter \	
		(The latch range can be set for the devices, B, F, V, T, ST, C, D, W, and R by parameter.)					

MELSEG L series

■ CPU built-in I/O function – input specifications (general-purpose input/interrupt input/pulse catch function)

Item			Description	
	Points		10	
	Input voltage/current		24 V DC 4.1 mA (TYP.)	
Standard input	Minimum input response	time	100 µs	
	Input response time setti	ng	0.1 ms, 1 ms, 5 ms, 10 ms, 20 ms, 70 ms	
	Common terminal arrange	ment	10 points/common (Positive or negative common)	
	Points		6	
	Input voltage/current	DC input	24 V DC 6.0 mA (TYP.)	
		Differential input	EIA Standard RS-422-A Differential line driver level	
High-speed input		Differential input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
	Minimum input response	time	10 µs	
	Input response time setti	ng	0.01 ms/0.1 ms/0.2 ms/0.4 ms/0.6 ms/1 ms	
	Common terminal arrange	ment	Independent	

■ CPU built-in I/O function – output specifications (general-purpose output function)

Item		Description			
Points		8			
Output voltage/current		524 V DC 0.1 A			
Response time	OFF to ON ON to OFF	≤ 1 µs (rated load, resistance load)			
Common terminal arrangement		L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 8 points/common (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 8 points/common (Source type)			

■ CPU built-in I/O function – positioning function specifications

	Item		Description	
Number of c	ontrolled axes		2	
Control unit	Control unit		pulse	
Operation pattern		PTP*1 control	Available	
Operation pa	allem	Path control	Not usable	
Number of p	ositioning data		10 data/axis	
	Da sitia min manatant	PTP*1 control	ABS/INC	
	Positioning control method	Speed/position switching control	INC	
D !#!!		PTP*1 control	-21474836482147483647 pulses	
Positioning control	Positioning range	Speed/position switching control	02147483647 pulses	
	Speed command		0200k pulses/s	
	Acceleration/decelera	tion system selection	Automatic trapezoid acceleration/deceleration and S-curve acceleration/deceleration	
	Acceleration/decele	eration time	032767 ms	
OPR method	OPR method		6 types	
Ctautina tima	tarting time (1-axis linear control)		Trapezoid acceleration/deceleration (single-axis start): 30 μs/axis	
Starting time			S-curve acceleration/deceleration (single-axis start): 35 µs/axis	
	Pulse output metho	d	L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 524V DC (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 524V DC (Source type)	
Command	Pulse output mode		4 types	
pulse output	Maximum output pu	ılse	200k pulses/s	
	Maximum connection of	distance with drive unit	2 m	
		DC input	24 V DC 6.0 mA (TYP.)	
	Zero signal	·	EIA RS-422-A differential line driver level	
		Differential input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
	Speed/position swit	ching signal		
External	Near-point dog sign	nal	01// 20 44 4 4 77/2)	
input	Upper and lower lin	nit signal	24 V DC 4.1 mA (TYP.)	
	Drive unit ready sig	nal		
			Zero signal: 10 µs	
	Input response time	•	Speed/position switching control, near-point dog signal: 100 µs	
			Upper and lower limit signal, drive unit ready signal: 2 ms	
External	Deviation counter of	lear signal	L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 524 V DC 0.1A (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 524 V DC 0.1A (Source type)	
output	Response time OFF to ON ON to OFF		≤ 1 µs (rated load, resistive load)	

<sup>\*1:</sup> Abbreviation for "Point to Point." This is a type of position control.

■ CPU built-in I/O function – high-speed counter specifications

nels		2 1-phase input (1 multiple/2 multiples)		
		CW/CCW,		
		2-phase input (1 multiple/2 multiples/4 multiples)		
	DC input	24 V DC 6.0 mA (TYP.)		
gnal level	Differential	EIA Standard RS-422-A Differential line driver level		
	input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent		
aximum counting speed		200k pulses/s (for 2 multiples of 1 phase and 4 multiples of 2 phases)		
ounting range		-21474836482147483647		
odel		UP/DOWN preset counter (with ring counter function)		
nimum count pulse	1 phase	5 µs		
dth (Duty ratio 50%)	2 phases	10 us		
n, phase differential for	2-phase			
input		5 μs		
	DC input	24 V DC 6.0 mA (TYP.)		
ase Z (preset)	_	EIA Standard RS-422-A Differential line driver level		
(J. 1117)		AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent		
nction start				
Latch		24 V DC 4.1 mA (TYP.)		
Input response time		Phase Z: 10 µs		
		Function start, latch: 100 µs		
		L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: Sink type		
Output format		L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: Source type		
	Coincidence			
	output No. 1 /	524 V DC/0.25 A*1		
tput voltage/current	PWM output			
	Coincidence	5 01/100011		
	output No. 2	524 V DC/0.1 A		
	OFF to ON			
sponse time	ON to OFF	≤ 1 µs (Rated load, resistance load)		
mparison range		-21474836482147483647		
<u> </u>		Set value < Counted value		
mparison result		Set value = Counted value		
		Set value > Counted value		
itput points		2 points/channel		
tput frequency range		DC200 kHz		
N width		1 µs		
ity ratio		On width can be set in increments of 0.1 µs.		
itput points		1 point/channel		
easurement item		Pulse width (On width: ≥ 200 μs, Off width: ≥ 200 μs)		
easurement resolution		5 μs		
Measurement points		5 μs 1 point/channel		
nidton	del imum count pulse the (Duty ratio 50%). phase differential for ut use Z (preset). Ction start with the country of the put format. The put voltage/current uponse time imparison range imparison result put points put frequency range width by ratio put points asurement item.	del imum count pulse the (Duty ratio 50%)   1 phase 2 phases   2 phases   2 phases the (Duty ratio 50%)   2 phases   2 phase the (Duty ratio 50%)   DC input Differential input   Differential input		

<sup>\*1:</sup> For units where the first six digits of the serial number are "120722" or later. The specification for previous serial numbers is 5 to 24 V DC/0.1 A.

■ CPU data logging function specifications

Item		L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT			
Number of data logging settings			10					
			For each setting, any of 32 to 4832K bytes (in units of 1K byte) can be specified.					
Data logging	g buffer capa	acity	The total value of settings No.1 to No.10 is up to 5120K bytes.					
Data storage location				Standard ROM (configuration	files only), SD Memory Card			
Logging typ	е			<ul> <li>Continuous logging</li> </ul>	<ul> <li>Trigger logging</li> </ul>			
ъ.	Sampling in	nterval	• (	<ul> <li>Each scanning cycle condition specification (Device specification)</li> </ul>	<ul> <li>Time specification pecification, Step No. specification</li> </ul>	ion)		
Data sampling	No. of data	sampling points		Up to 1280 (128 p	points per setting)			
sampling	AND conju	AND conjunction  In the Sampling interval setting, Device and Step No. under "Condition specification" can be specified in co (AND conjunction).				be specified in combination		
		Trigger condition	• When	ition specification (Device chang trigger instruction executed data logging trigger activated				
Data	Trigger	AND conjunction	In the Trigger setting, Device data change and Step No. under "Condition specification" can be specified in combination (AND conjunction).					
processing	logging	Trigger logging range	Data of the specified number of records are logged before and after a trigger.					
		Number of triggers	1					
		Number of trigger logging records	Up to 1000000					
	File name			Up to 48 one-byte characters	•			
			• File numl		3 ( 1. )	nd time*3		
	File format			CSV				
File output	Data type		<ul><li>Bit</li><li>Double word (unsigned)</li><li>FLOAT (double precise)</li></ul>	,	d) • FLOA	(signed) iT (single precision) eric string: 1256 bytes		
	Data outpu	t format (CSV file)	Decimal to	ormat • Hexadecimal for	mat • Exponential forma	t		
Handling of	File	File switching timing		No. of records	File size			
output files	switching	Number of saved files		16	5535			
*O. D ( 4)-		ana this number is sutome	Alas III. a a a laura al					

<sup>\*2:</sup> Part of the saved file name, this number is automatically assigned.

 $<sup>^{\</sup>star}3$ : Optional data to be appended to the saved file name.



#### **■ CPU** built-in Ethernet function specifications

Item			L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT		
	Data transfer spee	ed	100 or 10 Mbps					
	Communication mode			Full-duplex or half-duplex				
Transmission	Transmission meth	nod		Base band				
specifications	Maximum distance be	etween hub and node	100 m					
	Maximum number of 10BASE-T		Cascade connection: Up to four					
	nodes/connection	100BASE-TX	Cascade connection: Up to two					
Number of	TCP/IP	Total of 16 for socket communications, MELSOFT connections, and MC protocol.*1			protocol.*1			
connections	UDP/IP		One for FTP					
Connection	10BASE-T		0BASE-T Ethernet cable of category 3 or higher (STP/UTP cable)*3					
cable*2	100BASE-TX		Ethernet cable of category 5 or higher (STP cable)					

- \*1: Only the QnA-compatible 3E frame may be used.
  \*2: Standard (straight type) cable. Also, when the CPU is connected directly with a GOT(HMI), a cross cable (category 5e or less) may be used.
- \*3: The use of STP (Shielded Twisted Pair) cables is recommended in noisy environments.

# ■ Communication performance comparison (Comparison of LCPU with built-in Ethernet port and Ethernet interface module)

Function/performance	LCPU with built-in Ethernet port	Ethernet interface module
Communication speed	100 Mbps	100 Mbps
MC protocol communication	●*4	•
Socket communication	<b>●</b> *5	(Fixed buffer communication)
Communications using a random access buffer	_	•
E-mail function	_	•
Communications using data link instructions	_	•
File transfer (FTP server) function	●*6	•
Web function	_	•
MELSOFT products and GOT(HMI) connection	•	•

- \*4: QnA compatible 3E frame device memory access commands only. Refer to the relevant manual for details.
- \*5: There are some differences regarding the fixed buffer communications function. Refer to the relevant manual for details.
- \*6: The "quote cpuchg" command is not supported.

#### ■ CPU built-in serial communication function specifications

CFO built-in serial communication function specifications				
Item	L02SCPU			
Item	L02SCPU-P			
Communication mode	Full duplex			
Synchronization method	Asynchronous method			
Transmission speed	9.6 kbps, 19.2 kbps, 38.4 kbps, 57.6 kbps, 115.2 kbps			
	Start bits: 1			
Data format	Data bits: 8			
Data format	Parity bits: Odd number			
	Stop bits: 1			
MC protocol format <sup>-7</sup> (automatic judgment)	• Formats 4 (ASCII)			
inc protocor format (automatic judgment)	Formats 5 (Binary)			
Frame*7	QnA compatible 3C frame			
rame.	QnA compatible 4C frame			
Transmission control	DTR/DSR control			
Transmission distance (Overall distance)	Maximum 15 m			

\*7: Information relevant to the MC protocol format and frame are shown below.

<ul><li>Supported</li></ul>	—: Not supported

_			-
Function		Formats 4	Formats 5
Communication with	QnA compatible 3C frame	•	_
ASCII code	QnA compatible 4C frame	•	_
Communication with binary code	QnA compatible 4C frame	•	•

# ■ How to read the product code

# . <u>26 □ CPU - P BT - SET</u>

Number	Item	Code	Specification
		02	20K steps
1	Program memory capacity	06	60K steps
	Сарасну	26	260K steps
Number	Item	Code	Specification
2	Communication interface	Blank	Built-in Ethernet model
	Communication interface	S	Built-in RS-232 model
Number	Item	Code	Specification
3	Type of module	CPU	CPU module
Number	Item	Code	Specification
4	Built-in I/O output	Blank	Sink type
•	format	Р	Source type
Number	Item	Code	Specification
(5)	Built-in CC-Link function	Blank	_
	Built-iii CO-Link iunction	BT	•
Number	Item	Code	Specification
6	Product set	Blank	_
	1 Toddot Set	SET	Set includes a power supply module (L61P) and display unit (L6DSPU)

# **Branch/Extension Modules**



#### ■ Branch and extension module specifications

ltem	L6EXB [ Branch module ]	L6EXE [ Extension module ]
5 V DC internal current consumption	0.08 A	0.08 A
Weight	0.12 kg	0.13 kg

#### **■** Extension cable specifications

Item	LC06E	LC10E	LC30E
Cable length	0.6 m	1.0 m	3.0 m
Weight	0.19 kg	0.23 kg	0.45 kg

# **Power Supply Modules**



# ■ Power supply module specifications

■ Fower supply module specification			
Item	L61P	L63P	L63SP
Input power supply	100240 V AC (-15%+10%)	100240 V AC (-15%+10%) 24 V DC (-35%+30%)	
Input frequency	50/60 Hz (-5%+5%)	<del>-</del>	_
Input voltage distortion	≤ 5%	<del>-</del>	_
Maximum input apparent power	130 VA	<del>-</del>	
Maximum input power	_	45	W
Inrush current	20 A, ≤ 8 ms	100 A, ≤ 1 ms (	(24 V DC input)
Rated output current (5 V DC)		5 A	
Overcurrent protection (5 V DC)		≥ 5.5 A	
Overvoltage protection	5.56.5 V		
Efficiency	≥70%		
Allowable momentary power failure time	≤ 10 ms	≤ 10 ms (24	V DC input)
	2300 V AC per minute	510 V AC per minute	
	(altitude 02000 m)	(altitude 02000 m)	
Withstand voltage	Between the combined	Between the combined	<u></u> *1
	"line input/LG terminals"	"line input/LG terminals"	
	and the "FG terminal and output".	and the "FG terminal and output".	
	10 MΩ or higher by 500 V	DC insulation resistance tester	
Insulation resistance	Between the combined "line input/LG terminals" and the "FG terminal and output".		*1
insulation resistance	The line input and LG terminals.		
	• The FG ter	The FG terminal and output.	
Weight	0.32 kg	0.29 kg	0.19 kg

 $<sup>^{\</sup>star}$ 1: There is no isolation between the primary side 24 V DC and secondary side 5 V DC.

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# MELSEG L series

# **RS-232 Adapter**



L6ADP-R2

Transmission speed: 115.2 kbps GOT(HMI) connection MELSOFT oonnection Predefined protocol support function Serial communication function

#### **MODBUS®**

\*1: Please refer to each MELSOFT product manual for details on the supported software

#### ■ RS-232 adapter specifications

Item	Specification	
Maximum data transmission speed	115.2 kbps	
5 V DC internal current consumption	0.02 A	
Weight	0.10 kg	

# **RS-422/485 Adapter**



L6ADP-R4

Transmission speed: 115.2 kbps GOT(HMI) connection Predefined protocol support function Serial Communication function

MODBUS®

# ■ RS-422/485 adapter specifications

Item	Specification	
Maximum data transmission speed	115.2 kbps	
5 V DC internal current consumption	0.15 A	
Weight	0.12 kg	

# **END Cover with Error Terminal**



#### **■ END cover with error terminal specifications**

■ END Cover with error terminal specifications				
Item			Specification	
	Rated switching voltage, current		24 V DC 0.5 A	
	Minimum switching load		5 V DC, 1 mA	
	Response time	OFF to ON	≤ 10 ms	
EDD terminal		ON to OFF	≤ 12 ms	
ERR. terminal	Life	Mechanical	≥ 20 million times	
		Electrical	Rated switching voltage/current: 10 million times or more	
	Surge suppressor		_	
	Fuse		_	
Applicable wire	size		0.32.0 mm² (AWG2214) (Twisted wire/Solid wire)	
External interfac	External interface		Spring clamp terminal block	
5 V DC internal current consumption		on	0.06 A	
Weight			0.11 kg	

# **Display Unit**



# L6DSPU

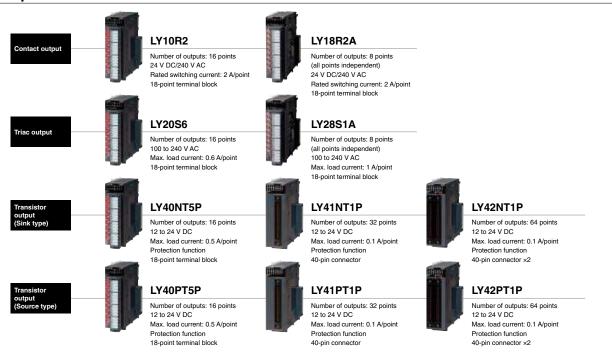
#### ■ Display Unit specifications

■ Display Office specifications		
Item	Specification	
Number of displayed characters	16 one-byte characters × 4 lines	
	Alphanumeric (two-byte/one-byte character)	
	Japanese character Katakana (two-byte/one-byte character)	
Displayed characters	Japanese character Hiragana (two-byte character)	
	Chinese character (two-byte character)	
	Symbol (two-byte/one-byte character)	
Language	Japanese/English	
Backlight	Green (normal), red (error)	
Weight	0.03 kg	

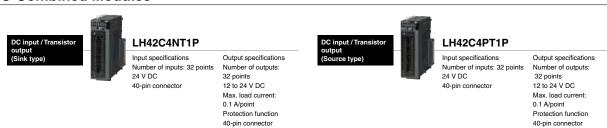
# Input Modules



# **Output Modules**



# I/O Combined Modules



#### Spring clamp terminal block (push-in type): L6TE-18S

The screw terminal block of installed modules can be replaced with a push-in type spring clamp terminal block. This terminal block type helps to reduce the amount of wiring and maintenance time.

■ Push-in type for reduced wiring

Easier to wire just by inserting into the terminal block.



■ Simple to confirm signal integrity

Includes dedicated terminals for insertion of a test probe, for example.



5

# MELSEG L series

# ■ Input module specifications AC input module

	Item	LX10	LX28
Number of input points		16 points	8 points
Rated input voltage, frequency		100120 V AC	100240 V AC
Hated Input v	rollage, frequency	(+10%/-15%), 50/60Hz (±3 Hz)	(+10%/-15%), 50/60 Hz(±3 Hz)
Input voltage	distortion	≤ 5	5%
			16.4 mA (200 V AC, 60 Hz),
Detections to		8.2 mA (100 V AC, 60 Hz),	13.7 mA (200 V AC, 50 Hz),
Rated input current		6.8 mA (100 V AC, 50 Hz)	8.2 mA (100 V AC, 60 Hz),
			6.8 mA (100 V AC, 50 Hz)
Inrush current		Max. 200 mA ≤ 1 ms	Max. 950 mA ≤ 1 ms
ON voltage/C	ON current	≥ 80 V AC /≥ 5 mA (50 Hz, 60 Hz)	
OFF voltage/	OFF current	≤ 30 V AC /≤ 1.7 mA (50 Hz, 60 Hz)	
Input resistar	nce	12.2 kΩ (60 Hz), 14.6 kΩ (50 Hz)	
D	OFF to ON	≤ 15 ms (100 V AC 50 Hz, 60 Hz)	≤ 15 ms (100 V AC 50 Hz, 60 Hz)
Response	OFF to ON		≤ 10 ms (200 V AC 50 Hz, 60 Hz)
time	ON to OFF	≤ 20 ms (100 V AC 50 Hz, 60 Hz)	≤ 20 ms (100/200 V AC 50 Hz, 60 Hz)
Common terr	ninal arrangement	16 points/common	8 points/common
Module size	allocation	1	
Number of o	ccupied I/O points	16 points (I/O assignment: input 16 points)	
External interface		18-point terminal block	
5 V DC internal current		OO ma A /TV/D all mainta ONI)	00 m A (TVP all mainte ON)
consumption		90 mA (TYP. all points ON)	80 mA (TYP. all points ON)
Weight		0.17 kg	0.15 kg

DC input module

DC IIIput IIIouule					
Item	LX40C6	LX41C4	LX42C4		
Number of input points 16 points		32 points	64 points		
Rated input voltage	24 V DC (I	ripple rate: ≤ 5%) (allowable voltage range: 20.42	28.8 V DC)		
Rated input current	6.0 mA TYP. (at 24 V DC)	4.0 mA TYP.	(at 24 V DC)		
ON voltage/ON current	≥ 15 V DC /≥ 4 mA	≥ 19 V D	C/≥ 3 mA		
OFF voltage/OFF current	≤ 8 V DC /≤ 2 mA	≤ 9 V DC	/≤ 1.7 mA		
Input resistance	3.8 kΩ	5.7 kΩ			
Hesponse time		1 ms, 5 ms, 10 ms, 20 ms, 70 ms or less Initial setting is 10 ms.	·		
Common terminal arrangement 16 points/common		32 points/common			
Module size allocation	·	1			
Number of occupied I/O points	16 points (I/O allocation: input 16 points)	32 points (I/O assignment: input 32 points)	64 points (I/O allocation: input 64 points)		
External interface	18-point terminal block	40-pin connector	40-pin connector x 2		
5 V DC internal current 90 mA (TYP. all points ON)		100 mA (TYP. all points ON)	120 mA (TYP. all points ON)		
Weight	0.15 kg	0.11 kg	0.12 kg		

# ■ Output module specifications

Contact outp	out module				
	Item	LY10R2	LY18R2A		
Number of output points		16 points	8 points		
Rated switching voltage, current		24 V DC 2 A (resistive load)/point, 8 A/common 240 V AC 2 A (COS	24 V DC 2 A (resistive load)/point, 8 A/module 240 V AC 2 A (COS		
Minimum switchin	ng load	5 V D	C 1 mA		
Maximum switching load		264 V AC	125 V DC		
Response time	OFF to ON	≤ 10	) ms		
nesponse ume	ON to OFF	≤ 1%	2 ms		
	Mechanical	≥ 20 mill	ion times		
		Usage environment	Switching life		
		Rated switching voltage/current, rate	d load 100 thousand times		
		200 V AC 1.5 A, 240 V AC 1 A (COSφ	= 0.7) 100 thousand times		
Life	Electrical	200 V AC 0.4 A, 240 V AC 0.3 A (COS	$\phi = 0.7$ ) 300 thousand times		
	Electrical	200 V AC 1 A, 240 V AC 0.5 A (COSφ	= 0.35) 100 thousand times		
		200 V AC 0.3 A, 240 V AC 0.15 A (CO	$S\phi = 0.35$ ) 300 thousand times		
		24 V DC 1 A, 100 V DC 0.1 A (L/R =	7 ms) 100 thousand times		
		24 V DC 0.3 A, 100 V DC 0.03 A (L/R = 7 ms) 300 thousand times			
Maximum switchin	ng frequency	3600 times/hour			
Surge suppressor	r	-	_		
Fuse		-	— (a fuse is recommended to be installed for each external wiring point)		
Common termina	l arrangement	16 points/common	No common (all points independent)		
Module size alloc	ation		1		
Number of occupied I/O points		16 points (I/O assignment: 16 output points)			
External interface		18-point te	minal block		
5 V DC internal cu	urrent consumption	460 mA (TYP. all points ON)	260 mA(TYP.all points ON)		
Weight		0.21 kg	0.18 kg		

# ■ Output module specifications Triac output

mao oatpat				
	Item	LY20S6	LY28S1A	
Number of output points		16 points	8 points	
Rated load voltage,	frequency	100240 V AC (+10%/-	-15%), 50/60 Hz(±3 Hz)	
Maximum load curre	ent	0.6 A/point, 4.8 A/common	1 A/point, 8 A/module	
Load voltage distorti	on ratio	≤ 5	5%	
Maximum load volta	ge	264 \	V AC	
Minimum load voltag	ge/current	24 V AC/100 mA, 100 V A	C/25 mA, 240 V AC/25 mA	
Maximum inrush cur	rent	≤ 20 A	/cycle	
Leakage current at 0	OFF	≤ 3 mA (at 240 V, 60 Hz), s	≤ 3 mA (at 240 V, 60 Hz), ≤ 1.5 mA (at 120 V, 60 Hz)	
Maximum voltage drop at ON		≤ 1.5 V (at load current of 0.6 A)		
Dannanas tima	OFF to ON	Total of 1 ms and	Total of 1 ms and 0.5 cycles or less	
Response time	ON to OFF	Total of 1 ms and 0.5 cycles or less (rated load, resistive load)		
Surge suppressor		CR absorber		
Fuse		None (Attaching a fuse to each e	external wiring is recommended.)	
Common terminal ar	rangement	16 points/common	No common (all points independent)	
Module size allocation		1		
Number of occupied I/O points		16 points (I/O assignment: output 16 points)		
External interface		18-point ten	18-point terminal block	
5 V DC internal current consumption		300 mA (TYP. all points ON)	200 mA (TYP. all points ON)	
Weight		0.22 kg	0.19 kg	

Transistor output (Sink type)

iransistor outpu	t (Sink type)					
	Item	LY40NT5P	LY41NT1P	LY42NT1P		
Number of output points		16 points	32 points	64 points		
Rated load voltage			10.228.8 V DC			
Maximum load current		0.5 A/point, 5 A/common	0.1 A/point,	2 A/common		
Maximum inrush currer	nt	Curr	ent is limited by the overload protection fun	ction.		
Leakage current at OFI	F		≤ 0.1 mA			
Maximum voltage drop	at ON	0.2 V DC(TYP.) 0.5 A, 0.3 V DC(MAX.) 0.5 A	,	TYP.) 0.1 A, MAX.) 0.1 A		
D	OFF to ON		≤ 0.5 ms			
Response time	ON to OFF		≤ 1 ms (rated load, resistance load)			
Surge suppressor	*		Zener diode			
Fuse		<del>-</del>				
Futomol novice combi	Voltage	12/24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 10.228.8 V DC)				
External power supply	Current	9 mA (at 24 V DC)/common	13 mA (at 24 V DC)/common	9 mA (at 24 V DC)/common		
Common terminal arrar	ngement	16 points/common	32 points	s/common		
Module size allocation			1			
Number of occupied I/C	) points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points)		
Protection function	Overload protection	Limited current when detecting overcurrent (overload protection): 1.53.5 A/point. Activated in increments of 1 point.	Limited current when detecting overcurrent (overload protection): 1  Activated in increments of 1 point.			
	Overheat protection		Activated in increments of 1 point			
External interface		18-point terminal block	40-pin connector	40-pin connector ×2		
5 V DC internal current	consumption	100 mA (TYP. all points ON)	140 mA (TYP. all points ON)	190 mA (TYP. all points ON)		
Weight		0.15 kg	0.11 kg	0.12 kg		

Transistor output (Source type)

Transistor outpo	ut (Source type)					
	Item	LY40PT5P	LY41PT1P	LY42PT1P		
Number of output poir	nts	16 points	32 points	64 points		
Rated load voltage			10.228.8 V DC			
Maximum load curren	t	0.5 A/point, 5 A/common	0.1 A/point,	2 A/common		
Maximum inrush curre	ent	Curre	ent is limited by the overload protection fund	ction.		
Leakage current at Of	F .		≤ 0.1 mA			
Maximum voltage dro	p at ON	0.2 V DC(TYP.)0.5 A, 0.3 V DC(MAX.)0.5 A	0.1 V DC ( <sup>1</sup> 0.2 V DC ( <sup>1</sup>			
D	OFF to ON		≤ 0.5 ms	·		
Response time	ON to OFF		≤ 1 ms (rated load, resistance load)			
Surge suppressor			Zener diode			
Fuse		-				
External power supply	Voltage	12/24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 10.228.8 V DC)				
External power supply	Current	17 mA (at 24 V DC)/common	20 mA (at 24 V DC)/common			
Common terminal arra	angement	16 points/common	32 points	/common		
Module size allocation	1		1			
Number of occupied la	/O points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points)		
Protection function	Overload protection	Overcurrent detection: ≥ 1.5 A/point. Activated in increments of 1 point.	Limited current when detecting of 13 A Activated in incre	•		
	Overheat protection	Activated in increments of 1 point.	Activated in incre	ments of 2 points.		
External interface		18-point terminal block	40-pin connector	40-pin connector ×2		
5 V DC internal currer	nt consumption	100 mA (TYP. all points ON)	140 mA (TYP. all points ON)	190 mA (TYP. all points ON)		
Weight		0.15 kg	0.11 kg	0.12 kg		

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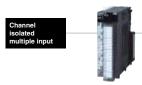
# MELSEG L series

# ■ I/O combined module specifications DC input/transistor output combined module

Item		LH42C4NT1P LH42C4PT1P			
■ Input specifications					
Number of input points		32 points			
Rated input voltage		24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 20.428.8 V DC)			
Rated input current		4.0 mA TYP. (at 24 V DC)			
Input ON voltage/ON cur	rrent	≥ 19 V DC/≥ 3 mA			
Input OFF voltage/OFF	current	≤ 9 V DC/≤ 1.7 mA			
Input resistance		5.7 kΩ			
I	OFF to ON	1 ms, 5 ms, 10 ms, 20	0 ms, 70 ms or less		
Input response time	ON to OFF	(Initial setting is 10 ms)			
Input common terminal a	arrangement	32 points/d	common		
■ Output specifications					
Output format		Transistor output combined module (Sink type)	Transistor output combined module (Source type)		
Number of output points		32 po	ints		
Rated load voltage		10.228.8 V DC			
Maximum load current		0.1 A/point, 2 A/common			
Maximum inrush current		Current is limited by the overload protection function.			
Leakage current at OFF		≤ 0.1 mA			
Maximum voltage drop a	+ ON	0.1 V DC (TYP.) 0.1 A,			
waxiiiuiii voitage urop a	II ON	0.2 V DC (MAX.) 0.1 A			
Output response time	OFF to ON	≤ 0.5 ms			
Output response time	ON to OFF	≤ 1 ms (rated load, resistance load)			
Surge suppressor		Zener diode			
Fuse					
Protection function	Overload protection	Limited current when detecting overcurrent (overload pro-	tection): 13 A/point, activated in increments of 1 point		
- Totection function	Overheat protection	Activated in increments of 1 point	Activated in increments of 2 points		
Output common terminal	l arrangement	32 points/o	common		
■ Common specification	s				
External power supply	Voltage	12/24 V DC (ripple rate: ≤ 5%) (allowal	ble voltage range: 10.228.8 V DC)		
External power supply	Current	9 mA (at 24 V DC)/common	20 mA (at 24 V DC)/common		
Module size allocation		1			
Number of occupied I/O	points	32 points (I/O assignment	: input/output 32 points)		
External interface		40-pin conr	nector ×2		
5 V DC internal current of	consumption	160 mA (TYP. all points ON)	150 mA (TYP. all points ON)		
Weight		0.12 kg			

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umber	Item	Code			Specification		
		Х			Input		
1	Module type	Υ			Output		
		Н			I/O combined		
	H	0-4-	Input spe	cifications		Output specificatio	ns
umber	Item	Code	AC input	DC input	Contact output	Triac output	Transistor output
	Valtage	1	100120 V AC	_	24 V DC/240 V AC	_	_
2	Voltage specification	2	100240 V AC	_	_	100240 V AC	_
	opeomodien -	4	_	24 V DC	_		1224 V DC
umber	Item	Code			Specification		
		0			16 points		
(3)	I/O points	1			32 points		
•	, o pointo	2			64 points		
		8			8 points		
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4	I/O type	NT			or output module (S	•••	
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umber	Item	Code			Contact output	Triac output	Transistor output
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umber	Item	1				1 A	0.1 A
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umber ⑤		1 2 4			 2 A		
	Current	1 2			 2 A		-
(5)	Current specification	1 2 4 5 6		— — 4 mA —	2 A — — — — — — — — — — — — — — — — — —	_ _ _	— — 0.5 A
⑤	Current	1 2 4 5		 4 mA  6 mA	 2 A	— — — 0.6 A	— — 0.5 A

# Multiple Input (Voltage/Current/Temperature) Module



#### L60MD4-G

Number of inputs: 4 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC Input micro voltage: -100 to 100 mV Input thermocouple: K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re Input RTD: Pt1000, Pt100, JPt100, Pt50

Hesolution

Voltage/Current/micro voltage: 1/20000

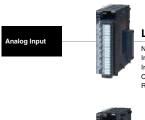
Thermocouple: B, R, S, N, PL II , W5Re/W26Re: 0.3°C,

K, E, J, T, U, L: 0.1°C

K, E, J, T, U, L: 0.1℃ RTD: Pt100, JPt100: 0.03℃/0.1℃, Pt1000, Pt50: 0.1℃

Conversion speed: 50 ms/channel

# **Analog Input Modules**



#### L60AD4

Number of inputs: 4 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC Conversion speed: 20 µs/channel Resolution: 1/20000



# L60ADVL8

Number of inputs: 8 channels Input voltage: -10 to 10 V DC Conversion speed: 1 ms/channel



# L60ADIL8

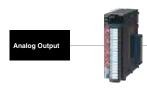
Number of inputs: 8 channels Input current: 0 to 20 mA DC Conversion speed: 1 ms/channel



#### L60AD4-2GH

Number of inputs: 4 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC Conversion speed: 40 µs/2 channels Resolution: 1/32000

# **Analog Output Module**



#### L60DA4

Number of outputs: 4 channels Output voltage: -10 to 10 V DC Output current: 0 to 20 mA DC Conversion speed: 20 µs/channel Resolution: 1/20000

# Analog I/O Module



#### L60AD2DA2

Analog input specifications Number of inputs: 2 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC Conversion speed: 80 μs/channel Resolution: 1/12000 Analog output specifications Number of outputs: 2 channels Output voltage: -10 to 10 V DC Output current: 0 to 20 mA DC Conversion speed: 80 µs/channel Resolution: 1/12000



# **Temperature Input Module**

RTD input



#### L60RD8

Number of inputs: 8 channels Input RTD: Pt1000, Pt100 (JIS C 1604–2013), JPt100 (JIS C 1604–1981), Pt50 (JIS C 1604–1981), Ni500 (DIN 43760 1987), Ni120 (DIN 43760 1987), Ni100 (DIN 43760 1987), Cu100 (GOST 6651-2009,  $\alpha$ =0.00428), Cu50 (GOST 6651-2009,  $\alpha$ =0.00428) Conversion speed: 40 ms/ch Resolution: 0.1°C

#### ■ Multiple/analog/temperature input features

Function		Multiple input (voltage/current/ temperature) module	urrent/ ture) Analog input module tle				Analog I/O module	Temperature input module	
			L60MD4-G	L60AD4	L60ADVL8	L60ADIL8	L60AD4-2GH	L60AD2DA2	L60RD8
Channel isolation			•		_		●*1	_	
	Sampling pr		•	•	•	•	•	•	•
		Time average	•	•	•	•	•	•	•
AD conversion method	Averaging processing	Count average	•	•	•	•	•	•	•
		Moving average	•	•	•	•	•	•	•
Time lag filter function			_	_	_	_	•	_	_
Digital filtering function			_	_	_	_	•	_	_
Conversion speed switch	function		_	•	_	1	_	_	_
Input range extended mo	de function		•	●*2	•	•	•	•	_
Maximum value/minimum	n value hold f	unction	•	•	•	•	•	•	•
Disconnection detection t	unction		•	_	_	_	_	_	•
Input signal error detection	n function		•	•	•	•	•	•	_
Input signal error detection	n extension	function	_	●*2	•	•	_	_	_
Warning output function	Process ala	rm	•	•	•	•	•	_	•
warning output function	Rate alarm		•	_	_	_	•	_	•
Scaling function			•	•	•	•	•	•	•
2-point sensor compensa	tion function		_	_	_	1	_	_	•
Shift function			—-3	●*2	—•3	_*3	•	—-3	•
Digital clipping function			— <u>,</u> 3	•	—*3	— <u>,</u> 3	•	— <u>*3</u>	_
Difference conversion fur	nction		—*3	●*2	—*3	_*3	•	—*3	_
Logging function			:4	●*2	*4	*4	•	•	*4
Flow amount integration to	function		_	●*2	_	1	_	_	_
Trigger conversion function	on		_	_			•	_	_
Variable arithmetic function	on		_	_	_	1	_	●*5	_
Variable conversion chara	acteristics fur	nction	_	_	_	1	_	●*5	_
Variable conversion charavariable arithmetic function		nction +	_	_	_	_	_	●*5	_

# ■ Analog output features

	Function	Analog output module	Analog I/O module
	FUNCTION	L60DA4	L60AD2DA2
Analog output HOLE	D/CLEAR function	•	•
Scaling function		•	•
Warning output function	Process alarm	•	•
Wave output functio	n	●*6	•
	Wave output step action function	●,e	•
Variable arithmetic f	unction	-	●*5
Variable conversion	characteristics function	_	●*5
Variable conversion characteristics function + variable arithmetic function		_	●'5

<sup>\*1:</sup> Every two channels are isolated. (CH1 and CH2 are isolated from CH3 and CH4).

<sup>\*2:</sup> Supported by models whose first five serial number digits are \*13041" or later.
\*3: Please use function blocks (FB) for the shift function, digital clipping function, and difference conversion function. The function blocks (FB) can be downloaded for free from the MELSOFT Library on the Mitsubishi Electric FA site.

<sup>\*4:</sup> For logging, please use the data logging function of the CPU module.

<sup>\*5:</sup> Supported by models whose first five serial number digits are "17042" or later.

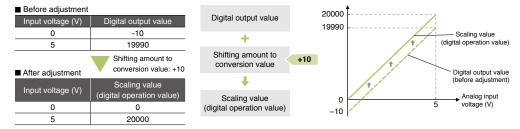
<sup>\*6:</sup> Supported by models whose first five serial number digits are "14041" or later.

#### Easily and finely adjust the system startup time with the shift function

#### Shift function

Using this function, the set shifting amount to conversion value can be added (shifted) to the digital output value. When the shifting amount to conversion value is changed, it is reflected to the scaling value (digital operation value) in real time. Therefore, fine adjustment can be easily performed when the system starts.

#### For L60AD4

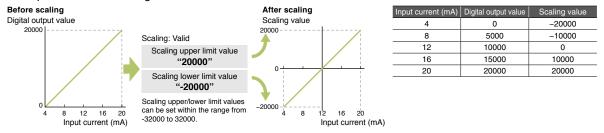


#### Reduce the time taken for programming

#### **Scaling function**

The scaling function converts values directly to easy-to-understand units without requiring any programming. Since a separate conversion program is not required, the number of overall programming steps can be reduced. Scaling settings example (L60AD4)

Normally an analog input of 4 to 20 mA is converted to a digital value from 0 to 20000. Using the scaling feature, the same input can result in a digital value of ±20000.



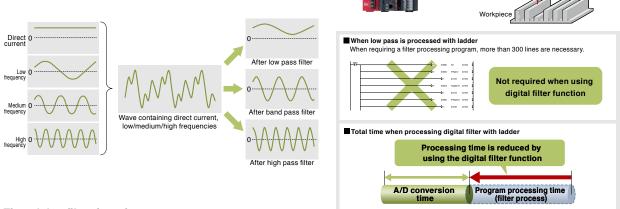
#### **Digital filtering function**

This function eliminates unnecessary frequency elements with simple parameter settings. Select from low pass filter, high pass filter or band pass filter.

Programming steps can be further reduced as extra ladder code is not required to achieve the filter processing.

The filtered A/D conversion program is available at the same time as conversion completion, reducing the overall conversion to filter process time.

Measurement of flatness Sensor



#### First-delay filter function

The first-delay filter function constant outputs a digital value which filters out (smooths) the excessive noise.

MELSEG L series

# Log data for up to 10,000 points

#### Logging function

Data is continuously collected at the set cycle and stored in the buffer memory.

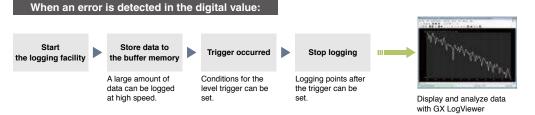
Data stored in the buffer memory can be used for debugging, and to periodically confirm data variations.

Item	Description					
item	L60AD4	L60AD4-2GH	L60AD2DA2			
Collectable points	10000 points/channel					
Collectable data	Digital or	utput value or scal	ing value			
Collectable data	(di	(digital operation value)				
	8032767 μs	4032767 μs	8032767 μs			
Logging cycle*1	132767 ms	132767 ms	132767 ms			
	13600 s	13600 s	13600 s			
Conversion speed	80 μs, or 1 ms	40 µs/2 channels	80 µs			
Level trigger condition	Abov	e, Below, Pass Th	rough			
Logging points after trigger	110000					

<sup>\*1:</sup> The actual logging cycle is "an integral multiple of the conversion cycle of each A/D conversion method"

Ex.) When using the sampling processing: Conversion cycle = conversion speed x number of channels in use.

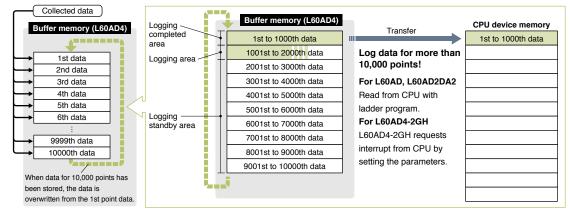
The logging data can be analyzed with the GX LogViewer.



Logging data can be transferred to the CPU device memory while still logging.

Logging and data transmission can be executed simultaneously so the next logging session can be started right away. Logging for 10,000 points and greater

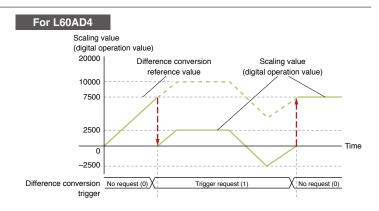
When logging of 1001 - 2000 points of data commences, the first 1000 points (1 - 1000) are stored into the CPU device memory. By storing every 1000 points of data in the CPU, overall logging of total data larger than 1000 points can be logged.

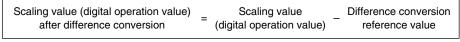


#### Easily measure part thicknesses!

#### Difference conversion function

When the difference conversion starts, the scaling value (digital operation value) at that time is determined as the difference conversion reference value. The value acquired by subtracting the difference conversion reference value from the scaling value (digital operation value) is stored as the scaling value (digital operation value) after difference conversion.





# Extend the detection method according to applications

#### Input signal error detection extension function

Using this function, the detection method of the input signal error detection function can be extended. Use this function to detect an input signal error only at the lower or upper limit, or to execute the disconnection detection.

# Input range extension function

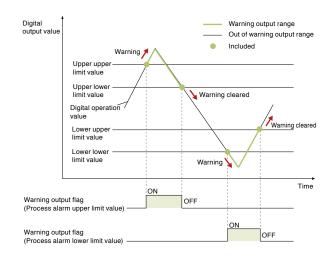
The input range can be extended. By combining this function with the input signal error detection function, simple disconnection detection can be executed.

# Connected devices monitoring alarm

#### Warning output function

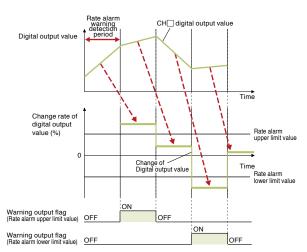
#### ■ Process alarm

Outputs an alarm when the digital output value enters a preset alarm range.



#### ■ Rate alarm

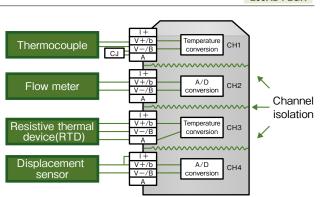
An alarm is generated if the digital output value's variation rate is larger than the rate alarm upper limit value, or if it is smaller than the rate alarm lower limit value.



# Noise isolation for smoother system operation

#### **Channel isolation**

Each channel is isolated preventing any noise interference between channels resulting in more stable measurements.



L60AD4-2GH

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MELSEG L series

# A/D variable conversion timing

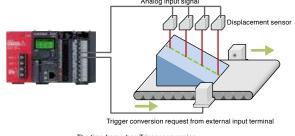
#### **Trigger conversion function**

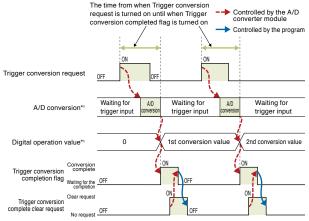
A/D conversion is processed at the rising edge of the trigger position timing.

This function enables easier use of the converter and enhances the overall program performance.

There are two types of trigger conversion request:

"External trigger conversion request (external input terminal)" or "internal trigger conversion request (buffer memory)".





\*1: Carried out in order with combination of channel 1, channel 3 and channel 2, channel 4.

# Quickly calculate and record flow amount

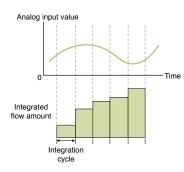
# Flow amount integration function

This function performs the A/D conversion of analog input value (voltage or current) from a flow meter and others, and integrates the scaling value (digital operation value) by every integration cycle. In this function, integral processing is performed regarding the scaling value (digital operation value) as the instantaneous flow amount.

# ■ Concept of integral processing

With this function, integral processing is performed using the following formula.

Integrated flow amount = 
$$\begin{pmatrix} Instantaneous \\ flow amount \end{pmatrix} \times \frac{\Delta T}{T} \times Unit scaling + Previous amount$$



Item		Description				
Integrated flow amount	Result of integral processing	esult of integral processing				
Instantaneous flow amount	Instantaneous flow amount	tantaneous flow amount value output in analog from flow meter				
ΔΤ	Integration cycle (ms)	gration cycle (ms)				
	Conversion value to conve	rt time unit of instantaneous flow amount to ms unit				
	Range of flow meter	Setting value to specify flow amount time unit	T (ms)			
T	/s	0	1000			
	/min	1	60000			
	/h	2	3600000			
	Unit scaling for integrated flow amount					
	This is used when the value of instantaneous flow amount $\times \Delta T/T$ is 0 to 1.					
	Se	Setting value to specify unit scaling				
		0	1			
Unit scaling		1	10			
		2	100			
		3				
		4	10000			
Previous amount	Stored integrated flow amo	unt value before integral processing				

#### Realize fast and smooth continuous analog output

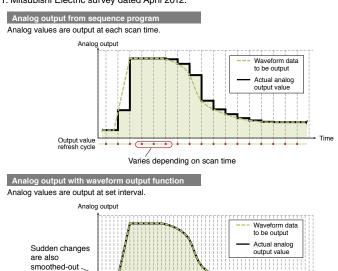
#### Wave output function

The industry's first\*1 waveform output function is included.

This function enables control wave data that is faster than the program control to be directly registered in the D/A converter module and output the data at a set conversion cycle.

Therefore, the analog output value is not affected by the scan time of the CPU module resulting in faster and smoother analog control.

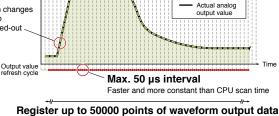
\*1: Mitsubishi Electric survey dated April 2012.

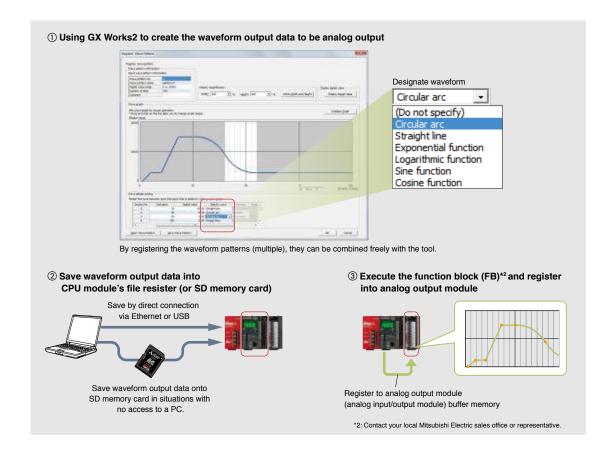


The actual waveform and the output waveform deviate.



The output waveform is closer to the actual waveform (less deviation).





SPC

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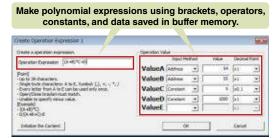


#### More flexible calculation and conversion reduce programming time

L60AD2DA2

#### Conversion by polynomial expressions

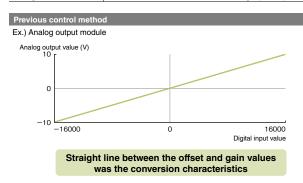
The variable arithmetic function enables the analog I/O module to perform polynomial calculations, eliminating the need of such calculations programmed by ladder. With the calculations performed on the analog I/O module side, advanced calculations are possible without being restricted by the scan time.

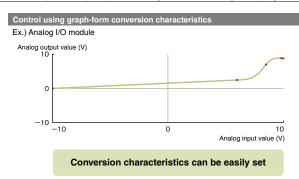


#### Graph-form conversion characteristics

The variable conversion characteristics function enables conversion characteristics for analog input, analog output, and analog I/O to be easily set on graphs. This means that conversion characteristics do not need to be programmed by ladder, which leads to reduced programming time.



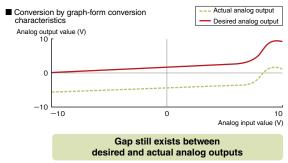


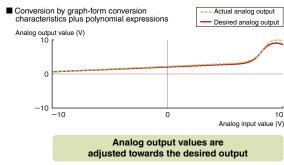


#### Conversion by graph-form conversion characteristics plus polynomial expressions

The two functions described above can also be combined; the digital values are first converted according to graph-form conversion characteristics and then by polynomial expressions. These two levels of conversion realize full adjustment of analog values at the time of output rather than adjusting them post-conversion.

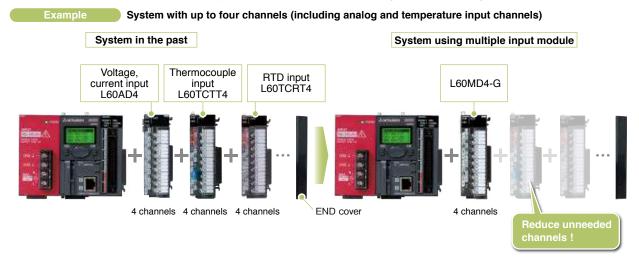
Ex.) Obtaining intended analog output using the conversion by graph-form conversion characteristics plus polynomial expressions





#### One module covering voltage, current, micro-voltage, thermocouples and RTD

For each channel, it is possible to select from voltage, current, micro-voltage, thermocouples or RTD. As a result, dedicated modules required for each type of sensor can now be integrated into a single module.



The multiple input module also supports the Pt50 and JPt100 sensors, which are compatible with the former JIS standards. Modules can be replaced without altering the already existing sensor equipment.

Thermocouple	K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re
RTD	Pt1000, Pt100, JPt100, Pt50

#### 8 input channels with wider input ranges

L60RD8

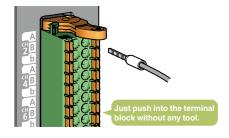
Single L60RD8 can measure temperatures of up to 8 channels. With the number of supported channels doubled compared to before (L60MD4-G), space and cost savings can be realized. The input range is expanded to meet the DIN standards, GOST standards, and Pt1000 range in addition to Pt100, JPt100, and Pt50, bringing new application possibilities.

RTD Pt1000, Pt100, JPt100, Pt50, Ni (DIN standards), Cu (GOST standards)

# Reduced wiring time with no screw tightening

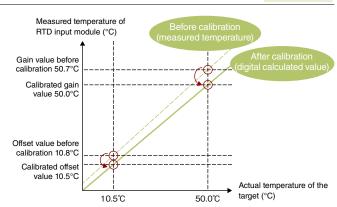
L60RD8

The module is equipped with a spring clamp terminal block, which does not require screw tightening. This push-in type terminal block does not require any dedicated wiring tool and significantly reduces the installation time.



#### Easier calibration L60RD8

Measured temperatures can be easily calibrated towards the actual temperature using the sensor calibration function (shift function, 2-point sensor compensation function).



The measured temperature of 10.8 to 50.7 ( $^{\circ}$ C) is calibrated to be 10.5 to 50.0 ( $^{\circ}$ C) by digital calculation. A temperature closer to the one input to RTD is obtained.

# MELSEG L series

#### ■ Multiple input (voltage/current/temperature) module specifications

	Item			L60MD4-G				
lumber of ar	nalog input channels			4 channels		·		
	Voltage	-1010 V DC (Input resistance value 1 MΩ)						
	Current	020 mA DC (Input resistance value 250 Ω)						
	micro voltage		-100100 mV DC					
Analog input		Ava	ilable type		K, J, T, E, N, R, S, B, U, L, PL II , W5Re/W26Re			
	Thermocouple	Cold junction compensation resistor  Use the included cold junction compensation						
		· · · · · · · · · · · · · · · · · · ·	Available type			Pt1000, Pt100, JPt100, Pt50		
	Resistive thermal device	Measurement method			1 (1)	3-wire system		
I		Voltage, Current, micro voltage			-2048020479			
Digital output			) (-20120°C), JPt100 (-201	20°C) -200	0 20000: Value r		s v 100 tim	
Digital output			rmal device (other than the ab		) -200020000: Value rounded off to two decimal places × 100 tim -400032000: Value rounded off to one decimal place × 10 tim			
When using the scaling function		Thermoduple, Hedisave and	,	32768327		rodrided on to one decimal plat	00 × 10 tilli	
	Trien doing the odding fanotion		Analog input range		output value	Resolution		
			010 V		20000	500 μV		
						·		
		Voltage	05 V	-	20000	250 μV		
		Voltage	15 V			200 μV		
			-1010 V		0020000	500 μV		
			15 V (Extended mode)	-500	0022500	200 μV		
		0	020 mA	0.	20000	1000 nA		
O characteri	istics, resolution	Current	420 mA		00500	800 nA		
		l	420 mA (Extended mode)		0022500	800 nA		
		micro voltage  -100100 mV		-	0020000	5 μV		
		Thermocouple				5Re/W26Re: 0.3°C		
					K, E, J, T, U, L: 0.1°C Pt100 (-20120°C),			
		Resistive thermal device (RTD)			JPt100 (-201	,,		
					Pt100 (-20:::1			
				JPt100 (-200600°C), Pt1000, Pt50: 0.1°C				
					Maximum value of the measurement			
		Voltage/Curre	Ambient temperature	25 ± 5°C		ge× (± 0.3%)		
		micro voltage		Maximum value of the meas				
		micro voltage	Ambient temperature					
			Ambient temperature	25 + 5°€				
		Thermocoupl	e Ambient temperature		` /			
		1	Temperature measure		1 dii 30aiex (± 0.070)			
			-100°C or high		≤ ± 1.0°C			
Accuracy*1*2					IE.			
Accuracy*1*2		Cold junction	Temperature measure	d value.				
Accuracy*1*2		compensation	Temperature measure			≤ ± 2.0°C		
Accuracy*1*2			-150°C100°	°C				
Accuracy*1*2		compensation		C ed value:		≤ ± 2.0°C ≤ ± 3.0°C		
Accuracy <sup>11</sup> 2		compensation resistor*4	1 -150°C100° Temperature measure -200°C150° (Accuracy)*5 - (Con)	C d value:		≤ ± 3.0°C		
Accuracy*1*2		compensation resistor 4	Temperature measure -200°C150°  (Accuracy)'5 = (Conv	C ed value: C ecversion accu		≤ ± 3.0°C ature characteristics) ×		
Accuracy <sup>-1-2</sup>		compensation resistor*4	-150°C100° Temperature measure -200°C150° mal (Accuracy)'5 = (Conv.) (Ope	C ed value: C c version accurating ambig	uracy) + (Tempera	≤ ± 3.0°C ature characteristics) ×		
	peed	compensation resistor 4	-150°C100° Temperature measure -200°C150° mal (Accuracy)'5 = (Conv.) (Ope	C ed value: C c version accurating ambig	uracy) + (Tempera	≤ ± 3.0°C sture characteristics) × change)		
Conversion s	speed  It for temperature detection	compensation resistor 4	Temperature measure  -200°C150°  (Accuracy)*5 (Cope  + (Allowable differ	ed value: eC version accurating ambi- erence of re	uracy) + (Tempera	≤ ± 3.0°C sture characteristics) × change)		
Conversion s	nt for temperature detection	compensation resistor 4	Temperature measure -200°C150°  (Accuracy)'s = (Com (Ope + (Allowable diffe	ed value: eC version accurating ambi- erence of re	uracy) + (Tempera ent temperature o sistance tempera Pt1000: 0.2 mA	≤ ± 3.0°C sture characteristics) × change)		
Conversion s Output currer Absolute max	nt for temperature detection kimum input	compensation resistor*4  Resistive their device	-150°C100° Temperature measure -200°C150° (Accuracy)'5 = (Conv (Ope + (Allowable diffe	d value: d value: d version accurating ambi- erence of re 50 ms/ch Pt50: 1 mA, 15 V, Currel	uracy) + (Tempera ent temperature o sistance tempera Pt1000: 0.2 mA nt: 30 mA's er power supply:	≤ ± 3.0°C  atture characteristics) ×  thange)  ture detector used)		
Conversion s Dutput currer bsolute max solation meth	nt for temperature detection kimum input hod	compensation resistor*4  Resistive their device	Temperature measure -200°C150°  (Accuracy)'s = (Con- (Ope + (Allowable difference)  Pt100, JPt100, Voltage: ±	d value: C version accurating ambierence of re 50 ms/ch Pt50: 1 mA, 15 V, Currentle controlle	uracy) + (Tempera ent temperature o sistance tempera Pt1000: 0.2 mA nt: 30 mA's er power supply:	≤ ± 3.0°C  atture characteristics) ×  thange)  ture detector used)		
Conversion s Dutput currer Absolute max Solation meth Module size a	nt for temperature detection ximum input hod allocation	compensation resistor*4  Resistive their device	Temperature measure -200°C150°  (Accuracy)' <sup>5</sup> = (Conv (Ope + (Allowable diffette)  Pt100, JPt100, Voltage: ± 1 I/O terminals and programma Between input ch	ord value: ord value: ord value: ord variang ambierence of re 50 ms/ch Pt50: 1 mA, 15 V, Currentable controller	uracy) + (Tempera ent temperature of sistance tempera Pt1000: 0.2 mA nt: 30 mA's er power supply: insformer isolation	≤ ± 3.0°C  ature characteristics) × change) ture detector used)		
Conversion s Dutput currer Absolute max solation methe Module size a Number of oc	nt for temperature detection kimum input hod allocation ccupied I/O points	compensation resistor*4  Resistive their device	Temperature measure -200°C150°C mal  (Accuracy)*5 = (Conv (Ope + (Allowable difference) Pt100, JPt100, Voltage: ± n I/O terminals and programma Between input ch	od value:  Oversion accurating ambi- erence of re-  50 ms/ch Pt50: 1 mA, 15 V, Currel bible controllinannels: tran-	uracy) + (Tempera ent temperature of sistance tempera Pt1000: 0.2 mA nt: 30 mA's er power supply: nsformer isolation	≤ ± 3.0°C  ature characteristics) × change) ture detector used)		
Conversion s Dutput currer Absolute max solation meth Module size a Number of oc External inter	nt for temperature detection kimum input hod allocation ccupied I/O points	compensation resistor*4  Resistive their device	Temperature measure -200°C150°C mal  (Accuracy)*5 = (Conv (Ope + (Allowable difference) Pt100, JPt100, Voltage: ± n I/O terminals and programma Between input ch	ord value: ord value: ord value: ord variang ambierence of re 50 ms/ch Pt50: 1 mA, 15 V, Currentable controller	uracy) + (Tempera ent temperature of sistance tempera Pt1000: 0.2 mA nt: 30 mA's er power supply: nsformer isolation	≤ ± 3.0°C  ature characteristics) × change) ture detector used)		

- \*1: Except when influenced by noise.
  \*2: To acquire sufficient accuracy, a warm-up (conduction) for 15 minutes is required.
  \*3: The accuracy for when the measured temperature of the type W5Re/W26Re thermocouple is 2000°C or higher is ±0.5%.
- \*4: The following table shows the accuracy of the cold junction compensation for when the type "T" thermocouple or type "U" thermocouple is used.

Measured temperature	T Thermocouple	U Thermocouple
0°C or higher	± 1.0°C	
-100°C0°C	± 2.0°C	
-150°C100°C	± 3.0°C	
-200°C150°C	± 5.0°C	± 4.0°C

\*5: The following table shows RTD types and values for each item.

3							
		Celsius		Fahrenheit			
RTD type	Measured temperature range	Conversion accuracy (operating ambient temperature: 25±5°C)	Temperature characteristics (for a change of 1°C in the operating ambient temperature)	Measured temperature range	Conversion accuracy (operating ambient temperature: 25±5°C)	Temperature characteristics (for a change of 1°C in the operating ambient temperature)	
Pt100	-20120°C	1°C	0.1°C	0200°F	1°F	0.1°F	
P1100	-200850°C	2°C	0.2°C	-3001500°F	3°F	0.3°F	
JPt100	-20120°C	1°C	0.1°C	0200°F	1°F	0.1°F	
JPIIOU	-200600°C	2°C	0.2°C	-3001100°F	3°F	0.3°F	
Pt1000	-200850°C	2°C	0.2°C	-3001500°F	3°F	0.3°F	
Pt50	-200650°C	2°C	0.2°C	-3001200°F	3°F	0.2°F	

• Allowable difference of Pt100 (JIS C 1604-1997, IEC 751 1983)

	Class	Allowable difference
Α		± (0.15 + 0.002 ltl)°C
В		± (0.3 + 0.005 ltl)°C

• Allowable difference of Pt100, allowable difference of Pt50 (JIS C 1604-1981)

	Class	Allowable difference				
0.15	5	± (0.15 + 0.0015 ltl)°C				
0.2		± (0.15 + 0.002 ltl)°C				
0.5		± (0.3 + 0.005 ltl)°C				

The allowable difference of Pt1000 is not provided in the JIS standard, and therefore is not described here. Please contact your Mitsubishi Electric or local sales representative

<sup>\*6:</sup> A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current is 24 mA.

#### ■ Analog input module specifications

#### L60AD4

LUUADT										
	Item	L60AD4								
Number of analog input channels		4 channels								
Voltage		-1010 V DC (Input resistance value 1 M $\Omega$ )								
Analog input	Current	020 mA DC (Input resistance value 250 Ω)								
Digital		-2048020479								
output	When using the scaling function			-32768	.32767					
				Analog input range	Digital output value	Resolution				
				010 V		500 μV				
				05 V	020000	250 μV				
				15 V		200 μV				
			Voltage	-1010 V	-2000020000	500 μV				
I/O character	ristics, resolution			15 V (Extended mode)	-500022500	200 μV				
				Users range setting	-2000020000	307 μV*1				
			Current	020 mA	020000	1000 nA				
				420 mA		800 nA				
				420 mA (Extended mode)	-500022500	800 nA				
				Users range setting	-2000020000	1230 nA*1				
A = = : : : = = : : * ?	Ambient temperature 25 ± 5°C	≤ ± 0.1% (± 20 digit)								
Accuracy*2	Ambient temperature 055°C	≤ ± 0.2% (± 40 digit)								
Conversion s	speed*3*4*5	High speed: 20 μs/channel Medium speed: 80 μs/channel Low speed: 1 ms/channel								
Absolute maximum input		Voltage: ± 15 V, Current: 30 mA*6								
Isolation method		Between I/O terminals and programmable controller power supply: photocoupler isolation								
		Between input channels: no isolation								
Module size allocation		1								
Number of occupied I/O points		16 points (I/O assignment: 16 points for intelligent)								
External interface		18-point terminal block								
5 V DC internal current consumption		0.52 A								
Weight				0.19	kg					

#### L60ADVL8

L60ADVL8							
	Item	L60ADVL8					
Number of a	nalog input channels	8 channels					
Analog input	Voltage		-1010 V DC (Input resistance value 1 MΩ)				
Digital		-1638416383					
output	When using the scaling function	-3276832767					
				Analog input range	Digital output value	Resolution	
				010 V	016000	625 μV	
			İ	05 V	08000	625 μV	
I/O character	ristics, resolution Voltag	1/4		15 V		500 μV	
		ollage	–1010 V	-1600016000	625 μV		
				15 V(Extended mode)	-20009000	500 μV	
				Users range setting	-80008000	625 μV 625 μV 500 μV 625 μV 500 μV 414 μV <sup>-1</sup>	
Accuracy*2	Ambient temperature 25 ± 5°C		-1010 V DC (Input resistance -1638416383 -3276832767  Analog input range    010 V     05 V     15 V     -1010 V   -1   15 V(Extended mode)   -   Users range setting   -   ≤ ± 0.2%     ≤ ± 1%     1 ms/ch     Voltage ± 15 V     Between I/O terminals and programmable controller possible points in the points of the	)			
Accuracy -	Ambient temperature 055°C	≤ ± 1%			$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		
Conversion speed*3*4*5		1 ms/ch					
Absolute max	ximum input	Voltage ± 15 V					
Isolation method							
		Between input channels: no isolation					
Module size allocation		1					
Number of occupied I/O points							
5 V DC internal current consumption		0.20 A					
Weight		0.19 kg					

#### L60ADIL8

L60ADIL8								
	Item	L60ADIL8						
Number of analog input channels		8 channels						
Analog input	Current	020 mA DC (Input resistance value 250 Ω)						
Digital		-81928192						
output	When using the scaling function	-3276832767						
				Analog input range	Digital output value	Resolution		
	ristics, resolution		Current	020 mA	08000	2500 nA		
I/O character				420 mA		2000 nA		
				420 mA(Extended mode)	-20009000	2000 nA		
				Users range setting	-80008000	1660 nA*1		
A a a	Ambient temperature 25 ± 5°C	≤±0.2%						
Accuracy*2	Ambient temperature 055°C			≤ ± 1%				
Conversion speed*3*4*5		1 ms/ch						
Absolute maximum input		Current 30 mA <sup>-6</sup>						
Isolation met	hod	Between I/O terminals and programmable controller power supply: photocoupler isolation						
isolation method		Between input channels: no isolation						
Module size allocation		1						
Number of occupied I/O points		16 points (I/O assignment: 16 points for intelligent)						
External interface		18-point terminal block						
5 V DC internal current consumption		0.21 A						
Weight		0.19 kg						
	1 11 1 11 11							

<sup>\*\*1:</sup> Maximum resolution in the user range setting.

\*\*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.

\*\*3: The default value is 80 µs/channel.

\*\*4: The logging function can be used only in the middle speed (80 µs/channel) or low speed (1 ms/channel).

\*\*5: The flow amount integration function can be used only in the low speed (1 ms/channel).

\*\*6: A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current is 24 mA.

#### ■ Dual channel isolation analog input module specifications

	Item			L60AD4-20	GH			
Number of anal	log input channels		4 channels					
Analog Voltage			-1010 V DC (Input resistance value 1 MΩ)					
input	Current		$020$ mA DC (Input resistance value 250 $\Omega$ )					
Digital output				-3200032	000			
Digital output	When using the so	caling function	-3276832767					
				Analog input range	Digital output value	Resolution		
				010 V		312.5 μV		
				05 V	032000	156 μV		
			Voltag	15 V		125 μV		
			Voltag	-1010 V	-3200032000	312.5 μV		
O characterist	tics, resolution			15 V (Extended mode)	-800032000	125 µV		
				Users range setting (Bipolar: voltage)	-3200032000	200 μV* <sub>1</sub>		
				020 mA	032000	625 nA		
			Currer	420 mA		500 nA		
			Garron	420 mA (Extended mode)	-800032000	500 nA		
				Users range setting (Unipolar: Current)	032000	400 nA <sup>*1</sup>		
Accuracy*2 F	Reference accura	,	≤ ± 0.05% (± 16 digit)					
-toouracy	Temperature coefficie	ent*4	≤ ± 40.1 ppm/°C					
Conversion spe	eed		40 μs/2 channel					
Absolute maxin	num input		Voltage: ± 15 V, Current: 30 mA*5					
solation metho	od		Between I/O terminals and programmable controller power supply: photocoupler isolation Between analog input channels: dual channel transformer isolation					
Module size alle	ocation		1					
Number of occu	upied I/O points		16 points (I/O assignment: 16 points for intelligent)					
External interfa	ce		18-point terminal block					
V DC internal	current consumpt	tion		0.76 A				
Weight			0.20 kg					
	Input points		1 point					
	Rated input	voltage		24 V DC (+ 20%/-15%, ri	ipple ratio: ≤ 5%)			
	Rated input	current		6.0 mA TYP. (at 2	24 V DC)			
External trigger	ON voltage/	ON current		≥ 13 V, ≥ 3	mA			
nput	OFF voltage	e/OFF current		≤ 8 V, ≤ 1.6	mA			
	Input resista	ance		3.9 kΩ				
	Response	OFF to ON		40 μs				
	time	ON to OFF	40 µs				-	

Example: Accuracy when the temperature changes from 25°C to 30°C

0.05% + 0.00401%/°C (temperature coefficient)  $\times\,5^{\circ}\text{C}$  (temperature change) = 0.070%

#### ■ Analog output module specifications

	Item	L60DA4						
Number of an	nalog output channels	4 channels						
Digital input		-2048020479						
Digital Input	When using the scaling function	-3276832767						
Analog	Voltage	-1010 V DC (External load resistance value 1 k $\Omega$ 1 M $\Omega$ )						
output	Current		020 mA DC (External load resi	stance value 0 $\Omega60$	00 Ω)			
			Analog output range	Digital value	Resolution	ı		
			05 V	020000	250 μV			
		Voltage	15 V	020000	200 μV			
I/O characteri	istics, resolution	voltage	-1010 V	-2000020000	500 μV			
i/O character	istics, resolution		Users range setting	-2000020000	333 μV* <sup>6</sup>			
			020 mA	020000	1000 nA			
		Current	420 mA	020000	800 nA			
			Users range setting	-2000020000	700 nA*6	i		
A 7	Ambient temperature 25 ± 5°C	≤ ± 0.1%						
Accuracy*7	Ambient temperature 055°C	≤±0.3%						
Conversion	Normal output mode	20 μs/channel						
speed	Wave output mode		50 μs/channel 80	μs/channel				
Output short	protection	Protected						
		Between I/O terminals and programmable controller power supply: photocoupler isolation						
Isolation meth	hod	Between output channels: no isolation						
		Between external power supply and analog output: transformer isolation						
Module size a	allocation	1						
Number of oc	ccupied I/O points	16 points (I/O assignment: 16 points for intelligent)						
External inter	face		18-point termin	al block				
			24 V DC (+ 20°	%/-15%)				
External pow	or ounnly	Ripple, spike 500 mV <sub>P-P</sub> or lower						
External pow	er suppry		Inrush current: 4.3 A, 10	000 µs or shorter				
		Current consumption: 0.18 A						
5 V DC intern	nal current consumption		0.16 A					
Weight			0.20 kg	1				
*6: Maximum resolution in the user range setting								

<sup>\*6:</sup> Maximum resolution in the user range setting.

<sup>\*1:</sup> Maximum resolution in the user range setting.
\*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.

<sup>\*3:</sup> Accuracy under the ambient temperature when the offset/gain setting is performed.

<sup>\*4:</sup> Accuracy when the temperature changes 1°C.

<sup>\*5:</sup> A momentary input current value which does not cause damage to internal resistors of the module. The maximum input current value for constant application is 24 mA.

<sup>\*7:</sup> Accuracy for the maximum value of analog output value. Except when influenced by noise. Warm up (power on) the module for 30 minutes to satisfy the accuracy shown in the table.

#### ■ Analog input/output module specifications

	Item		L60AD2	DAZ			
number of a	ersion part						
	analog input channels	2 channels					
Analog	Voltage	-1010 V DC (Input resistance value 1 MΩ)					
nput	Current		020 mA DC (Input res				
Digital		-1638416383					
output	When using the scaling function	-3276832767					
			Analog input range	Digital output value	Resolution		
			010 V	016000	625 μV		
			05 V	012000	416 μV		
		Voltage	15 V	012000	333 μV		
		voltage	-1010 V	-1600016000	625 µV		
O characte	eristics, resolution		15 V (Extended mode)	-300013500	333 µV		
			Users range setting	-1200012000	321 µV*1		
			020 mA		1666 nA		
			420 mA	012000	1333 nA		
		Current	420 mA (Extended mode)	-300013500	1333 nA		
			Users range setting	-1200012000	1287 nA*1		
			Cools range county		-		
			Analog input range	Ambient tem	perature 055°C		
			010 V				
			-1010 V	≤ ± 0.2%	≤ ± 0.3%		
		Voltage	05 V		<u> </u>		
ccuracy*2		- Chage	15 V	┥			
			15 V (Extended mode)	_			
		<u> </u>	020 mA	≤ ± 0.2%	≤ ± 0.3%		
		Current	420 mA	-			
		Current	420 mA (Extended mode)	$\dashv$			
			420 IIIA (Extended filode)				
	Logging function		80 μs/ch	annel			
	Wave output function		σο μο/οπ				
nversion	Variable conversion characteristics function		100 μs/ch	nannel			
eed	Variable arithmetic function						
	Variable conversion characteristics function +		160 µs/ch	nannel			
variable arithmetic function			•				
solute ma	aximum input		Voltage: ± 15 V, C	urrent: 30 mA*3			
	ersion part		- 5. mag 5 5 V, O				
	analog output channels		2 chani	nels			
TIDEL OF S	maiog output chamiliois						
ital input	Mile and order than 10 of 10	-1638416383					
	When using the scaling function		-32768				
nalog	Voltage		-1010 V DC (External load re	esistance value 1k to 1	VI Ω)		
ıtput	Current		020 mA DC (External load re	esistance value 0 to 60	0 Ω)		
			Analog output range	Digital value	Resolution		
			05 V		416 µV		
			15 V	012000	333 μV		
		Voltage	-1010 V	-1600016000	625 µV		
) characte	eristics, resolution		Users range setting	-1200012000	319 µV*1		
			020 mA		1666 nA		
		Current	420 mA	012000	1333 nA		
		Current		-12000 12000	696 nA*1		
		Culteria	Users range setting	-1200012000	696 nA*1		
		Garren	Users range setting	Ambient tem	perature		
	_	Cunum	Users range setting  Analog output range				
		Curion	Users range setting  Analog output range  05 V	Ambient tem	perature 055°C		
ocuracy*2		Voltage	Users range setting  Analog output range  05 V  15 V	Ambient tem 25 ± 5°C ≤ ± 0.2%	perature 055°C ≤ ± 0.4%		
ocuracy*2			Users range setting  Analog output range  05 V	Ambient tem	perature 055°C		
curacy*2		Voltage	Users range setting  Analog output range  05 V  15 V	Ambient tem 25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
curacy*2			Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA	Ambient tem 25 ± 5°C ≤ ± 0.2%	perature 055°C ≤ ± 0.4%		
ccuracy*2	Normal output	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V	Ambient tem 25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
ccuracy*2	Normal output	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA	Ambient tem 25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
	Wave output function	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion	Wave output function Variable conversion characteristics function	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion	Wave output function Variable conversion characteristics function Variable arithmetic function	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function +	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion	Wave output function Variable conversion characteristics function Variable arithmetic function	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
nversion eed	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function +	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annel  annels*4	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion eed utput shori	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/cł	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annel  annels*4	perature 055°C ≤ ± 0.4% ≤ ± 0.4%		
onversion eed utput shor	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4	perature 055°C ≤±0.4% ≤±0.4% ≤±0.4%		
onversion peed utput short Common	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection part	Voltage	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  ted  troller power supply: ph	perature 055°C ≤±0.4% ≤±0.4% ≤±0.4%		
onversion beed utput short Common	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection part	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/cf  320 µs/2 ch  Protec  D terminals and programmable con Between output char	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  troller power supply: prinels: no isolation	perature 055°C ≤±0.4% ≤±0.4% ≤±0.4%		
onversion peed output short Common	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection part	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  troller power supply: prinels: no isolation	perature 055°C ≤±0.4% ≤±0.4% ≤±0.4%		
onversion peed output short Common solation me	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection part thod allocation	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ct  320 µs/2 ch  Protec  D terminals and programmable con Between output chart tween external power supply and a	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  s ± 0.2%  annel  annel  annels*4  troller power supply: phanels: no isolation nalog output: transform	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%     ≤ ± 0.4%		
conversion peed butput short Common solation me	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function tt protection part  thod  allocation occupied I/O points	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/cf  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  s ± 0.2%  annel  annel  annels*4  ted  troller power supply: phanels: no isolation nalog output: transform  16 points for intelligent	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%     ≤ ± 0.4%		
conversion peed butput short Common solation me	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function tt protection part  thod  allocation occupied I/O points	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ct  320 µs/2 ch  Protec  D terminals and programmable con Between output chart tween external power supply and a	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  s ± 0.2%  annel  annel  annels*4  ted  troller power supply: phanels: no isolation nalog output: transform  16 points for intelligent	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
Conversion peed  Dutput short Common solation me	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function tt protection part  thod  allocation occupied I/O points	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/cf  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  s ± 0.2%  annel  annels*4  ted  troller power supply: phonels: no isolation nalog output: transform  16 points for intelligent inal block	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
conversion peed  Dutput short Common solation me Module size tumber of control intervenal intervenance in the control i	Wave output function Variable conversion characteristics function Variable arithmetic function Variable arithmetic function Variable arithmetic function t protection part  allocation cocupied I/O points erface	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a  11 16 points (I/O assignment:	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  since the second of the secon	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
onversion peed butput short Common solation me lodule size tumber of coxternal interest	Wave output function Variable conversion characteristics function Variable arithmetic function Variable arithmetic function Variable arithmetic function t protection part  allocation cocupied I/O points erface	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a  1 16 points (I/O assignment: 18-point term 24 V DC (+2 Ripple, spike 500	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  ted  troller power supply: phonels: no isolation nalog output: transform  16 points for intelligent inal block  0%/-15%)  mV-P or lower	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
onversion peed utput shor Common olation me odule size umber of c xternal inte	Wave output function Variable conversion characteristics function Variable arithmetic function Variable arithmetic function Variable arithmetic function t protection part  allocation cocupied I/O points erface	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a  1 16 points (I/O assignment: 18-point term 24 V DC (+ 2 Ripple, spike 500 Inrush current: 3.5 A,	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  ted  troller power supply: principles: no isolation nalog output: transform  16 points for intelligent i	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
onversion peed utput shor Common olation me odule size umber of c xternal inte	Wave output function Variable conversion characteristics function Variable arithmetic function Variable conversion characteristics function + variable arithmetic function t protection part  withod allocation occupied I/O points orface wer supply	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a  1 16 points (I/O assignment: 18-point term 24 V DC (+ 2 Ripple, spike 500 Inrush current: 3.5 A, Current consum	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  sannel  annels*4  troller power supply: pt nels: no isolation nalog output: transform  16 points for intelligent inal block 0%/-15%) mVpp or lower 1000 µs or shorter ption: 0.12 A	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		
Common  solation me  flodule size lumber of contact internal internal power.	Wave output function Variable conversion characteristics function Variable arithmetic function Variable arithmetic function Variable arithmetic function t protection part  allocation cocupied I/O points erface	Voltage Current	Users range setting  Analog output range  05 V  15 V  -1010 V  020 mA  420 mA  80 µs/ch  100 µs/ch  320 µs/2 ch  Protec  D terminals and programmable con Between output char tween external power supply and a  1 16 points (I/O assignment: 18-point term 24 V DC (+ 2 Ripple, spike 500 Inrush current: 3.5 A,	Ambient tem  25 ± 5°C  ≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  annel  annels*4  troller power supply: phanels: no isolation nalog output: transform  16 points for intelligent inal block  0%/-15%)  mV-p or lower  1000 µs or shorter ption: 0.12 A  A	055°C   ≤ ± 0.4%   ≤ ± 0.4%   ≤ ± 0.4%   ≤ motocoupler isolation		

<sup>\*1:</sup> Maximum resolution in the user range setting.

\*2: Accuracy for the maximum value of the digital /analog output value. Except when influenced by noise.

\*3: A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current 24 mA.

\*4: When the variable arithmetic function or the variable conversion characteristics function + variable arithmetic function is used, the operation speed for polynomial expressions is 320 µs. Since each operation result of two polynomial expressions is output on each D/A conversion channel, D/A conversion is executed at intervals of 320 µs regardless of the number of conversion enabled channels.

#### ■ Temperature input module specifications

	Item		L60	ORD8		
Number of	f analog input channels		8 ch	annels		
O t t	Temperature measured value	-328015620				
Output	Digital operation value		-32768	332767		
Applicable RTD		9 types Pt1000, Pt100 (JIS C 1604–2013), JP100 (JIS C 1604–1981), Pt50 (JIS C 1604–1981), Ni500 (DIN 43760 1987), Ni120 (DIN 43760 1987), Ni100 (DIN 43760 1987), Cu100 (GOST 6651–2009, α=0.00428)				
Measured	temperature range, accuracy*1	(Acc	curacy) = (Conversion accuracy)	) + (Allowable difference of RTD used)		
	1	1 mA	Pt100,	JPt100, Pt50, Ni120, Ni100, Cu100, Cu50		
remperatu	re detecting output current*2	100 μΑ		Pt1000, Ni500		
Resolution	1*3		0.	1°C		
Conversion	n speed	40 ms/ch				
Number of 2-point sensor compensation settings		10000 times maximum				
Isolation m	nethod	Between input terminals and programmable controller power supply: Photocoupler Between input channels: Non-isolation				
Module siz	ze allocation	1				
Number of	f occupied I/O points	16 points (I/O assignment: Intelligent 16 points)				
External in	nterface	24-point spring clamp terminal block				
Applicable	cable type*4		Solid wire, stranded wir	re, bar solderless terminal		
Applicable	uive eine	Core		0.51.5 mm <sup>2</sup> (AWG2416)		
Applicable	wire size	Terminal hole size		2.4 mm×1.5 mm		
		Al 0.5-10WH [Applical	ble wire size: 0.5 mm <sup>2</sup> ]			
Applicable	solderless terminal	Al 0.75-10GY [Applicat	ole wire size: 0.75 mm²]	PHOENIX CONTACT GmbH & Co. KG		
Applicable	Solueness terminal	A 1-10 [Applicable	wire size: 1.0 mm <sup>2</sup> ]	PROENIX CONTACT GIIIDH & CO. KG		
		A 1.5–10 [Applicable wire size: 1.5 mm <sup>2</sup> ]		<u> </u>		
Wire strip I	length	·	10	) mm		
5 V DC int	ernal current consumption		0.:	22 A		
Weight			0.1	15 kg		

<sup>\*1:</sup> The following table shows RTD types and values for each item.

		Celsius		Fahrenheit			
RTD type		Conversion	n accuracy	Maria	Conversion accuracy		
	Measured temperature range	Operating ambient temperature 25±5°C	Operating ambient temperature 055°C	Measured temperature range	Operating ambient temperature 25±5°C	Operating ambient temperature 055°C	
	-20120°C	±0.6°C	±2.0°C	-4248°F	±1.1°F	±3.6°F	
Pt100	-200850°C	Specified temperature ×±0.3% or ±0.8°C, whichever is greater	Specified temperature ×±0.8% or ±2.7°C, whichever is greater	-3281562°F	Specified temperature ×±0.3% or ±1.5°F, whichever is greater	Specified temperature ×±0.8% or ±4.9°F, whichever is greater	
	-20120°C	±0.6°C	±2.0°C	-4248°F	±1.1°F	±3.6°F	
JPt100	-200600°C	Specified temperature ×±0.3% or ±0.8°C, whichever is greater	Specified temperature ×±0.8% or ±2.7°C, whichever is greater	-3281112°F	Specified temperature ×±0.3% or ±1.5°F, whichever is greater	Specified temperature ×±0.8% or ±4.9°F, whichever is greater	
Pt1000	-200850°C	Specified temperature ×±0.3% or ±0.8°C, whichever is greater	Specified temperature ×±0.8% or ±2.7°C, whichever is greater	-3281562°F	Specified temperature ×±0.3% or ±1.5°F, whichever is greater	Specified temperature ×±0.8% or ±4.9°F, whichever is greater	
Pt50	-200650°C	Specified temperature ×±0.3% or ±0.8°C, whichever is greater	Specified temperature ×±0.8% or ±4.1°C, whichever is greater	-3281202°F	Specified temperature ×±0.3% or ±1.5°F, whichever is greater	Specified temperature ×±0.8% or ±7.4°F, whichever is greater	
Ni100	-60250°C	±0.6°C	Specified temperature ×±0.8% or ±1.4°C, whichever is greater	-76482°F	±1.1°F	Specified temperature ×±0.8% or ±2.6°F, whichever is greater	
Ni120	-60250°C	±0.6°C	Specified temperature ×±0.8% or ±1.4°C, whichever is greater	-76482°F	±1.1°F	Specified temperature ×±0.8% or ±2.6°F, whichever is greater	
Ni500	-60250°C	±0.6°C	Specified temperature ×±0.8% or ±1.4°C, whichever is greater	-76482°F	±1.1°F	Specified temperature ×±0.8% or ±2.6°F, whichever is greater	
Cu100	-180200°C	±0.8°C	±2.7°C	-292392°F	±1.5°F	±4.9°F	
Cu50	-180200°C	±0.8°C	±2.7°C	-292392°F	±1.5°F	±4.9°F	

#### • Allowable difference of Pt100 (JIS C 1604-2013)

Class	Allowable difference
A	±(0.15+0.002 t )°C
В	±(0.3+0.005iti)°C

• Allowable difference of JPt100 and Pt50 (JIS C 1604-1981)

Class	Allowable difference
0.15	±(0.15+0.0015iti)°C
0.2	±(0.15+0.002'tt')°C
0.5	±(0.3+0.005't')°C

#### • Allowable difference of Ni100, Ni120, and Ni500 (DIN 43760 1987)

Class	Allowable difference
-600°C	±(0.4+0.007'tt)°C
0250°C	±(0.3+0.0028iti)°C
0250°C	±(0.3+0.0028iti)°C

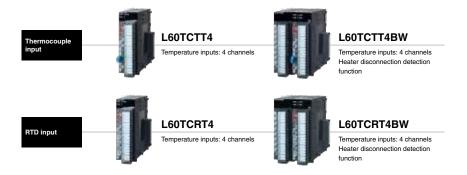
#### • Allowable difference of Cu100 and Cu50 (GOST 6651-2009)

Class	Allowable difference				
AA	±(0.1+0.0017iti)°C				
A	±(0.15+0.002iti)°C				
В	±(0.3+0.005 t )°C				
C	±(0.6±0.01!t!)°C				

The allowable difference of Pt1000 is not provided in the JIS standard, and therefore is not described here. 

- \*2: Current is output only on channels in which conversion is being performed.
- \*3: When the standard product (L60MD4-G) is replaced by this module, the resolution of Pt100 (-20 to 120°C) and JPt100 (-20 to 120°C) is different.
  \*4: When a stranded wire is used, attach a bar solderless terminal.

#### **Temperature Control Modules**



Function	L60TCTT4	L60TCTT4BW	L60TCRT4	L60TCRT4BW	
Function	Thermoco	ouple input	RTD input		
Standard control	•	•	•	•	
Heating-cooling control	•	•	•	•	
Self-tuning function	•	•	•	•	
Peak current suppression function	•	•	•	•	
Simultaneous temperature rise function	•	•	•	•	
Selectable sampling cycle	•	•	•	•	
Temperature input mode	•	•	•	•	
Temperature control mode	•	•	•	•	
Heater disconnection detection function	_	•	_	•	

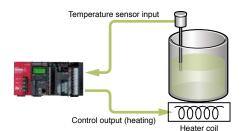
#### Highly stable temperature control

#### Standard control/heating and cooling control

Prevent overheating and overcooling in devices that require a high level of temperature stability, such as in an extrusion molding machine.

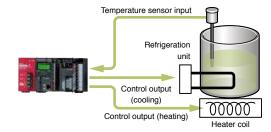
The following control methods can be selected according to the target device.

- Standard control (heating or cooling)
- Heating/cooling control (heating and cooling)
- Mix control (combination of standard control and heating-cooling control)
  - Example: Standard control (heating only)
    The temperature of the object is controlled by adjusting the heater output based on the PID calculations resulting from the temperature sensor input.



## ■ Example: Heating-cooling control (heating and cooling elements controlled simultaneously)

(heating and cooling elements controlled simultaneously)
Heating is performed when the control object's temperature is lower
than the target temperature, and cooling is performed when it is hotter
or the humidity needs to be reduced.



#### Reduce running costs by taking advantage of the energy-saving effect

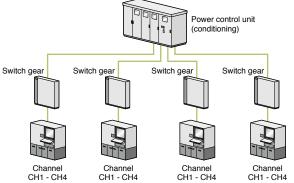
#### **Peak current control function**

The peak current control function reduces the peak current by automatically changing the upper-output limit value for each channel, while dividing the transistor output timing\*1. The energy conserved by reducing the peak current, such as a reduction in system power capacity and reduction in contracted power, can help to reduce running costs.

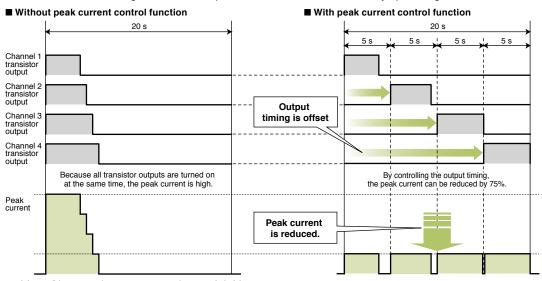
\*1: The timing can be split between two to four outputs.

The maximum power supply capacity requirement is lowered.

We can save money on our electricity contract!



When two or more loads are being controlled, the peak current can be minimized by spreading the total load out over time.



#### **Ensures uniform temperature control**

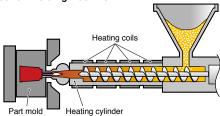
#### Simultaneous temperature rise function

Ensures uniform temperature control by synchronizing the temperature arrival times from multiple loops.

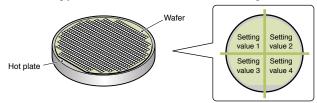
Perform a uniform temperature rise using two or more control loops without going over temperature or resulting in unexpected thermal expansion.

A "no idling" format increases energy efficiency and reduces running costs.

■ Example: Temperature control of injection molding machine

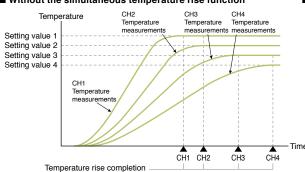


#### ■ Example: Wafer heating process for semiconductor manufacturing

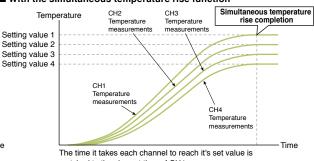


#### The running costs is reduced!

#### ■ Without the simultaneous temperature rise function



#### ■ With the simultaneous temperature rise function



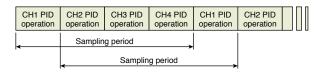
matched to the slowest time of CH4.

Using this function, it is possible to coordinate the control of two or more loops to reach their target values (SV) at the same time. Control the simultaneous rise in temperature of separate loops by setting a channel group (Max. 2 groups). This is an effective way to control applications where differing target temperature arrival times can result in undesirable temperature differentials.

#### Support a range of system requirements

#### Sampling cycle change function

Choose a sampling cycle of 250 ms/4 channels or 500 ms/4 channels.

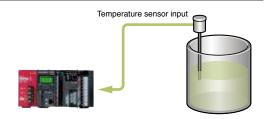


Sampling period: The time it takes to execute a PID operation for all channels (CHn) before beginning the PID operation of the present channel (CHn) again is called a sampling period.

#### Temperature input mode

This function allows the temperature control module to be used as a standard temperature input module.

Using the switch setting, it is possible to easily change the input mode.



#### ■ Specifications

Specif		em	L60TCTT4	L60TCTT4BW	L60TCRT4	L60TCRT4BW	
Control out		em	Transistor output				
	temperature input chann	ols.	4 channels				
	temperature sensors	613	Thorm		T	ormal davisa	
Applicable t	lemperature sensors	A	Thermocouple Resistive thermal device Full scale × (± 0.3%)				
	Indication accuracy	Ambient temperature: 25 ± 5°C					
	0.11: "	Ambient temperature: 055°C		Full Scale	× (± 0.7%)		
Accuracy*1	Cold junction temperature	Temperature process value (PV): -100°C or more	≤±	1.0°C			
	compensation accuracy:	Temperature process value (PV): -150100°C	≤ ± 2	2.0°C	-	_	
	(ambient temperature: 055°C)	Temperature process value (PV): -200150°C	≤±3	3.0°C			
Sampling cy	ycle				channels channels		
Control outp	put cycle			0.51	100.0 s		
Input imped	lance			1 1	MΩ		
Input filter				0100 s (0: Ir	nput filter OFF)		
Sensor corr	rection value setting			-50.00	.50.00%		
Operation a	at sensor input disconnec	etion		Upscale p	processing		
Temperatur	e control method			PID ON/OFF pulse of	or two-position control		
PID constants setting			Can be set b		-		
		Proportional band (P)	0.01000.0% (0: Two-position control)				
PID constar	nts range	Integral time (I)	03600 s (set 0 for P control and PD control.)				
		Derivative time (D)	03600 s (set 0 for P control and PI control.)				
Set value (S	SV) setting range	pentante une (2)	Within the temperature range set in the thermocouple/platinum resistance thermometer to be used				
	setting range		0.110.0%				
Dodd barra	octaing range	Output signal	ON/OFF pulse				
		Rated load voltage			0 V DC		
		Max. load current			0.4 A/common		
Transistor of	outout	Max. inrush current			10 ms		
Transistor C	σιραί				1 mA		
		Leakage current at OFF					
		Max. voltage drop at ON			2.5 V DC (MAX) at 0.1 A		
		Response time			ON→OFF: ≤ 2 ms		
Number of a	accesses to non-volatile	memory			D <sup>12</sup> times		
Isolation me	ethod		Between input ter	rminal and programmable o Between input channel	ontroller power supply: Tras: Transformer isolation	ansformer isolation	
Heater disc	onnection pecifications	Current sensor	_	• CTL-12-S36-10 (0.0100.0 A)*2 • CTL-12-S56-10 (0.0100.0 A)*2 • CTL-6-P-H (0.0020.00 A)*2	_	• CTL-12-S36-10 (0.0100.0 A)*2 • CTL-12-S56-10 (0.0100.0 A)*2 • CTL-6-P-H (0.0020.00 A)*2	
		Input accuracy	1	Full scale × (± 1.0%)		Full scale × (± 1.0%)	
		Number of alert delay	1	3255	1	3255	
Module size allocation		1	2	1	2		
Number of o	occupied I/O points			16 points (I/O assignme	ent: Intelligent 16 points)	•	
External into	erface		18-point terminal block	18-point terminal block × 2	18-point terminal block	18-point terminal block × 2	
	rnal current consumption	1	0.30 A	0.33 A	0.31 A	0.35 A	
Weight			0.18 kg	0.33 kg	0.18 kg	0.33 kg	
*1: Calculate	e the accuracy in the follo	owing method (only when it is not affective	cted by noise).				

<sup>1:</sup> Calculate the accuracy in the following method (only when it is not affected by noise).

Accuracy (°C) = full scale × indication accuracy + cold junction temperature compensation accuracy

Ex.) Accuracy at the input range of 38 (-200.0 to 400.0 °C), the operating ambient temperature of 35 °C, and the temperature process value (PV) of 300 °C (Full scale)  $\times$  (indication accuracy) + cold junction temperature compensation accuracy

=  $(400.0^{\circ}\text{C} - (-200.0^{\circ}\text{C})) \times (\pm 0.007) + (\pm 1.0^{\circ}\text{C})$ 

= ± 5.2°C

#### ■ Control mode

■ Control mode							
Control mode	Contents	Number of controllable loops					
Standard control	Performs the standard control of four channels.	Standard control 4 loops					
Heating-cooling control (normal mode)	Performs the heating-cooling control. CH3 and CH4 cannot be used.	Heating-cooling control 2 loops					
Heating-cooling control (expanded mode)	Performs the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Heating-cooling control 4 loops					
Mix control (normal mode)	Performs the standard control and the heating-cooling control. CH2 cannot be used	Standard control 2 loops Heating-cooling control 1 loop					
Mix control (expanded mode)		Standard control 2 loops Heating-cooling control 2 loops					

#### Control for each channel is as follows.

Channel	Standard control	Heating-cooling control		Mix control	
Channel	Standard Control	Normal mode	Expanded mode	Normal mode	Expanded mode
CH1	Standard control	Heating-cooling control	Heating-cooling control	Heating-cooling control	Heating-cooling control
CH2	Standard control	Heating-cooling control	Heating-cooling control	—*3	Heating-cooling control*4
CH3	Standard control	*3	Heating-cooling control*4	Standard control	Standard control
CH4	Standard control	*3	Heating-cooling control*4	Standard control	Standard control

<sup>\*3:</sup> Only temperature measurement using a temperature input terminal can be performed.

<sup>\*2:</sup> U.R.D.Co., LTD. For more information, visit http://www.u-rd.com

<sup>\*4:</sup> Heating-cooling control is performed using an output module in the system.



#### **Simple Motion Modules**



#### LD77MS2

Number of control axes: 2 axes Communication cycle: 150 Mbps Positioning data: 600 data/axis Max. connection distance: 100 m





#### LD77MS4

Number of control axes: 4 axes Communication cycle: 150 Mbps Positioning data: 600 data/axis Max. connection distance: 100 m





#### LD77MS16

Number of control axes: 16 axes Communication cycle: 150 Mbps Positioning data: 600 data/axis Max. connection distance: 100 m



\*SSCNET(Servo System Controller NETwork)

Function		LD77MS2	LD77MS4	LD77MS16
Positioning control to	unction	•	•	•
Speed/torque contr	ol function	•	•	•
Linear interpolation		2 axes	2/3/4 axes	2/3/4 axes
Circular interpolatio	n	2 axes	2 axes	2 axes
Cumahuanaua	External encoder	•	•	•
Synchronous control function	Cam	•	•	•
CONTROL IGNICTION	Phase compensation	•	•	•
Manual pulse gener	ator operation function	•	•	•
OPR control function	n	•	•	•

#### **Positioning Modules**



#### LD75P1

Number of control axes: 1 axis Max. output pulses: 200K pulses/s Positioning data: 600 data/axis Max. connection distance: 2 m



#### LD75P2

Number of control axes: 2 axis
Max. output pulses: 200K pulses/s
Positioning data: 600 data/axis
Max. connection distance: 2 m



#### LD75P4

Number of control axes: 4 axis Max. output pulses: 200K pulses/s Positioning data: 600 data/axis Max. connection distance: 2 m



#### LD75D1

Number of control axes: 1 axis Max. output pulses: 4M pulse/s Positioning data: 600 data/axis Max. connection distance: 10 m



#### LD75D2

Number of control axes: 2 axis Max. output pulses: 4M pulse/s Positioning data: 600 data/axis Max. connection distance: 10 m



#### LD75D4

Number of control axes: 4 axis Max. output pulses: 4M pulse/s Positioning data: 600 data/axis Max. connection distance: 10 m

Function	LD75P1	LD75P2	LD75P4	LD75D1	LD75D2	LD75D4	
Fullction	(	Open collector outpu	it		Differential output		
Positioning control function	•	•	•	•	•	•	
Speed control function	•	•	•	•	•	•	
Linear interpolation	_	2 axes	2/3/4 axes	_	2 axes	2/3/4 axes	
Circular interpolation	_	2 axes	2 axes	_	2 axes	2 axes	
OPR control function	•	•	•	•	•	•	

#### Countless applications are possible

LD77MS□

A variety of control types including positioning control, speed control, torque control, cam control and synchronous control can be implemented easily with simple parameter settings and a sequence program.

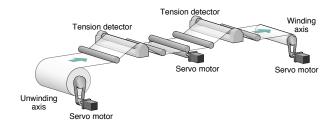
#### **Positioning control**

- Support for a multitude of applications thanks to a wide variety of control formats including linear interpolation control (up to 4 axes), 2-axis circular interpolation control, fixed feed control and continuous orbit control.
- Use a sequence program to set the positioning address, speed, etc. for easy automatic operation.
- Quickly implement powerful auxiliary functions such as step operation, target position change, M codes, and the skip function.

#### Speed control and torque control

- Tension control applications such as winding and rewinding are supported.
- Switch from positioning control, to speed and torque control, and back to positioning control.
   Because the present location is tracked even in speed and
- Because the present location is tracked even in speed and torque control mode, it is possible to maintain the current absolute position when returning to positioning control.

# XY table 2-axis linear interpolation 2-axis circular interpolation 3-axis linear interpolation Continuous orbit control Continuous orbit control Continuous orbit control Continuous orbit control Linear/circular interpolation

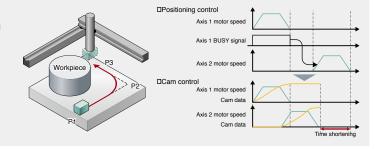


#### Synchronous control and cam control

• Cam control may be used alone or combined with synchronous control.

#### Example application for cam control:

To create a movement path around a workpiece using positioning control, axis 2 waits for axis 1 to complete the move from P1 to P2 before it begins moving from P2 to P3. By using cam control, axis 2 does not need to wait for axis 1 to complete its movement and the in position time can be shortened.



#### Many functions in a compact design

#### LD77MS□

#### Use a synchronous encoder with synchronous control

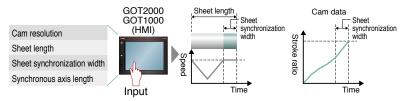
- Input pulses from a synchronous encoder can be used to perform synchronous control and cam control.
- The incremental synchronous encoder can be used by using the LD77MS built-in interface. An option unit is not required.
- To further improve the synchronization accuracy, the phase compensation function, designed to compensate for synchronous encoder delays, can be used.

#### Standard mark detection function

 The built-in mark detection signal interface allows these units to be used in packaging systems for example, without additional option modules.

#### Automatic cam data generation for rotary cutter

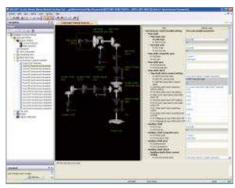
 Complicated cam data for rotary cutters can be automatically generated just by specifying a few parameters like the sheet length and synchronization width.



#### Perfect synchronous control is easy to achieve

Replace mechanical gears, shafts, speed change gears, cams, etc. and generate synchronous control operations using software.

- Complicated programs are unnecessary for synchronous control because it can be implemented easily using parameter settings.
- Start and stop synchronous control for each axis.
   Use the synchronous control axis and positioning control axis together.
- Convey the travel value of main shaft to the output axis via the clutch.



Synchronous Control Parameter Settings

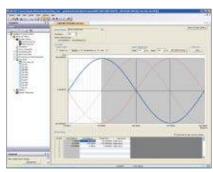
#### Cam control made simple

LD77MS□

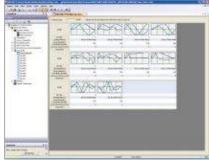
LD77MS□

Create cam data patterns easily.

- Create cam profiles unrestricted by existing concepts of electronic cam control.
- · Change the acceleration, speed, stroke, and jerk while simultaneously seeing how it effects the profile.
- Easily check created cam data by viewing them as thumbnails.
- Import and export cam data in CSV format.



Cam Data



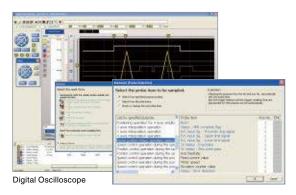
Cam Data List

#### Simplified debugging and commissioning

#### LD77MS□

#### Digital oscilloscope function

- Collection of data from the simple motion module is synchronized with the operation cycle and waveform displays to facilitate an efficient start up.
- The assistant function explains each step.
- Use the purpose-based probe setting to easily set frequentlyviewed data.
- Sample 16CH word and 16CH bit data and display 8CH words and 8CH bits in real time.



#### Monitor and test functions

- Complete the system installation and perform operational checks easily using powerful monitor and test functions.
- Select items to be displayed on the monitor using a wealth of information monitoring options.
- The test function can be used to check basic operations without a sequence program.



Monitor Positioning Test

	Ite	m	LD77MS2*1	LD77MS4	LD77MS16			
Number of control a	axes		2 axes	4 axes	16 axes			
Operation cycle				3 ms	0.88 ms/1.77 ms*2			
Interpolation function	on		Linear interpolation (2 axes), Circular interpolation (2 axes)  2-axis/3-axis/4-axis linear interpolation, Circular interpolation (2 axes)  PTP (Point To Point) control, path control (both linear and arc can be set), speed control,					
Control system			,	itrol, path control (both linear and arc c d-position switching control, position-sp	,, , , , , , , , , , , , , , , , , , ,			
Acceleration/decele	eration proces	SS		eleration/deceleration, S-curve acceleration				
Compensation fund	tion			compensation, Electronic gear, Near pa				
Synchronous contro	ol		External encoder,	Cam, Phase Compensation, Cam gene	rated automatically			
Control unit			COO data (pacitioning data No. 1 CO	mm, inch, degree, pulse				
Positioning data			"	00) / axis (Can be set with GX Works2 and block start data can be saved on fl				
Machine OPR control			d 1), Count method 2), Data set metho					
PR control Fast OPR control			•					
	Sub functions			OPR retry, OP shift				
		Linear control		xis linear interpolation control, 3-axis linear appears (Companies appears Re				
	Position	Fixed-feed control	· ·	olation control*3 (Composite speed, Re s fixed-feed control, 3-axis fixed-feed control, 3-axis fixed-feed control, 3-axis fixed-feed control, 3-axis fixed-feed control (action to the	<u>'</u>			
	control	2-axis circular interpolation	· ·	point designation, center point design				
	Canadana	control						
Position control	Speed cont	roi tion switching control	i-axis speed control, 2	-axis speed control, 3-axis speed control, INC mode, ABS mode	oi, 4-axis speed control			
		eed switching control		INC mode				
		Current value changing	Changing to a new current value usi	ng the positioning data, Changing to a	new current value using the start N			
	Other	NOP instruction		•				
	control	JUMP instruction		Unconditional JUMP, Conditional JUMI	)			
liab laval iti		LOOP, LEND	Disability O	dition atom Wait atom Cimultonacus ato	wt. Damastad start			
ligh-level positioning	ng control JOG operat	ion	Block start, Conc	lition start, Wait start, Simultaneous sta	rı, nepeated start			
Manual control	Inching ope			•				
	Manual pulse generator operation		Possible to connect	1 module (Incremental) Unit magnifica	tion (110000 times)			
xpansion control	Speed-torq	ue control	Speed control withou	ut positioning loops, Torque control with	out positioning loops			
bsolute position sy				pattery to the servo amplifier to ensure				
synchronous encod		,	Up to 4 channels (Total of the internal interface, interface via servo amplifier, and interface via the PLC CPU)					
	Internal interface Speed limit function		1 channel (Incremental)  Speed limit value, JOG speed limit value					
	Torque limit		Torque limit value_same setting, torque limit value_individual setting					
functions that limit	Forced stop function		Torique minicipa	Valid/invalid setting	arrada coung			
ontrol	Software st	roke limit function	Movable range check with	current feed value, movable range che	ck with machine feed value			
		troke limit function	•					
		nge function	•					
unctions that	Override fu	nction n/deceleration time change	•					
hange control	function	n/deceleration time change	•					
letails	Torque cha	nge function	•					
		ion change function	Target position	on address and target position speed a	e changeable			
	M code out			•				
Other functions	Step function			Deceleration unit step, Data No. unit ste equence CPU, Via external command	·			
	Teaching fu		Via S	equence CFO, via external command	signal			
	rousining is		Mark detection mode (Continuous	Detection mode, Specified Number of I	Detections mode, Ring Buffer mode			
Mark detection unction	Mark detec	tion signal		4 points				
	Mark detec	tion setting	-	4	16			
Optional data monit				4 points/axis				
Master-slave opera Amplifier-less opera				•				
Digital oscilloscope			Rit data: 8 channels \	Word data: 4 channels	Bit data: 16 channels,			
дш. осолюоооре	30.011		Za data. O ona mois, t		Word data: 16 channels*4			
			1-axis linear control					
			1-axis speed control					
				ation control (Composite speed) (Reference axis speed)				
			2-axis circular interp					
tarting time*5			2-axis speed control		0.88 ms			
			·	ation control (Composite speed)				
				ation control (Reference axis speed)				
			3-axis speed control					
			4-axis linear interpol 4-axis speed control		4			
			4-axis speed control					
				100				
		tions [m (ft.)]		100 m				
Module size allocat	ion	tions [m (ft.)]	22 r	2	pints)			
Module size allocat Number of occupied	ion d I/O points		32 p		pints)			
Maximum distance Module size allocati Number of occupied Servo amplifier con 5 V DC internal curr	ion d I/O points nection syste	em		2 points (I/O assignment: Intelligent 32 po	oints)			

<sup>1:</sup> The maximum number of control axes for LD77MS2 is two axes. Use LD77MS4 or LD77MS16 to control three or more axes.

<sup>\*2:</sup> Default value is 1.77 ms. If necessary, check the operation time and change to 0.88 ms.
\*3: 4-axis linear interpolation control is enabled only at the reference axis speed.
\*4: 8CH word data and 8CH bit data can be displayed in real time.

<sup>\*5:</sup> Using the pre-reading start function, the actual starting time can be shortened.

	ilications	Item	LD75P1/LD75D1 <sup>-1</sup>	LD75P2/LD75D2 <sup>*1</sup>	LD75P4/LD75D4"			
Number o	f control axes	5	1 axis					
Interpolati	ion function		2-axis linear interpolation 2-axis circular interpolation		2-axis/3-axis/4-axis linear interpolation			
			DTD (Deies Te I		2-axis circular interpolation			
Control sy	/stem			Point) control, path control (both linear and ed-position switching control, position-spe				
Control ur	nit		speed control, spe	mm, inch, degree, pulse	ed Switching Control			
	-			600 data (positioning data No.1600) /axi	is			
Positionin	g data			e set with peripheral device or sequence p				
Backup			· · · · · · · · · · · · · · · · · · ·	, and block start data can be saved on flas				
	Ditii	PTP*2 control		Increment system, absolute system				
	Positioning control	Speed-position switching control		Increment system, absolute system*3				
	system	Position-speed switching control		Increment system				
		Path control		Increment system, absolute system				
				-214748364.8214748364.7 (μm)				
		In absolute system		-21474.8364821474.83647 (inch)				
		,		0359.99999 (degree) -21474836482147483647 (pulse)				
				-214748364.8214748364.7 (µm)				
				-21474.8364821474.83647 (inch)				
	Positioning	In increment system		-21474.8364821474.83647 (degree)				
	control			-21474836482147483647 (pulse)				
Positioning	range	In annual monition assistables		0214748364.7 (μm)				
control		In speed-position switching control (INC mode)/		021474.83647 (inch)				
		position-speed switching control		021474.83647 (degree) 02147483647 (pulse)				
		In speed-position switching control (ABS mode)*3	0359.99999 (degree)					
		,	0.0120000000.00 (mm/min)					
	Speed comr	mand	0.0012000000.000 (inch/min)					
	Opeed com	nand	0.0012000000.000 (degree/min)					
			14000000 (pulse/s)					
	Acceleration	/deceleration system selection	Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration					
	Acceleration	/deceleration time	18388608 ms  Four patterns can be set for each of acceleration time and deceleration time					
	Sudden stor	deceleration time	i oui patierno ou	18388608 ms	accoloration time			
OPR meth		a document and		6 types				
			1-axis linear contro		1.5 ms			
			1-axis speed contr		1.5 ms			
			•	olation control (Composite speed)	1.5 ms			
				1 1 1	1.5 ms			
				2-axis linear control (Reference axis speed) 2-axis circular interpolation control				
Starting tir	me*4		2-axis speed contr	ol	1.5 ms			
ŭ			3-axis linear interp	olation control (Composite speed)	1.7 ms			
				olation control (Reference axis speed)	1.7 ms			
			3-axis speed contr	ol	1.7 ms			
			4-axis linear interp	olation control	1.8 ms			
			4-axis speed contr		1.8 ms			
		LD75P□		200 kpulse/s				
Maximum	output pulse	LD75D□		4 Mpulse/s				
Maximum c	onnection	LD75P□		2 m				
	tween drive uni			10 m				
	ze allocation	201000		2				
	f occupied I/0	) points	32	2 points (I/O assignment: Intelligent 32 points	nts)			
	· · · · · · · · · · · · · · · · · · ·			onnector	40-pin connector ×2			
External interface		LD75P□	•	0.48 A	0.55 A			
	ternal current	LD/3FL						
	ternal current ion	LD75D	0.51 A	0.62 A	0.76 A			

weignt

\*1: LD75P□ refers to the open collector output type, and LD75D□ refers to the differential driver output type.

\*2: The abbreviation for Point To Point, referring to position control.

\*3: In speed-position switching control (ABS mode), "degree" is the only control unit available.

\*4: Using the pre-reading start function, the actual starting time can be shortened.

SPU

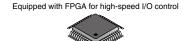


#### Flexible High-Speed I/O Control Module



#### LD40PD01

Input specifications Number of inputs: 12 points (all for 5 V DC/24 V DC/differential) Pulse input speed: Max. 8M pulse/s (2MHz) Output specifications Number of outputs: 8 points for 5 V DC to 24 V DC, 6 points for differential Pulse output speed: Max. 8M pulse/s (2MHz)



I/O response

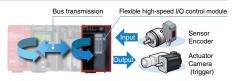
Resolution 25 ns

Intuitive setting

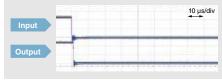
#### Fast and stable I/O response

High-speed response is realized with the hardware performance asynchronous to the CPU and control bus.

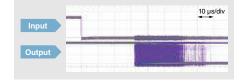
- LD40PD01 is equipped with an external I/O interface and FPGA\*1. This feature enables LD40PD01 to perform high-speed control, without being restricted by the CPU scan time and control bus performance. Dedicated configuration tool is also available to pre-check the product operation, further reducing the startup time.
- I/O response is stable as its processing speed only fluctuates in nanoseconds.



■ Flexible high-speed I/O control module



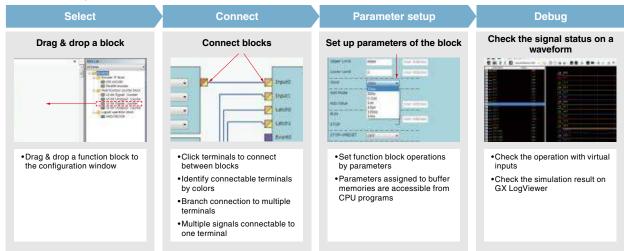
■ Existing programmable controller (LCPU embedded I/O + interrupts)



<sup>\*1:</sup> Abbreviation of Field Programmable Gate Array. FPGA is an LSI that can be programmed after the manufacture.

#### Easy FPGA setup with dedicated configuration tool\*2

The design process associated with FPGA (HDL programming, logic synthesis, timing analysis) is no longer required, drastically reducing the development time. The configuration tool is also useful to pre-check the product operation, further reducing the startup time.



<sup>\*2:</sup> For further information on "Flexible High-Speed I/O Control Module Configuration Tool", please contact your local Mitsubishi sales representative.

#### Supporting versatile applications

The flexible high-speed I/O control module realizes a wide range of controls including speed measurement, adjusted pulse output, ratio setting/distributed output, PWM control, and cam switch control.

#### Pulse adjustment

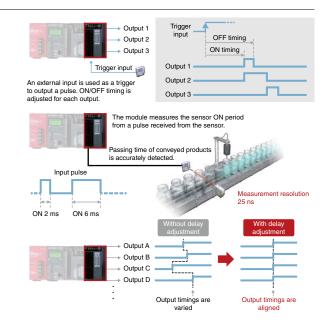
- ON/OFF timings are finely adjusted down to 25 ns by using trigger inputs.
- Fluctuation of ON/OFF operation is minimized down to nanoseconds, enabling highly precise control.

#### Speed measurement

- In addition to ON and OFF width, measurement in different conditions is possible, such as ON timing difference between sensors.
- The measurement increment of minimum 25 ns realizes highly accurate measurement.

#### Delay output

• Output timing delays are adjusted for each point, minimizing output variations.



n		LD40		
		DC	Differential	
		12 points (5/24 \	/ DC/differential)	
		8 points (524 V DC, 0.1 A/point)	6 points	
		8 inte	rrupts	
		≤ 1 µs (pulse input speed: Max. 200 kpulse/s)	≤ 1 µs (pulse input speed: Max. 8 Mpulse/s)	
		≤ 1 µs (pulse input speed: Max. 200 kpulse/s)	≤ 1 µs (pulse input speed: Max. 8 Mpulse/s)	
configura	tion tool)			
Logic se	ect	Inverted, n	ot inverted	
Filter tim	e		ns, 0.2 ms, 0.4 ms, 0.6 ms, 1 ms, 5 ms kpulse/s, 1 Mpulse/s, 2 Mpulse/s, 4 Mpulse/s, 8 Mpulse/s	
Input dat	a type	Pure binary, g	ray code, BCD	
Data len	gth	1 bit	12 bits	
Input dat	a type	Pure binary	, gray code	
Data len	gth	1 bit32 bits (Data length for single to	urn, multi-turn, and status can be set.)	
Transmission speed		100 kHz, 200 kHz, 300 kHz, 400 kHz, 500 kHz, 1.0 MHz, 1.5 MHz, 2.0 MHz		
Counter timer block	i_	Addition, subtraction, linear counter mo	ode, ring counter mode, addition mode,	
	Type	preset counter function, latch coun	nter function, internal clock function	
	Internal clock	25 ns, 50 ns, 0.1 μs, 1	μs, 10 μs, 100 μs, 1 ms	
	Counting	32-bit signed binary (-214748364821474836	647), 32-bit unsigned binary (04294967295)	
	range	16-bit signed binary (-3276832767	7), 16-bit unsigned binary (065535)	
Compare	Compare value	Same as the d	counting range	
	Compare mode	=, >, <, ≥, ≤, <>, within the	e range, outside the range	
Cam switch block number of steps		Up to 16 steps		
Set/reset block		Uses the signal input to the Set terminal as a trigger to output the High fixed signal.  Uses the signal input to the Reset terminal as a trigger to output the Low fixed signal.		
Logical c	peration type	• .		
-	· · · · · · · · · · · · · · · · · · ·	,	•	
		None, 12.5 ns, 25 ns, 50 ns, 0.1 μs, 1 μs, 10 μs, 10 μs, 1 ms Can be set up to 64 multiplies.		
nerformed	with		· · · · · · · · · · · · · · · · · · ·	
cks	•••••		ace conversion	
	logic			
		• 1	2	
Module size allocation		32 points (I/O assignme	ent: Intelligent 32 points)	
Number of occupied I/O points  External interface		32 points (I/O assignment: Intelligent 32 points) 40-pin connector ×2		
nts		40-pin cor	nnector ×2	
mis		·	nnector ×2 6 A	
	configura Logic sel Filter time Input dat Data leng Input dat Data leng Transmis Counter timer block Compare block Cam swin number of Set/reset Logical of Logic sel Delay time	configuration tool)  Logic select  Filter time  Input data type Data length Input data type Data length Transmission speed  Counter timer Internal clock block Counting range  Compare value block Compare mode  Cam switch block number of steps  Set/reset block Logical operation type Logic select Delay time	12 points (5/24 No. 12 p	

#### **High-Speed Counter Modules**



Function	LD62	LD62D
FullClion	DC input	Differential input
Linear counter function	•	•
Ring counter function	•	•
Coincidence output function	•	•
Preset function	•	•
Disable count function	•	•
Latch counter function	•	•
Sampling counter function	•	•
Periodic pulse counter function	•	•

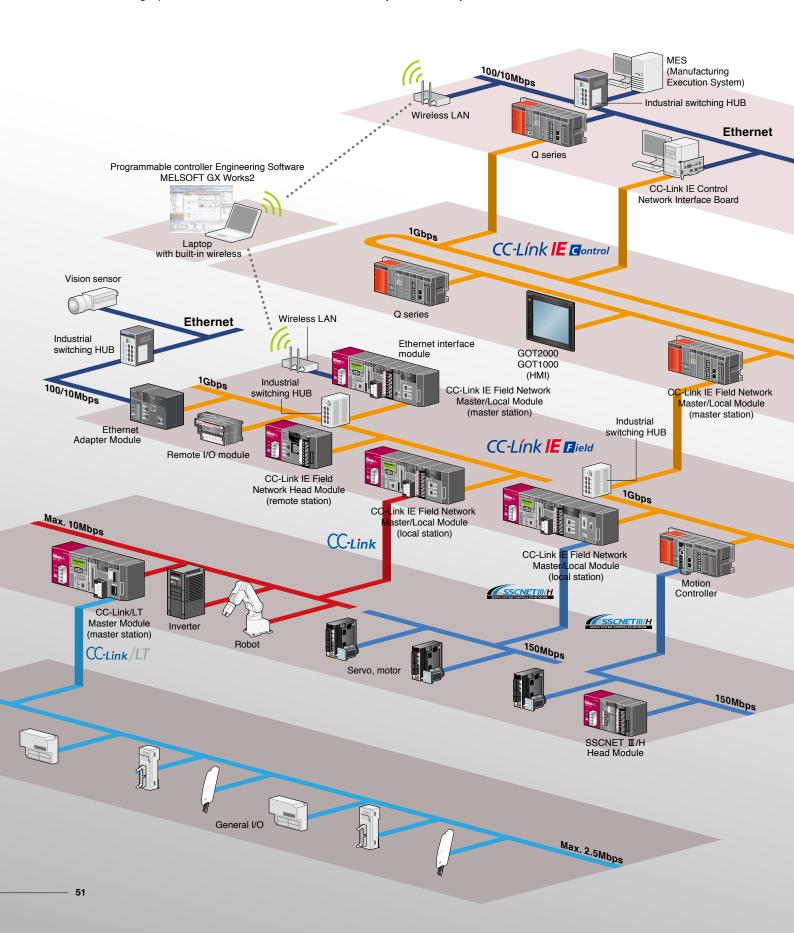
	Item		LD62 [DC input]	LD62D [Differential input]				
Number of c	hannels		2 channels					
Counting sp	eed switch setting		10K pulses/s, 100K pulses/s, 200K pulses/s 10K pulses/s, 100K pulses/s, 200K pulses/s, 500K pulses/s					
Count input	Phase		1-phase input (multiple of 1/2), CW/0	CCW, 2-phase input (multiple of 1/2/4)				
signal	Signal level (A, B)		5/12/24 V DC 25 mA	EIA Standard RS-422-A differential type line driver level (Equivalent with AM26LS31 (manufactured by Texas Instruments Japan Limited))				
	Maximum counting speed	<b> </b> *1	200K pulses/s	500K pulses/s				
	Counting range		-2147483648	32147483647				
	Туре		UP/DOWN preset counte	r and ring counter functions				
			10K pulses/s 50 μs	10K pulses/s 50 μs				
	Minimum count pulse wid	th	100K pulses/s 5 μs	100K pulses/s 5 μs				
Counter	(Duty ratio 50%)		200K pulses/s 2.5 μs	200K pulses/s 2.5 μs				
Counton				500K pulses/s 1 μs				
			10K pulses/s 25 μs	10K pulses/s 25 μs				
	Minimum phase differenti	al for	100K pulses/s 2.5 μs	100K pulses/s 2.5 μs				
	2-phase input		200K pulses/s 1.25 μs	200K pulses/s 1.25 μs				
				500K pulses/s 0.5 μs				
Coincidence	Comparison range		Binary with 32-bit code (-21474836482147483647)					
output	Comparison result		Set value < Count value Set value = Count value Set value > Count value					
	Preset			5/12/24 V DC 25 mA (Differential type line drivers				
External	Function start		5/12/24 V DC 25 mA conforming to EIA standard RS-422-A are also applicable.					
input	Minimum input	OFF to ON	Function s	tart: 0.5 ms				
	response time	ON to OFF	Function start: 1 ms					
	Coincidence output		2 points/channel					
External	Output voltage/current		1224 V DC 0.5 A					
output	Output response time	OFF to ON	≤ 0.1 ms (rated load, resistive load)					
	<u> </u>	ON to OFF	<u> </u>	<u> </u>				
Module size				1				
	ccupied I/O points			ent: Intelligent 16 points)				
External inte				connector				
	nal current consumption		0.31 A	0.36 A				
Weight			0.1	13 kg				

<sup>\*1:</sup> The counting speed is affected by the rising/falling pulse speed. For details, refer to the corresponding manual.

#### Seamless integration of multiple networks

The MELSEC L Series is part of a family of products all interconnected across various levels of automation. Based on the seamless message protocol (SLMP\*1), data flows transparently between the sensor level and the management level across multiple industry-standard automation networks.

CC-Link IE, Asia's No. 1 industrial network, realizes fast gigabit data transmission speeds, further optimizing the manufacturing cycle. In addition, the SSCNET 3/H high-speed motion control network further enhance the factory-wide connectivity solution.





#### Seamless communication

Seamless data communication through Ethernet, CC-Link IE Control, CC-Link IE Field, and CC-Link networks allow easy access to information, no matter where it resides on the network. Through this technology, it is possible to "drill down" from the Enterprise or IT layer through multiple networks accessing programming controllers using GX Works2 programming or other related software.

In addition, many devices supporting SLMP\*1 such as vision sensors and RFID controllers may be connected to the CC-Link IE Field Network.

\*1: SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.



## CC-Línk IE Gontrol

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications (128K word) over a high-speed (1 Gbps) dual-loop optical cable topology.

\*: L Series does not support the CC-Link IE Control Network.

## CC-Línk IE Field

CC-Link IE Field is a versatile gigabit Ethernet-based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations. \*: Compatible modules: LJ71GF11-T2, LJ72GF15-T2

### -Link

CC-Link is a high-speed and high-reliable deterministic I/O control network which realizes reduced wiring whilst offering multi-vendor compatible products. This open field network is a global standard originating from Japan and Asia.

\*: Compatible modules: L26CPU-BT, L26CPU-PBT, LJ61BT11

## SSCNETIII/H

SSCNETIII/H is a dedicated high-speed, high-performance, and highly reliable servo system control network that offers flexible long distance wiring capabilities based on optical fiber cable topology.

\*: Compatible modules: LD77MS2, LD77MS4, LD77MS16, LJ72MS15

## CC-Link/LT

CC-Link/LT is a wire-saving sensor level network which is designed for use in panels between simple discrete devices. Its wiring system is based on reducing incorrect wiring and is based on CC-Link realizing high-speed and robust noise resistance features.

\*: Compatible module: LJ61CL12

#### **MODBUS®**

L-Series is now supporting the MODBUS® protocol network, realizing easy communication, with various MODBUS® slave devices compatible with Ethernet MODBUS®/TCP or RS-232/422/485 serial communication.

- Module supporting MODBUS®/TCP: L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT, LJ71E71-100 (master only)
  : Modules supporting MODBUS®: L6ADP(-R2/R4), LJ71C24(-R2) (master only)

#### BACnet™

This network supports the communication protocol standard BACnet<sup>™</sup> client function. This network is mainly used to monitor and control airconditioning, lighting and fire detection, etc. in building automation system applications.

\*: Compatible modules: L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT, LJ71E71-100 (client only)

	Application	Enterprise level network	Control level network		Device level network		Sensor level network
Network		Information communication	Controller distributed control	I/O control	Safety control	Motion control	Control
Ethernet		•					
CC-Link IE Control			•				
CC-Link IE Field			•	•	•	•	
CC-Link				•			
CC-Link/LT							•
SSCNET II/H						•	
BACnet™		•					
MODBUS®/TCP			•				
MODBUS®				•			

#### **CC-Link IE Field Network Master/Local Module**





#### Easy to configure settings

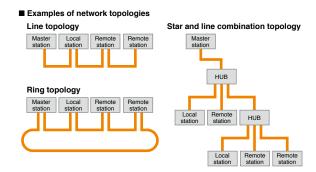
Network parameters are configured using the engineering tool, GX Works2. Only the master station needs to be configured, thereby greatly simplifying the network setup. Updating the system configuration is a breeze.



#### Flexible network topology

Various network topologies are supported including star, line, star and line combination, and ring. When hubs\*1 are used, new equipment can be added and machine layouts can be changed easily.

 $^{\star}$ 1: Hubs cannot be used in a ring configuration.



	Item		LJ71GF11-T2
Transmission speed	t		1 Gbps
		Line topology	12000 m (when cables are connected to 1 master station and 120 slave stations)
		Star topology	Depends on the system configuration
(Waximum transmis		Ring topology	12100 m (when cables are connected to 1 master station and 120 slave stations)
Maximum number of	connected	Master station	1 station (Up to 120 slave stations can be connected to the master station)
stations		Local station	120 stations
		Remote register (RWw)	8192 points, 16 KB
Maximum link point	e por etation	Remote register (RWr)	8192 points, 16 KB
waxiiiuiii iiik poiit	s per station	Remote input (RX)	16384 points, 2 KB
		Remote output (RY)	16384 points, 2 KB
		Remote register (RWw)	8192 points, 16 KB
	Master	Remote register (RWr)	8192 points, 16 KB
	station	Remote input (RX)	16384 points, 2 KB
Maximum link		Remote output (RY)	16384 points, 2 KB
points per station		Remote register (RWw)	8192 points, 16 KB (also including the send range of own station)
	Local	Remote register (RWr)	8192 points, 16 KB
	station	Remote input (RX)	16384 points, 2 KB
		Remote output (RY)	16384 points, 2 KB (also including the send range of own station)
Network topology			Line topology, star topology (Coexistence of line topology and star topology is possible.),
Network topology			and ring topology
Communication me			Token passing method
Communication por	t		CC-Link IE Field Network port x 2
RAS function			Automatic return, Slave station disconnection, Loopback function
Connection cable*2			Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000BASE-T standard
Module size allocat			2
Number of occupied	<u> </u>		32 points (I/O assignment: Intelligent 32 points)
5 V DC internal curr	rent consumpt	tion	0.89 A
Weight			0.27 kg

<sup>\*2:</sup> Standard (straight type) cable

#### **CC-Link IE Field Network Head Module**



#### LJ72GF15-T2

CC-Link IE Field Intelligent device station Communication speed: 1 Gbps Remote I/O: 2048 points Remote register: 1024 words RAS function

\*: END cover is included.



#### CC-Link IE Field Network remote I/O station

L Series I/O and intelligent function modules can be connected to the remote I/O head module without a dedicated CPU. There are many benefits to using intelligent device stations including reduced CPU and wiring costs, great flexibility in selecting I/O and intelligent function modules, and compact unit size.

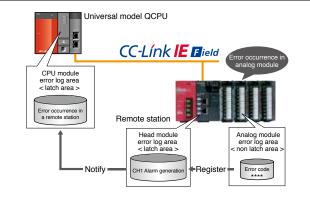


Modules compatible with the CC-Link IE Field Network head module

Wodales compatible with the GO Elink IE Field Network ricad mediale				
Ite	em			
I/O module	Input, output, I/O combined			
Multiple input module	Multiple input (voltage/current/ temperature)			
Analog module	Analog input, analog output, analog input/output			
Temperature input module	RTD input			
Temperature control module				
Simple motion module				
Positioning module				
High-speed counter module				
Network module	CC-Link, CC-Link/LT, serial communication			
AnyWireASLINK master module				

#### RAS (Reliability, Availability, Serviceability) functions

One feature of RAS is to store all remote station error histories in the master station's latched memory. This preserves the error information in one place in the event of power loss and allows for easy troubleshooting. Other RAS features include network event logging, unit error logging, and testing and monitoring capabilities.



Item		LJ72GF15-T2		
Transmission speed		1 Gbps		
Maximum overall cable	Line network topology	12000 m (with 1 master and 120 slaves connected)		
distance (Maximum transmission distance)	Star network topology	Depends on the system configuration		
	Ring network topology	12100 m (with 1 master and 120 slaves connected)		
Transmission path		Line, star, line and star mixed, or ring topology		
Communication method		Deterministic (token passing)		
Maximum number of install	able modules*1	10		
Communication port		CC-Link IE Field Network port x 2		
RAS function		Network event logging, unit error logging, testing, monitoring, and error history preservation function		
Connection cable*2		Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000 BASE-T standard		
5 V DC internal current cons	sumption	1.00 A		
Weight		0.23 kg		

<sup>\*1:</sup> The total number of modules that can be installed onto a CC-Link IE Field Network head module. (END cover and power supply module are not included.) Note that only one head module per system is possible.

<sup>\*2:</sup> Standard (straight type) cable.

#### **CC-Link Master/Local Module**

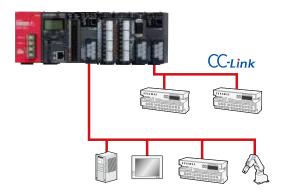




## Connect with a huge selection of device types using CC-Link

With such a large selection of CC-Link open network compatible devices, constructing a control system is easy.

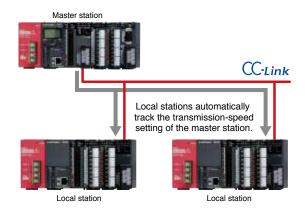
Even applications requiring vast amounts of data transmissions can be satisfied because CC-Link Ver.2.0 is supported.



## Local stations do not require transmission speed settings

#### Transmission speed auto-tracking function

When used as a local station, no transmission speed setting is required; the setting is made through automatic detection of the master station setting. The current transmission speed is indicated by an LED on the front surface of the module.



■ Specifications		LJ61BT11	
Transmission speed		156 kbps/625 kbps/2.5 Mbps/5 Mbps/10 Mbps	
Maximum overall cable distance (Maximum transmission distance)		1200 m (without repeater, varies according to the transmission speed)	
Maximum number of connected stations (master station)		64	
Number of occupied stations (local station)		14 stations (The number of stations can be switched using the GX Works2 parameter setting)	
	Remote I/O (RX, RY)	2048 points	
Maximum number of nk points per system*2	Remote register (RWw)	256 points (master station → remote device station/local station/intelligent device station/standby master station)	
iik poirits per system -	Remote register (RWr)	256 points (remote device station/local station/intelligent device station/standby master station → master station)	
	Remote I/O (RX, RY)	32 points (local station is 30 points)	
Number of link points per station*2	Remote register (RWw)	4 points (master station → remote device station/local station/intelligent device station/standby master station)	
ialion -	Remote register (RWr)	4 points (remote device station/local station/intelligent device station/standby master station → master station)	
Communication method		Broadcast polling method	
Synchronous method		Frame synchronization method	
Encoding method		NRZI method	
Fransmission path		Bus (RS-485)	
Transmission format		Conforms to HDLC	
Error control system		CRC (X <sup>16</sup> +X <sup>12</sup> +X <sup>5</sup> +1)	
		Automatic return function	
RAS function		Slave station cut-off function	
		Error detection via link special relay/register	
Connection cable		CC-Link dedicated cables compatible with Ver.1.10	
Module size allocation		1	
Number of occupied I/O points		32 points (I/O assignment: Intelligent 32 points)	
5 V DC internal current consumption		0.46 A	
Weight		0.15 kg	

<sup>\*2:</sup> Indicates the number of link points for Remote net Ver.1 mode.

#### **CC-Link/LT Master Module**

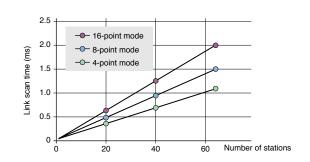




#### High speed equipment response

CC-Link/LT has an excellent response time. With 64 stations and a transmission speed of 2.5 Mbps, the maximum link scan time is just 1.2 ms. According to the transmission distance required, it is possible to select speeds of 2.5 Mbps, 625 kbps, or 156 kbps.

#### ■ CC-Link/LT link scan time (using a transmission speed of 2.5 Mbps)



#### Simple networking that 'just works'

There are no confusing parameters settings to make, and with remote I/O, only the master station needs to set the transmission speed.

Item			LJ61CL12		
Point mode		4-point mode	8-point mode	16-point mode	
Maximum link points			256 points	512 points	1024 points
(the same I/O address used)			(512 points)	(1024 points)	(2048 points)
Link points per station			4 points	8 points	16 points
(the same I/O address used)		ed)	(8 points)	(16 points)	(32 points)
Link scan time	32 stations connected	Points	128 points	256 points	512 points
		2.5 Mbps	0.7 ms	0.8 ms	1.0 ms
		625 kbps	2.2 ms	2.7 ms	3.8 ms
		156 kbps	8.0 ms	10.0 ms	14.1 ms
	64 stations connected	Points	256 points	512 points	1024 points
		2.5 Mbps	1.2 ms	1.5 ms	2.0 ms
		625 kbps	4.3 ms	5.4 ms	7.4 ms
		156 kbps	15.6 ms	20.0 ms	27.8 ms
Transmission speed			2.5 Mbps/625 kbps/156 kbps		
Communication method			BITR method (Broadcast polling + Interval Timed Response)		
Network topology			T-branch type		
Error control system			CRC		
Number of connectable modules		odules	64		
Remote station number			164		
Installation position of master station		ster station	End of a trunk line		
RAS function			Network diagnostics, internal loopback diagnostics, slave station cutoff function, automatic return function		
Connection cable*2			Dedicated flat cable (0.75 mm <sup>2</sup> × 4)*3, VCTF cable*4, flexible cable*3		
allocation			1		
Number of occupied I/O points*5		16, 32, 48, 64, 128, 256, 512, or 1024 points (I/O assignment: Intelli.)			
5 V DC internal current consumption		0.16 A			
	Voltage		20.428.8 V DC		
er supply*6	supply*6 Current consumption		0.03 A		
Current on startup		tartup	0.07 A		
			0.12 kg		
	Maximum lin (the same I// Link points p (the same I// Link points p (the same I// Link scan time  Transmission Communicat Network top: Error control Number of c Remote stat Installation p RAS function connection allocation coupied I/O p all current control control coupied I/O p all current control control coupied I/O p all current control control coupied I/O p all current control con	Maximum link points (the same I/O address us Link points per station (the same I/O address us  32 stations connected  Link scan time  64 stations connected  Transmission speed Communication method Network topology Error control system Number of connectable m Remote station number Installation position of ma RAS function Connection cable*2 allocation coupied I/O points*5 nal current consumption  Voltage ver supply*6 Current consumption	Maximum link points (the same I/O address used)  Link points per station (the same I/O address used)  32 stations connected  Link scan time  625 kbps  156 kbps  156 kbps  156 kbps  Transmission speed Communication method Network topology Error control system Number of connectable modules Remote station number Installation position of master station RAS function Connection cable*2 allocation coupied I/O points*5 tolal current consumption  Voltage ere supply*6  Current consumption	A-point mode	A-point mode

<sup>\*2:</sup> When the cables other than dedicated flat cables, VCTF cables, and flexible cables are used, performance of CCLink/LT is not guaranteed.

<sup>\*3:</sup> Use the dedicated flat cables and flexible cables accredited by CC-Link Partner Association. CC-Link Partner Association website: http://www.cc-link.org

 $<sup>^{\</sup>star}4:$  Refer to the manual for details regarding VCTF cable specifications.

<sup>\*5:</sup> Set the number of occupied I/O points using the operation setting switch. Refer to the manual for details.

 $<sup>^{\</sup>star}6$ : 24 V DC power supply is supplied through the dedicated power supply or power supply adapter.

#### SSCNET **II**/H Head Module



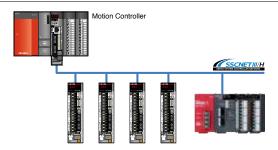


#### SSCNET **II**/H remote station

The SSCNET II/H head module is used to connect the MELSEC-L Series I/O and intelligent function modules to the SSCNET II/H network.

Functioning as the motion controller's remote station, flexible system configuration can be achieved while realizing reduced system wiring and a smaller footprint.

In addition, modules installed on the SSCNET  $\rm III/H$  head module can be used as a motion controller input/output using cyclic transmission.



#### ■ SSCNET II/H head module compatible modules

Product		
I/O module	Input, output, I/O combined	
Multiple input module	Multiple input (voltage/current/ temperature)	
Analog module	Analog input, analog output, analog I/O combined	
Temperature input module	RTD input	
High-speed counter modules		

#### ■ Compatible motion controller

·	
Category	Model
Motion CPU	Q172DSCPU
WIGHTOFO	Q173DSCPU
Standalone motion controller	Q170MSCPU

Item		LJ72MS15	
Maximum link points per	RWr, RX	256 bytes	
network	RWw, RY	256 bytes	
Maximum link points per	RWr, RX	64 bytes	
station	RWw, RY	64 bytes	
Communication speed		150 Mbps	
	Communication cycle: 888 µs	4	
Maximum connectable stations per network*1	Communication cycle: 444 µs	2	
	Communication cycle: 222 µs	1	
Maximum station-to-station of	distance	POF type: 20 m, H-PCF type: 50 m	
Connection method		Daisy chain connection (Regenerative relay system with a servo amplifier)	
Synchronous method		Synchronization of the control cycle and communication cycle that synchronize with the data transmission of the motion controller	
Communication cycle		222 µs/444 µs/888 µs	
Maximum number of installable modules*2		10	
Communication port		SSCNET III/H port x2	
Connection cable		SSCNET III cable (optical fiber cable)	
5 V DC internal current consumption		0.55 A	
Weight		0.20 kg	
*1: This number includes only	u bood modulos Conio	amplifiance are not included	

<sup>\*1:</sup> This number includes only head modules. Servo amplifiers are not included.

<sup>\*2:</sup> Total number of modules that can be installed onto a SSCNET III/H head module. (Does not include the END cover or power supply module.) Note that only one head module per system is possible.

#### **Ethernet Interface Module**



#### BACnet<sup>™</sup> MODBUS®/TCP

#### Modify/collect CPU data from other devices

#### SLMP (MC protocol) communication\*1

SLMP (Seamless Message Protocol) realizes seamless communication across devices on Ethernet that support the SLMP protocol.

\*1: This function can be used with modules with first five serial number digits are "15042" or later.



#### **MELSOFT** connection

The MELSOFT connection feature realizes the connection to various MELSOFT products including the GX Works2 programming tool. In addition, by using together with the MX Component communication support tool (optional product), custom communications programs can be created, without having to consider any dedicated protocol (send/receive procedure).

#### Easily connect to BACnet™ and MODBUS®/TCP

#### **Predefined Protocol support function**

Use the GX Works2 Predefined Protocol support function to easily set the required protocol for communicating with other devices.

Selecting from the communication protocol library Easily communicate with target devices by selecting a prepared protocol. The communication protocol library supports the SLMP, MODBUS®/TCP and BACnet™ client functions.



► Randomly preparing and editing a protocol

By creating a random protocol with the predefined protocol support function, data can be exchanged with a protocol that matches the target device.

Item			LJ71E	71-100	
Standard			100 BASE-TX	10 BASE-T	
	Data transmission speed		100 Mbps	10 Mbps	
	Interface		RJ45 (AUTO MDI/MDI-X)		
	Communication mode		Full duplex/Half duplex	Half duplex	
	Transmission method		Base band		
	Maximum segment length		100 m (length between a hub and node)*2		
	Maximum number of cascade connections		Cascade connection (maximum of 2 levels)*3	Cascade connection (maximum of 4 levels)*3	
	Number of simultaneous open connections		16 connections (Connections usable on a program)		
Sending/	Fixed buffer		1K word × 16		
receiving	Random access buffer		6K words × 1		
data storage memory	E-mail	Attachment	6K wo	rds × 1	
		Main text	960 wd	ords × 1	
Module size allocation			1		
Number of occupied I/O points			32 points (I/O assignment: Intelligent 32 points)		
5 V DC internal current consumption		nption	0.60 A		
Weight			0.18 kg		

<sup>\*2:</sup> For the maximum segment length (a length between hubs), consult with the manufacturer of the switching hub used.

<sup>\*3:</sup> This applies when a repeater hub is used. For the number of levels that can be constructed when a switching hub is used, consult with the manufacturer of the switching hub used.

#### **Serial Communication Modules**





**MODBUS®** 

#### **MODBUS®**

#### **Quick connection using predefined protocols**

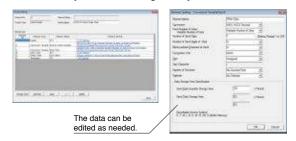
The predefined protocol enables easy setup of protocols to communicate with external devices using GX Works2. Connections are quickly setup by selecting the target device from the communications protocol library.



#### Easy to create/edit of predefined protocols

Easily create or edit predefined protocols from within the communications library.

Even if the target device protocol is not listed, it can be added easily to the existing library.



	Item	LJ71C24	LJ71C24-R2		
ntaufaaa	CH 1	RS-232 compliant (D-Sub 9P female)	RS-232 compliant (D-Sub 9P female)		
Interface	CH 2	RS-422/485 compliant (2-piece terminal block)	RS-232 compliant (D-Sub 9P female)		
	Line	Full-duplex/half-duplex communications			
Communication	MC protocol	Half-duplex communications			
	Predefined protocol				
	Nonprocedural protocol	Full-duplex/half-dupl	ex communications		
	Bidirectional protocol				
ynchronization m	ethod	Asynchronous method			
		50 bps/300 bps/600 bps/1200 bps/240	00 bps/4800 bps/9600 bps/14.4 kbps/		
		19.2 kbps/28.8 kbps/38.4 kbps/57.6 kbps/115.2 kbps/230.4 kbps			
ransmission spee	d	Transmission speed 230.4 kbps is only available for channel 1.			
		Total transmission speed of two inter	faces is available up to 230.4 kbps.		
		Total transmission speed of two interfaces is available up to 115.2	kbps when the communication data monitoring function is used		
	Start bits	1			
ata format	Data bits	7 or 8			
ala ioiiial	Parity bits	1 (vertical parity) or none			
	Stop bits	1 or 2			
	Parity check	All protocols and when ODD/EVEN is selected by parameter.			
rror detection		MC protocol/bidirectional prot	tocol selected by parameter.		
inor detection	Sum check code	For the predefined protocol, whether or not a sum check code is needed depends on the selected protocol			
		Nonprocedural protocol	selected by user frame.		
			RS-232 RS-422/485		
		DTR/DSR (ER/DR) control	• –		
		RS/CS control	• –		
ransmission contr	rol	CD signal control	• –		
		DC1/DC3 (Xon/Xoff) control			
		DC2/DC4 control	•   •		
		DTR/DSR signal control and DC code control are selected by the user.			
Module size allocation		1			
Number of occupied I/O points		32 points (I/O assignment: Intelligent 32 points)			
V DC internal cur	rrent consumption	0.39 A 0.26 A			
Veight		0.17 kg 0.14 kg			

0

## MELSEG L series

#### **AnyWireASLINK Master Module**



#### **AnyWireASLINK**

#### Linking the sensor I/O with the programmable controller

The AnyWireASLINK master module links the sensor inputs and outputs to the programmable controller.

The module enables flexible layout of miniature sensors with 512 I/O points.

The sensor power can be supplied to the AnyWireASLINK transmission line (2-wire) for communication, allowing sensors to be added easily.

With the MELSEC-Q/L/F Series, faulty sensors can be detected and the slave module settings can be managed at once by GX Works2 engineering environment, further reducing the engineering time.

#### ■ Basic configuration

Either the 2-wire type or 4-wire slave device can be selected according to the load current for AnyWireASLINK. In addition to the 2-wire type, a 4-wire type can also be used by supplying the local power.

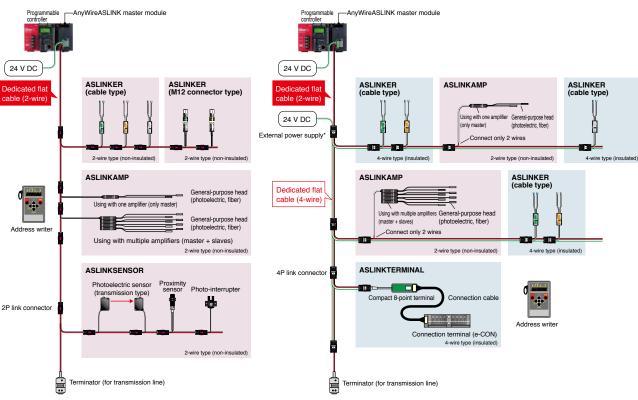
#### 2-wire type

If the load current is low, 2-wire type (non-insulated) slave devices can be used without an external power supply.

#### 4-wire type

The 4-wire type (insulated) slave devices require an external 24 V DC power supply to satisfy large load current applications, for example.

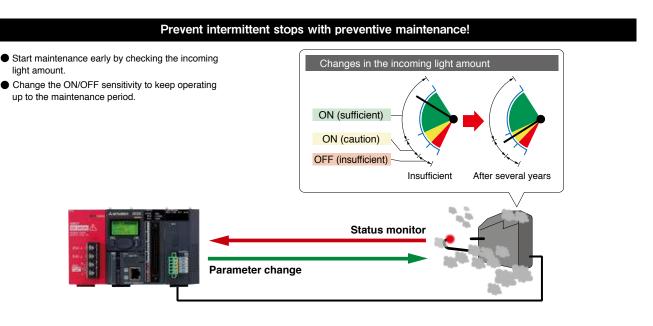
#### Configuration with 2-wire type (with no local power feed) Configuration with 2-wire/4-wire type (with local power feed)



\* External power for 4-wire type wiring.

#### **Preventing intermittent operation stops**

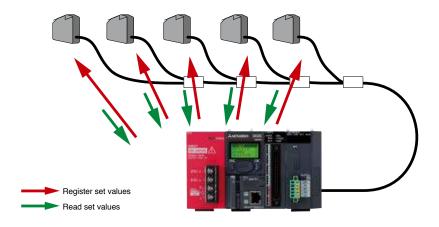
AnyWireASLINK can be used to monitor and save the sensor information within the programmable controller. Parameter settings of the AnyWireASLINK can also be changed via the programmable controller. Perform "preventive maintenance" with this function to prevent intermittent stops before they happen.



#### Reducing the setup time, and providing the traceability

AnyWireASLINK enables the set value to be registered at once to multiple sensors via a GOT (HMI) or personal computer. Also, the initial set values can be re-confirmed easily without having to read each sensor individually.

• Register set values to multiple sensors, and automatically read the initial set values.



Item	LJ51AW12AL DB	
Transmission clock	27.0 kHz	
Maximum transmission distance (overall length)	200 m*1	
Transmission method	DC power superimposed total frame cyclic method	
Connection style	Bus type (multi-drop method, T-branch method, tree branch method)	
Transmission protocol	Dedicated protocol (AnyWireASLINK)	
Error control	Checksum, double verification method	
Number of connected I/O points	Max. 512 points (256 input points/256 output points)	
Number of connected modules	Max. 128 modules (varies according to each slave module's current consumption)	
RAS function	Transmission cable break position detection function, transmission cable short-circuit detection function, transmission power drop detection function	
Transmission cable (DP, DN)	UL compatible universal 2-wire cable (VCTF, VCT 1.25 mm², 0.75 mm², rated temperature 70°C or more) UL compatible universal cable (1.25 mm², 0.75 mm², rated temperature 70°C or more) Dedicated flat cable (1.25 mm², 0.75 mm², rated temperature 90°C)	
• UL compatible universal 2-wire cable (VCTF, VCT 0.75 mm²2.0 mm², rated temperature 70°C or more)     • UL compatible universal cable (0.75 mm²2.0 mm², rated temperature 70°C or more)     • Dedicated flat cable (1.25 mm², 0.75 mm², rated temperature 90°C)		
Transmission cable supply current*2  Using 1.25 mm² cable: Max. 2 A Using 0.75 mm² cable: Max. 1 A		
Module size allocation	1	
Number of occupied I/O points	32 points (I/O assignment: 32 intelligent points)	
Voltage: 21.627.6 V DC (24 V DC -10+15%), ripple voltage 0.5 Vp-p or less  Recommended voltage: 26.4 V DC (24 V DC +10%)  Module current consumption: 0.1 A  Transmission cable current supply: Max. 2 A*1		
5 V DC internal current consumption	Max. 0.2 A	
Weight	0.2 kg	

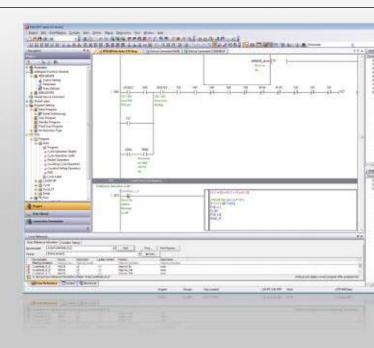
<sup>\*1:</sup> With the slave module having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.

\*2: Refer to the manual for the relation of the overall length, transmission cable (DP, DN) wire diameter and transmission cable current supply. In some slave modules with cables, the wire diameter of the transmission cable (DP, DN) integrated with the module may be 0.75 mm² or less.

# Increase productivity and lower the total cost of ownership

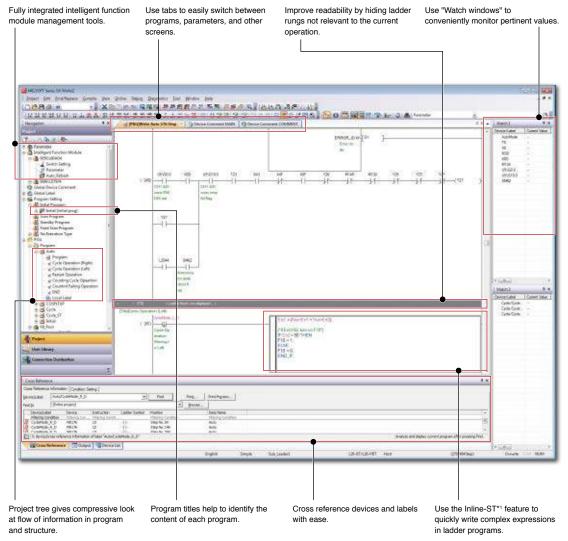
## GX Works2

GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.



#### User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.

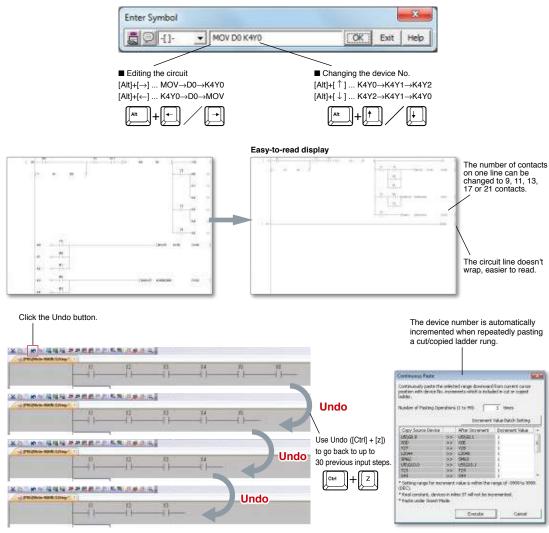


\*1: In-line ST can be only be created in projects that use labels.



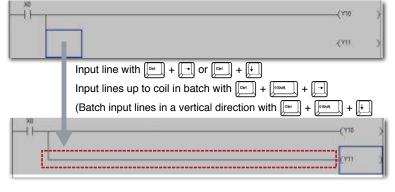
#### Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [ Alt ] + [  $\leftarrow$  ] / [  $\rightarrow$  ] or [ Alt ] + [  $\uparrow$  ] / [  $\downarrow$  ] keys.



#### Efficiently edit lines with keyboard

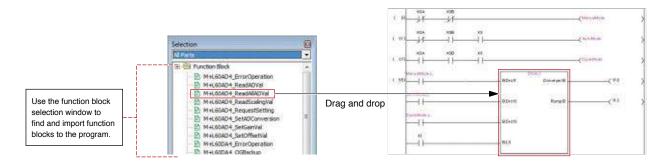
Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.



■ How to input a line Press [Ctrl] + [ $\rightarrow$ ] or [Ctrl] + [ $\downarrow$ ] at an empty spot. Press [Ctrl] + [ $\rightarrow$ ] or [Ctrl] + [ $\downarrow$ ] on top of a line to delete it.

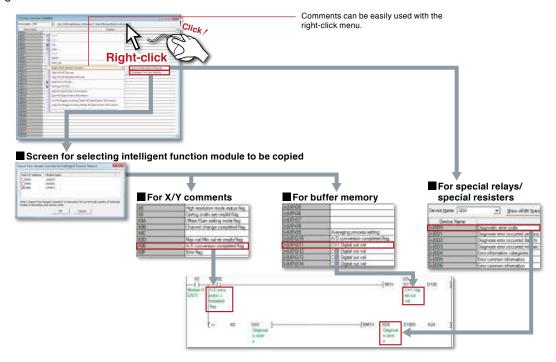
#### Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.



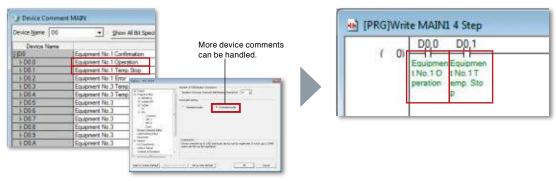
#### Use sample comments to eliminate the need to input comments

Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.



#### Quickly identify similar devices

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.

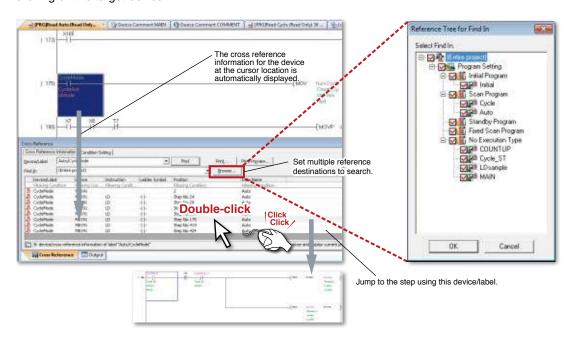


Function



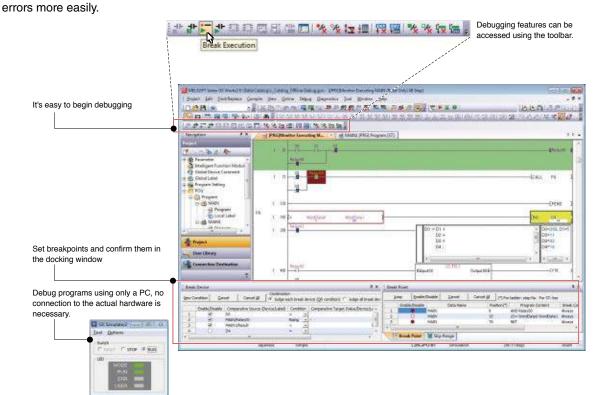
#### Cross referencing interlinked with circuit displays

Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.



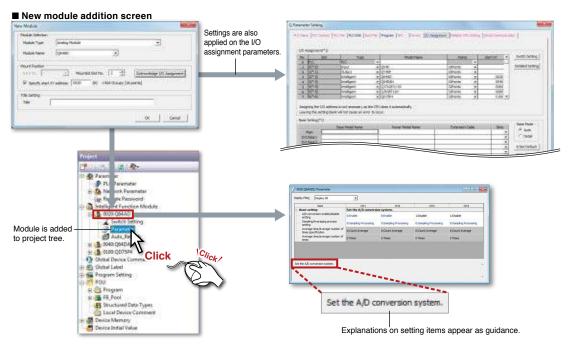
#### Offline debug without physical hardware

The simulation function is now integrated. The program can be executed in a step-by-step method, finding program



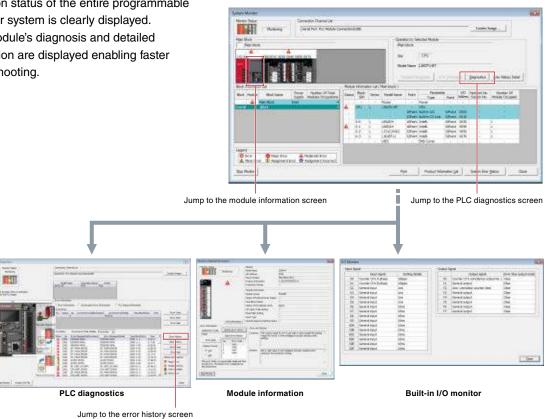
#### Integrating the intelligent function module setting tool (GX Configurator)

The intelligent function module's setting functions have been unified with GX Works2. Manage the intelligent function module's setting with a GX Works2 project.



#### System monitor and PLC diagnostics

Operation status of the entire programmable controller system is clearly displayed. Each module's diagnosis and detailed information are displayed enabling faster troubleshooting.



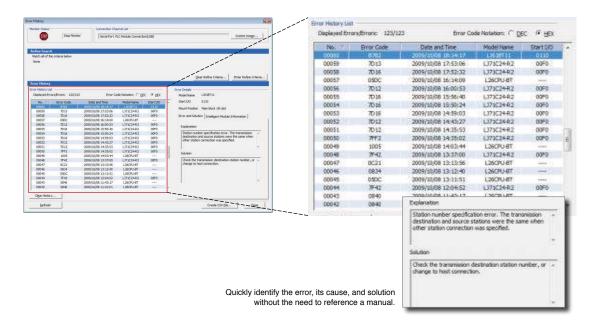
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CPU



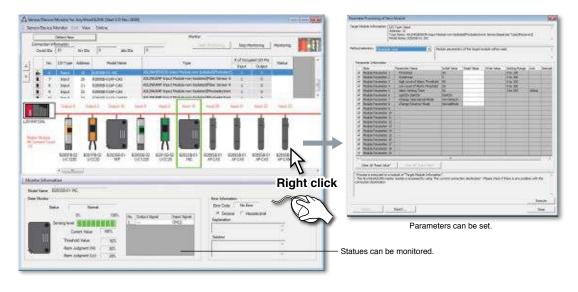
#### Time-stamped error history list

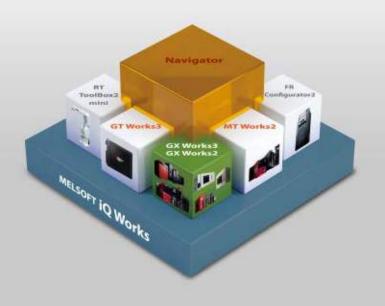
Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.



#### Set parameters and monitor the sensor

Parameter settings and monitoring can be performed on the third-party partner products, which support the iQ Sensor Solution (iQSS). Sensor connection and current values can be checked visually, allowing the user to act faster in case of a trouble.





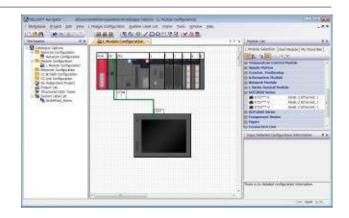
## MELSOFT iQ Works

# **Next Generation Integrated Engineering Environment**

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, GX Works2, MT Works2, GT Works3, RT ToolBox2 mini and FR Configurator2. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.

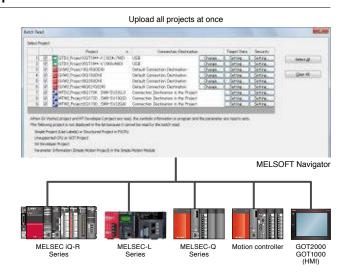
#### **Graphical project management**

The entire control system is represented using the "Network Configuration", "Module Configuration" and field network configuration windows. System components are easily added using a drag & drop interface, and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc. Different programmable controller and GOT (HMI) projects can be grouped together (for example by factory, line, and cell) for central management.



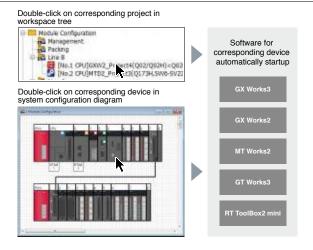
#### Read project data for multiple devices in a batch

Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT(HMI) on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.



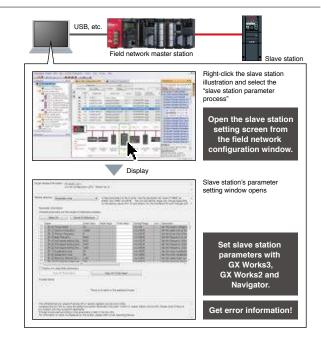
#### Automatically start up the relevant maintenance software with a single click

Just double-click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.



#### Set up field network slave stations

There's no need to prepare a dedicated tool to check or change the parameter settings of a slave station on-site. The latest version of iQ Works includes slave station setting utility. Inverter parameters, for example, can be confirmed or changed for speed adjustment directly from the field network configuration window. In addition, error information can be read easily.





CC-Link

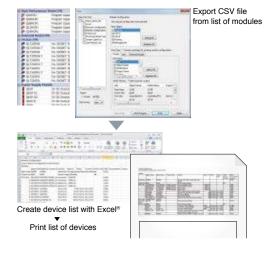
#### **Ethernet**

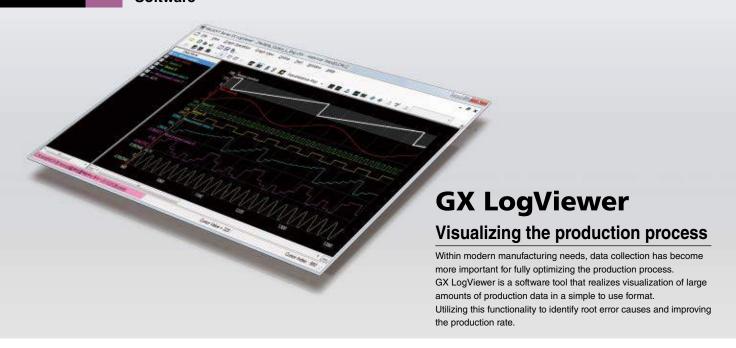
**AnyWireASLINK** 

#### Prepare a device from the system configuration diagram with no manual inputs

A list of modules used can be exported as a CSV file from the system configuration diagram.

This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel®, etc.

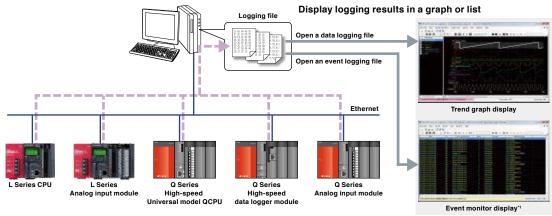




#### Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q Series or MELSEC-L Series.

The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.

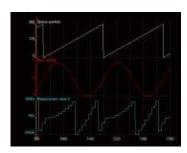


\*1: The event monitor display is supported only with the Q Series high-speed logger module.

#### Easily adjust graphs without referring to the setup manual

#### **Arranging graphs**

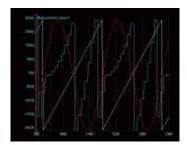
Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.



#### Overlapping graphs

With this it is possible to overlap each graph over one another.

Multiple graphs can be compared enabling easier data analysis and comparison.



#### Automatically adjusting graphs

Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.



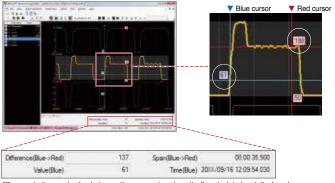
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CPU

MELSEG L series

## Easily confirm changes in data with dual cursors

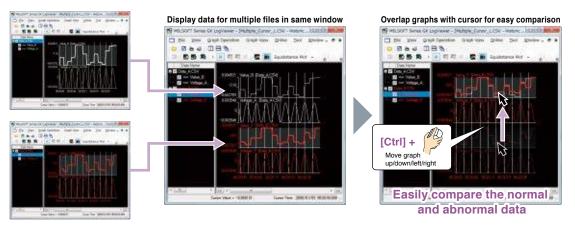
Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multi-cursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.



The difference in time and value between the cursors is automatically calculated and displayed.

## Display data for multiple files within one graph area for easy comparison

Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.



## Quickly jump cursor to designated position

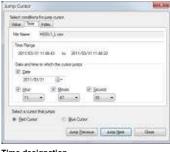
#### **Cursor jump**

Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.





Values are searched, and the cursor jumps to the position where the conditions match.



**Time designation**The cursor jumps to the designated time.



Index designation
The cursor jumps to the designated index.



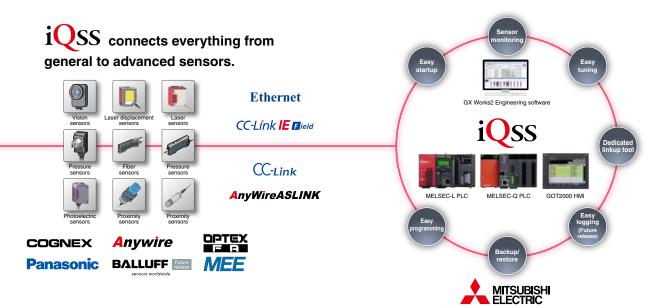
iQ Sensor Solution

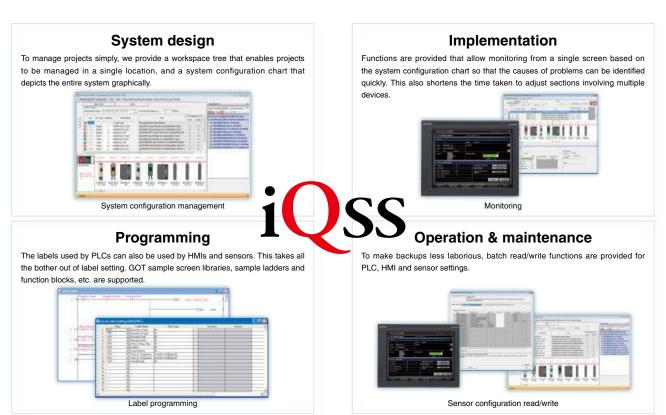
## A tool for connecting! Visualizing! For a more seamless sensor control!

Sensors used on the manufacturing floor are becoming more intelligent and complex, requiring even more maintenance of equipment and the overall management of various configuration setup software. With iQSS, the intelligent sensor solution provided by Mitsubishi Electric, configuration and maintenance of sensors are further simplified with the connectivity to other components such as automation controllers, HMIs, and engineering software even further enhanced reducing the overall TCO\*. \* Total Cost of Ownership

For further details please refer to the "iQ Sensor Solution Catalog".







Further simplifying the management of sensors in the control system



**Vision Solution** 

# COGNEX® machine vision system and Mitsubishi Electric FA Devices

## Innovating your production with this integral power.

Functioning as devices that "watch" instead of human eyes, COGNEX machine vision systems have continued to reform automation of production lines. Mitsubishi Electric FA devices, such as programmable controllers, lead the future of automation.

this spirit of innovation, have continued to increase.



For further details, please refer to the "Vision System & **Factory Automation** Solution Catalog".

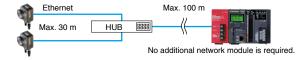
The possibilities of vision system solutions, created in the integration of

## COGNEX In-Sight EZ Series iQSS ready! Device partner High-speed processing model ..... EZ-740 High resolution model ...... EZ-742

## Simple connection

#### **Directly connect with Ethernet**

The "In-Sight EZ" can be directly connected to the Ethernet port provided on the "MELSEC-Q Series universal model" and "MELSEC-L" programmable controller, and to the Ethernet interface module on the MELSEC-F. By using a switching hub, a multi-unit vision system having units installed as far as 100 m away can be created.



## Simple communication with SLMP

Now that "In-Sight EZ" supports SLMP, data can be easily written from the vision system to the programmable controller. Communication is easily configured with "EasyBuilder". Just select the connected device and SLMP, set the programmable controller device used for communication and select the communication data from the list. With the SLMP scanner mode, a trigger can be applied on the vision system via SLMP.

## Simple control with function blocks (FB)

Intuitively setup the vision control system from the GX Works2 programming tool utilizing dedicated vision function blocks without having to develop specific programming code.

## COGNEX DataMan® Barcode Reader Device partner

- Fixed DataMan ......DataMan 50/60/300 • Hand-held DataMan ...... DataMan 8050/8100/8500
- DataMan active in various industries



Automotive







components

●Fixed DataMan 50/60

- ▶ Unmatched read rate performance with Hotbars™
- ▶ Proprietary Hotbars™ technology
- Solid state design with no moving parts
- Easy setup with three position adjustable lens and integrated lighting aimer
- ▶ IP65-rated housing (DataMan 50)
- ▶ Supports SLMP (DataMan 60)

# DataMan 50

DataMan 60

## ●Fixed DataMan 300 Series

- ▶ Unprecedented read rate with Hotbars™
- ▶ Reads the most difficult-to-read 2-D Direct Part Mark (DPM) codes
- Liquid lens with automatic variable focus
- ▶ Intelligent tuning
- ▶ Integrated lighting module
- ▶ Supports SLMP



DataMan 300



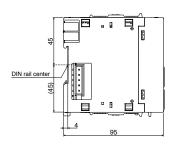
## ●Hand-held DataMan 8050/8100/8500 Series

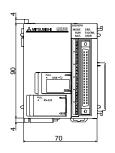
- ▶ UltraLight®: Two types of lighting enable optimum reading\*1
- Newly developed body enhances sturdiness
- ▶ Standard automatic focus adjustment function\*2
- ▶ Supports SLMP
- ▶ Cordless capability (up to 30 m communication range)
- ▶ Unprecedented read rate with Hotbars™
- \*1: DataMan 8500
- \*2: DataMan 8100 and 8500

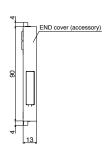


## CPU modules

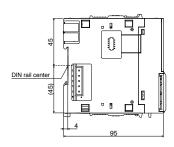
L02SCPU, L02SCPU-P

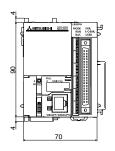


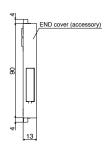




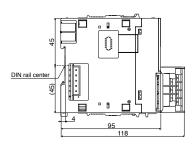
L02CPU, L02CPU-P, L06CPU, L06CPU-P, L26CPU, L26CPU-P

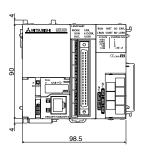


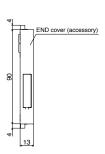




L26CPU-BT, L26CPU-PBT

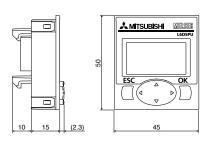






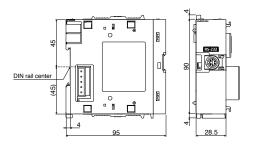
## Display unit

L6DSPU



## RS-232 adapter

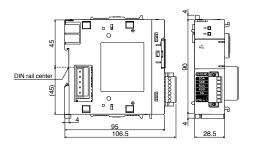
L6ADP-R2





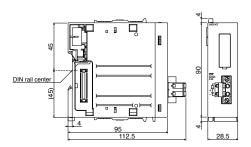
## RS-422/485 adapter

#### L6ADP-R4



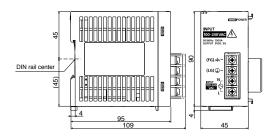
## **END** cover with error terminal

## L6EC-ET

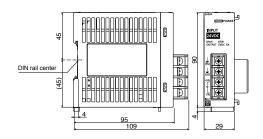


## **Power supply modules**

L61P, L63P

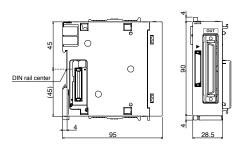


L63SP



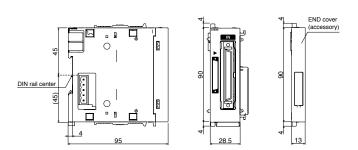
## Branch module

## L6EXB



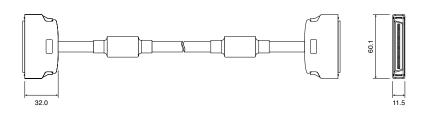
## **Extension module**

L6EXE



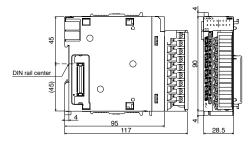
## **Extension cable**

LC06E, LC10E, LC30E

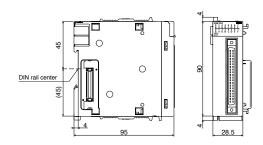


## Input/Output/I/O combined modules

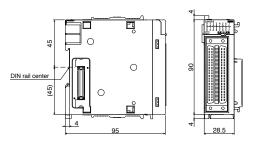
LX10, LX28, LX40C6, LY10R2, LY18R2A LY20S6, LY28S1A, LY40NT5P, LY40PT5P



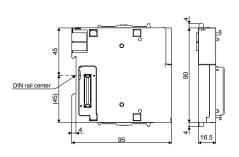
LX41C4, LY41NT1P, LY41PT1P



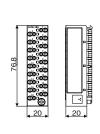
LX42C4, LY42NT1P, LY42PT1P LH42C4NT1P, LH42C4PT1P



LG69

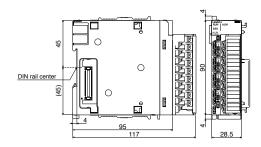


L6TE-18S



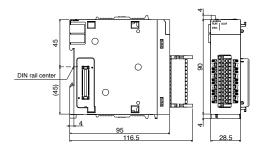
## Multiple input (voltage/current/temperature)/Analog input/output/I/O module

L60MD4-G, L60AD4, L60DA4, L60ADVL8, L60ADIL8, L60AD4-2GH, L60AD2DA2



## Temperature input module

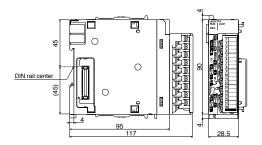
L60RD8



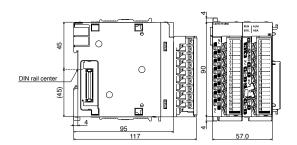


## **Temperature control modules**

L60TCTT4, L60TCRT4

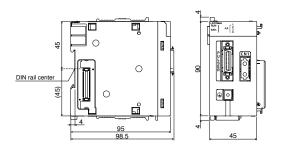


L60TCTT4BW, L60TCRT4BW



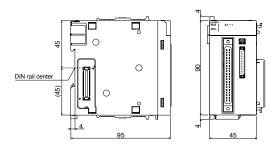
## Simple motion modules

LD77MS2, LD77MS4, LD77MS16

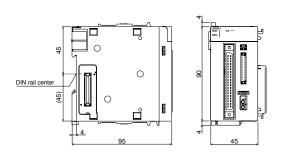


## **Positioning modules**

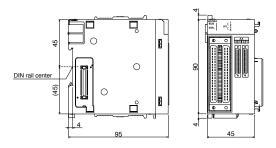
LD75P1, LD75P2



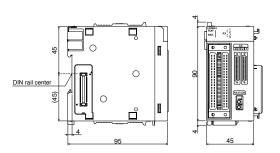
LD75D1, LD75D2



LD75P4

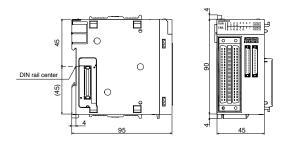


LD75D4



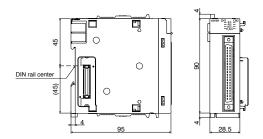
## Flexible high-speed I/O control module

#### LD40PD01



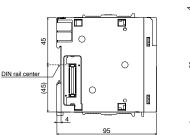
## **High-speed counter module**

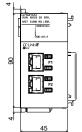
LD62, LD62D



## CC-Link IE Field Network master/local module

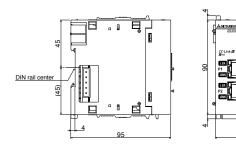
LJ71GF11-T2

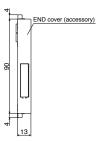




## CC-Link IE Field Network head module

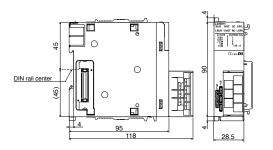
LJ72GF15-T2





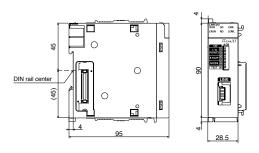
## CC-Link master/local module

## LJ61BT11



## CC-Link/LT master module

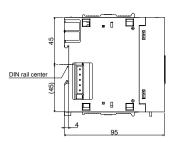
## LJ61CL12

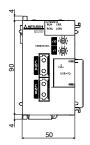


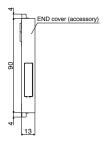


## SSCNET II/H head module

LJ72MS15

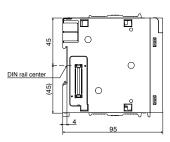


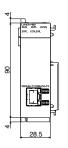




## Ethernet interface module

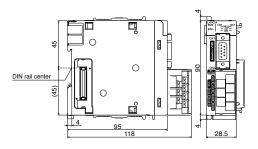
LJ71E71-100



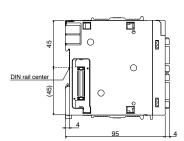


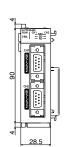
## Serial communication modules

LJ71C24



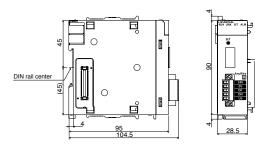
LJ71C24-R2



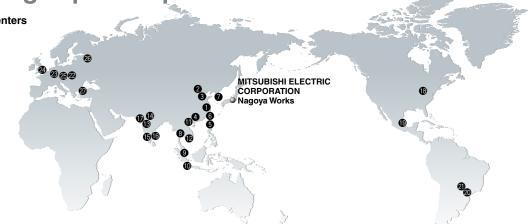


## AnyWireASLINK master module

LJ51AW12AL DB



Extensive global support coverage providing expert help whenever needed ■ Global FA centers



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#### (5) India Bangalore FA Center

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#### Mexico

#### Mexico FA Center

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#### Brazil

#### Brazil FA Center

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#### Brazil Boituva FA Center

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# **Factory Automation Global website**

Mitsubishi Electric Factory Automation provides a mix of services to support its customers worldwide. A consolidated global website is the main portal, offering a selection of support tools and a window to its local Mitsubishi Electric sales and support network.

#### ■ From here you can find:

- Overview of available factory automation products
- Library of downloadable literature
- Support tools such as online e-learning courses, terminology dictionary, etc.
- Global sales and service network portal
- Latest news related to Mitsubishi Electric factory automation

Mitsubishi Electric Factory Automation Global website:

www.MitsubishiElectric.com/fa



## Online e-learning

An extensive library of e-learning courses covering the factory automation product range has been prepared. Courses from beginner to advanced levels of difficulty are available in various languages.



## ■ Beginner level

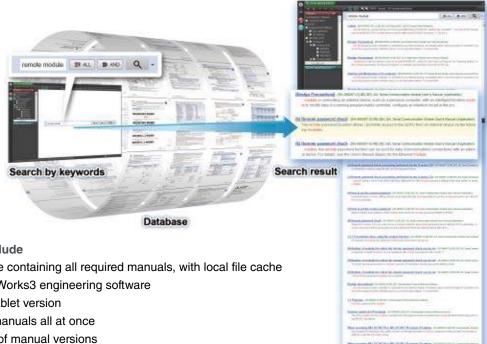
Designed for newcomers to Mitsubishi Electric Factory Automation products gaining a background of the fundamentals and an overview of various products related to the course.

#### ■ Basic to Advanced levels

These courses are designed to provide education at all levels. Various different features are explained with application examples providing an easy and informative resource for in-house company training.

## Innovative next-generation, e-Manual

The e-Manual viewer is a next-generation digital manual offered by Mitsubishi Electric that consolidates all manuals into an easy-to-use package with various useful features integrated into the viewer. The e-Manual is modeled around a centralized database allowing multiple manuals to be cross-searched at once, further reducing the time for reading individual product manuals when setting up a control system.



## ■ Key features include

- One-stop database containing all required manuals, with local file cache
- Included with GX Works3 engineering software
- Also available in tablet version
- Easily download manuals all at once
- Automatic update of manual versions
- Search information across multiple manuals
- Visual navigation from hardware diagram showing various specifications
- · Customizable by adding user notes and bookmarks
- Directly port sample programs within manuals to GX Works3

## ■ MITSUBISHI ELECTRIC FA e-Manual (tablet version)



The e-Manual application is available on iOS and Android™ tablets. e-Manual files are provided as in-app downloads.



#### ■ Supported versions

—			
os	OS version	Model	
iOS	iOS 8.1 or later	Apple iPad 2, iPad (3rd generation), iPad (4th generation), iPad Air, iPad Air 2,	
105		iPad mini, iPad mini 2, iPad mini 3	
Android™ Android™ 4.3/4.4/5.0		ASUS Nexus7™ (2013)*1	

<sup>\*1:</sup> When using a tablet not listed above, 7-inch (resolution of 1920×1200 dots (WUXGA)) or better is recommended.

## **Product List**

Please check the compatibility and restrictions of the product in the related manual before purchasing.

[ Legend ] Double brand product (Note) NEW : Recently released product SOON : Product available soon

## MELSEC-L series

Туре	Model	Outline
	L02SCPU	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/F: None, Built-in I/O functions (General-purpose input: 16 points, General purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L02SCPU-P	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/F: None, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L02CPU	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L02CPU-P	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L06CPU	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
CPU	L06CPU-P	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L26CPU	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L26CPU-P	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
	L26CPU-BT	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
	L26CPU-PBT	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
	L02CPU-SET	CPU module (L02CPU), Display unit (L6DSPU), and Power supply module (L61P) set
	L02CPU-P-SET	CPU module (L02CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
	L06CPU-SET	CPU module (L06CPU), Display unit (L6DSPU), and Power supply module (L61P) set
CPU packages	L06CPU-P-SET	CPU module (L06CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
Or O packages	L26CPU-SET	CPU module (L26CPU), Display unit (L6DSPU), and Power supply module (L61P) set
	L26CPU-P-SET	CPU module (L26CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
	L26CPU-BT-SET	CPU module (L26CPU-BT), Display unit (L6DSPU), and Power supply module (L61P) set
	L26CPU-PBT-SET	CPU module (L26CPU-PBT), Display unit (L6DSPU), and Power supply module (L61P) set

Note: General specifications and product guarantee conditions of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi representative for details.

## **MELSEC-L** series

	Туре		Model	Outline
	Display un	it	L6DSPU	STN black-and-white LCD, 16 characters x4 lines
			Q6BAT	Replacement battery
	Battery		Q7BAT-SET	High capacity battery with a battery holder for CPU installation
	Danoi		Q7BAT	High capacity replacement battery
			NZ1MEM-2GBSD*1	SD memory card, capacity: 2 GB
			NZ1MEM-4GBSD*1	SDHC memory card, capacity: 4 GB
CPU options	SD Memoi	y Card		
or options			NZ1MEM-8GBSD*1	SDHC memory card, capacity: 8 GB
			NZ1MEM-16GBSD*1	SDHC memory card, capacity: 16 GB
	RS-232 ac	lapter	L6ADP-R2	For GOT(HMI) connection, 1 x RS-232 channel, maximum transmission speed: 115.2Kpbs, MELSOFT connectable
				MODBUS® RTU master function (using predefined protocol support function)
	RS-422/48	5 adapter	L6ADP-R4	For GOT(HMI) connection, 1 x RS-422/485 channel, maximum transmission speed: 115.2Kpbs
		·		MODBUS® RTU master function (using predefined protocol support function)
ND cover wit	h error termi	nal	L6EC-ET	END cover with error terminal
			L61P	Input voltage: 100240 V AC, Output voltage: 5 V DC, Output current: 5 A
ower supply			L63P	Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A
	Slim type I	Power supply	L63SP	Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A, No isolation
			L6EXB	Branch module
ranch / Exter	nsion module	•	L6EXE	Extension module with END cover
			LC06E	0.6-m cable for connecting branch and extension modules
	Extension	cable	LC10E	
	LAGUSION	Cable		1.0-m cable for connecting branch and extension modules
			LC30E	3.0-m cable for connecting branch and extension modules
		AC input	LX10	16 points, 100120 V AC, Response time: 20 ms or less, 16 points/common, 18-point terminal block
			LX28	8 points, 100240 V AC, Response time: 20 ms or less, 8 points/common, 18-point terminal block
			LX40C6	16 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
	Input			16 points/common, Positive/Negative common, 18-point terminal block
	Input	DC input	LX41C4	32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
		DC input	LX41C4	32 points/common, Positive/Negative common, 40-pin connector
			17/1001	64 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
			LX42C4	32 points/common, Positive/Negative common, 40-pin connector x2
				16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, Response time: 12 ms or less,
			LY10R2	16 points/common, 18-point terminal block
		Relay		8 points, 24 V DC/240 V AC, 2 A/point, 8 A/module, Response time: 12 ms or less,
			LY18R2A	No common (all points independent), 18-point terminal block
				16 points, 100240 V AC, 0.6 A/point, 4.8 A/common, Response time: 1 ms + 0.5 cycles or less,
			LY20S6	16 points/common, 18-point terminal block
		Triac		8 points, 100240 V DC, 1 A/point, 8 A/module, Response time: 1 ms + 0.5 cycles or less,
			LY28S1A	No common (all points independent), 18-point terminal block
			LY40NT5P	16 points, 1224 V DC, 0.5 A/point, 5 A/common, Response time: 1 ms or less, 16 points/common,
	Output	Transistor (Sink)		18-point terminal block, overload protection function, overheat protection function, surge suppression
			LY41NT1P	32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
O module				Sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
			LY42NT1P	64 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
				Sink type, 40-pin connector x2, overload protection function, overheat protection function, surge suppres
		Transistor (Source)	LY40PT5P	16 points, 1224 V DC, 0.5 A/point, 5 A/common, Response time: 1 ms or less, 16 points/common,
				18-point terminal block, overload protection function, overheat protection function, surge suppression
			LY41PT1P	32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
			2.711 111	40-pin connector, overload protection function, overheat protection function, surge suppression
			LY42PT1P	64 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
			L142F11F	40-pin connector x2, overload protection function, overheat protection function, surge suppression
				Input specifications : 32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
		DC input/transistor output (sink)		32 points/common, Positive/Negative common
			L HAOCANTAD	Output specifications: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or le
			LH42C4NT1P	32 points/common, overload protection function, overheat protection function
				surge suppression
	I/O			40-pin connector x2
	combined			Input specifications : 32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
				32 points/common, Positive/Negative common
		DC input/transistor	LUI40C4DT4D	Output specifications: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or le
		output (source)	LH42C4PT1P	32 points/common, overload protection function, overheat protection function
		, ,		surge suppression
				40-pin connector x2
Space module			LG69	Space module for AnS module replacement
		k	L6TE-18S	Alternative to a 18-point screw terminal block, 0.31.0 mm² (AWG2218), push-in type
pring clamp t				

#### MFLSEC-L series

MELSEC-L series Type		Model	Outline
Multiple input (voltage/current/temperature) modules		- Model	4 channels, Input: -1010 V DC, 020 mA DC, micro voltage-100100 mV DC, Thermocouple (K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re),
		L60MD4-G	RTD (Pt1000, Pt100, JPt100, Pt50), Output (resolution): 020000, -2000020000, (with voltage, current, micro voltage input) Conversion speed: 50 ms/channels, 18-point terminal block, Channel isolated
		L60AD4	4 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 020000, -2000020000, Conversion speed: 20 μs, 80 μs, 1 ms/channel, 18-point terminal block
	Analog input	L60ADVL8	8 channels, Input: -1010 V, Output (resolution)-1600016000, Conversion speed: 1 ms/channels 18-point terminal block
	Analog input	L60ADIL8	8 channels, Input: 020 mA DC, Output (resolution): 08000, Conversion speed: 1 ms/channels 18-point terminal block
Analog I/O module		L60AD4-2GH	4 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 032000, -3200032000, Conversion speed: 40 µs/2 channels, 18-point terminal block, Dual channel isolation
Analog I/O module	Analog output	L60DA4	4 channels, Input (resolution): 020000, -2000020000, Output: -1010 V DC, 020 mA DC, Conversion speed: 20 µs/channel, 18-point terminal block
	Analog I/O	L60AD2DA2	Input specifications : 2 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 012000, -1600016000, Conversion speed: 80 µs/channel, Output specifications : 2 channels, Input (resolution): 012000, -1600016000, Output: -1010 V DC, 020 mA DC, Conversion speed: 80 µs/channel, 18-point terminal block
Temperature input module	RTD input	L60RD8	8 channels, RTD (Pt1000, Pt100, JPt100, Pt50, Ni500, Ni120, Ni100, Cu100, Cu50) Resolution: 0.1°C, Conversion speed: 40 ms/ch, 24-point spring clamp terminal block
	Thermocouple input	L60TCTT4	4 channels (normal mode) /2 channels (heating-cooling control), Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), No Heater disconnection detection function, sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block
Temperature control		L60TCTT4BW	4 channels (normal mode) /2 channels (heating-cooling control), Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II ,W5Re/W26Re), Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block x2
module	RTD input	L60TCRT4	4 channels (normal mode) /2 channels (heating-cooling control), Platinum type resistive temperature device(Pt100, JPt100), No Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block
		L60TCRT4BW	4 channels (normal mode) /2 channels (heating-cooling control), Platinum type resistive temperature device (Pt100, JPt100), Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block x2
	SSCNET II/H	LD77MS2*1	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
Simple motion module		LD77MS4*1	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
		LD77MS16*1	16 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
	Open collector	LD75P1	1 axis, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector
		LD75P2	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector
Desiries in a secondale		LD75P4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector x2
Positioning module	Differential driver	LD75D1	1 axis, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector
		LD75D2	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector
		LD75D4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector x2
Flexible high-speed I/O cor	ntrol module	LD40PD01	12 input points (all for 5 V DC/24 V DC/differential) 14 output points (8 points for DC (5 V DC24 V), 6 points for differential)
		LD62	2 channels, 200/100/10 kpps, Count input signal: 5/12/24 V DC, External input: 5/12/24 V DC, Coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector
High-speed counter module		LD62D	2 channels, 500/200/100/10 kpps, Count input signal: EIA standards RS-422-A (Differential line driver level) External input: 5/12/24 V DC, Coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector

<sup>\*1:</sup> The connector is not appended. Please obtain an LD77MHIOCON separately.

#### MELSEC-L series

WILLOLO-E SELIES				
	Туре	Model	Outline	
	CC-Link IE Field	LJ71GF11-T2	Master/Local station	
	Network	LJ72GF15-T2*1	Remote station (Head module with END cover)	
	CC-Link	LJ61BT11	Master/Local station, CC-Link Ver.2.0 compatible	
	CC-Link/LT	LJ61CL12	Master station, CC-Link/LT system compatible	
	SSCNET III/H	LJ72MS15*2	Remote station (Head module with END cover)	
Network module	Ethernet interface	H.I71E71-100	10BASE-T/100BASE-TX	
	Ethernet interface		BACnet™ client function, MODBUS® TCP master function (using predefined protocol support function)	
	Serial communication	LJ/1C24	RS-232: 1 channel, RS-422/485: 1 channel, Total transmission speed of 2 channels: 230.4 kbps	
			MODBUS® RTU master function (using predefined protocol support function)	
			RS-232: 2 channels, Total transmission speed of 2 channels: 230.4 kbps	
			MODBUS® RTU master function (using predefined protocol support function)	
Digital link sensor		LJ51AW12AL DB	AnyWireASLINK system compatible master module	

<sup>\*1:</sup> The CPU module, branch and extension module, display unit, RS-232 adapter, CC-Link IE Field Network master/local module and Ethernet interface module cannot be mounted on a system using LJ72GF-T2.

#### Compatible module for each protocol

Compatible protocol	Compatible module	Model	Outline
SLMP (MC protocol)	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	SLMP server function (only MC protocol QnA compatible 3E frame) SLMP client function (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	SLMP server function (including MC protocol) SLMP client function (using predefined protocol support function)
BACnet™  MODBUS®/TCP	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	Compatible BACnet™ object: Analog Input (AI), Binary Input (BI), Binary Output (BO), Accumulator (AC) (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	
	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	MODBUS®/TCP communication master function (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	
MODBUS®	CPU (Built-in RS-232)	L02SCPU(-P)	
	RS-232 adapter	L6ADP-R2	MODBUS®RTU communication master function
	RS-422/485 adapter	L6ADP-R4	(using predefined protocol support function)
	Serial Communication Modules	LJ71C24(-R2)	

#### **Options**

- Pro-			
Туре	Model	Outline	
	A6CON1*3*4	Soldering type 32-point connector (40-pin connector)	
Connector	A6CON2*3 *4	Crimp contact type 32-point connector (40-pin connector)	
Connector	A6CON3*3 *5	Flat cable pressure welding type 32-point connector (40-pin connector)	
	A6CON4*3*4	Soldering type 32-point connector (40-pin connector, cable connectable in bidirection)	
	A6TBXY36*6 *7 *8	For positive common type input module and sink type output module (Standard type)	
Connector/terminal block converter module	A6TBXY54*6 *7 *8	For positive common type input module and sink type output module (2-wire type)	
	A6TBX70*6 *9	For positive common type input module (3-wire type)	

<sup>\*3:</sup> Available for the L Series CPU, LX41C4, LX42C4, LY41NT1P, LY42NT1P, LY41PT1P, LY42PT1P, LH42C4NT1P, and LH42C4PT1P.

## Ethernet related products

Ethernet related products				
		Туре	Model	Outline
ı		U.S.A.	NZ2WL-US*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Wireless LAN	Europe	NZ2WL-EU*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Adapter	China	NZ2WL-CN*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Auapiei	Korea	NZ2WL-KR*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
		Taiwan	NZ2WL-TW*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Industrial switch	ching HUB	NZ2EHG-T8N	10 Mbps/100 Mbps/1 Gbps AUTO-MDIX, DIN rail mountable, 8 ports
			DB SOON	To wibbs/100 wibbs/1 dbbs A010-wibix, bill fall mountable, o ports
			NZ2EHF-T8 DB	10 Mbps/100 Mbps AUTO-MDIX, DIN rail mountable, 8 ports

<sup>\*10:</sup> Each product is usable only in the respective country.

<sup>\*2:</sup> The CPU module, branch and extension module, display unit, RS-232 adapter, temperature control module, simple motion module, positioning module, CC-Link IE Field Network master/local module, CC-Link IE Field network head module, CC-Link master/local module, CC-Link/LT master module, Ethernet interface module, serial communication module, and AnyWireASLINK master module cannot be mounted on a system using LJ72MS15.

<sup>\*5.</sup> Available for LID75P1, LD75P2, LD75P4, LD75D1, LD75D1, LD75D4, LD40PD01, LD62 and LD62D.
\*5. Available for the L Series CPU when using all the I/O signals for normal I/O output functions.
\*6: Available for LX41C4 and LX42C4. (Positive common only)
\*7: Available for LY41NT1P, LY42NT1P, LY41PT1P and LY42PT1P.

<sup>\*8:</sup> Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common.)

<sup>\*9:</sup> Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common. Output side is not usable.)

<sup>\*11:</sup> Both access points and stations are supported, and can be switched with the settings.

»For details on the software versions compatible with each module, refer to the manual for each product.

Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

## MELSOFT — Programming Tool

Туре	Model	Outline
		FA engineering software*1
		System Management Software: MELSOFT Navigator
		Controller Programming Software: MELSOFT GX Works3 <sup>+2</sup> , GX Works2, GX Developer
		Motion Programming Software: MELSOFT MT Works2
MELSOFT iQ Works	SW2DND-IQWK-E	HMI Programming Software: MELSOFT GT Works3
		Robot Programing Software: MELSOFT RT ToolBox2 mini
		Inverter Setup Software: MELSOFT FR Configurator2
		C Controller setting and monitoring tool: MELSOFT CW Configurator
		MITSUBISHI ELECTRIC FA Library
		Controller Programming Software: MELSOFT GX Works3*2
MELSOFT GX Works3	SW1DND-GXW3-E	MITSUBISHI ELECTRIC FA Library Comes with GX Works2 and GX Developer
		Controller Programming Software
MELSOFT GX Works2	SW1DNC-GXW2-E	Comes with GX Developer
	SW4DNC-ACT-E	ActiveX® library for communication
MELSOFT MX Component	SW1DNC-ACTAND-B	Library for communication (for Android application development) (Japanese/English version)
	SW1MIC-ACTIOS-B	Library for communication (for iOS application development) (Japanese/English version)
MELSOFT MX Sheet	SW2DNC-SHEET-E*3	Excel® communication support tool
MELSOFT MX Works	SW2DNC-SHEETSET-E	A set of two products: MELSOFT MX Component, MELSOFT MX Sheet

<sup>\*1:</sup> For detailed information about supported modules, refer to the manuals of the relevant software package.

\*2: The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese. (Traditional Chinese and Korean will be supported soon.)

\*3: To use MELSOFT MX Sheet, MELSOFT MX Component is required.

## Compliance with international quality assurance standards

All of Mitsubishi Electric's FA products have acquired the international quality assurance "ISO9001" and environment management system standard "ISO14001" certification. Mitsubishi Electric's products also comply with various safety standards, including UL standards.

\*For jointly developed and partner products, guaranteed quality standards may differ. Please refer to the product manuals for details.

#### **Safety Standards**



**Council Directive of the European Communities** 



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